**Test Report issued under the responsibility of:**

# TEST REPORT
## Engineering Recommendation EN 50549-1:2019
## Requirements for the connection of generation equipment in parallel with public distribution networks

| | |
|---|---|
| **Report Reference No.** .....: | 220900591SHA-002 |
| Tested by (name + signature) .....: | Chuanhui Xie |
| Approved by (name + signature).....: | Sleif Sui |
| Date of issue.....: | 2022-09-23 |
| Contents .....: | 100 pages |
| **Testing Laboratory** .....: | Intertek Testing Services Shanghai. |
| Address.....: | Building No.86, 1198 Qinzhou Road (North), Shanghai 200233, China. |
| Testing location / address.....: | Same as above |
| Applicant's name .....: | Afore New Energy Technology (Shanghai)Co., Ltd. |
| Address.....: | Build No.7, 333 Wanfang Road, Minhang District, Shanghai. China. 201112 |
| **Test specification:** | |
| Standard .....: | EN 50549-1:2019 Requirements for the connection of generation equipment in parallel with public distribution networks. |
| Test procedure.....: | testing |
| Non-standard test method .....: | N/A |
| **Test Report Form/blank test report** | |
| Test Report Form No. .....: | TTRF_ 50549-1 |
| TRF Originator .....: | Intertek Shanghai |
| Master TRF.....: | 2019-11 |

| | |
|---|---|
| **Test item description** ..... : | AC coupled inverter |
| Trade Mark ..... : | Afore |
| Manufacturer ..... : | Same as applicant |
| Model/Type reference..... : | AF1K-SL-0, AF1.5K-SL-0, AF2K-SL-0, AF2.5K-SL-0, AF3K-SL-0, AF3.6K-SL-0, AF4K-SL-0, AF4.6K-SL-0, AF5K-SL-0, AF5.5K-SL-0, AF6K-SL-0 |
| Rating……..: | See below Specifications table |

| **Specifications table** | | | | |
|---|---|---|---|---|
| **Model** | AF1K-SL-0 | AF1.5K-SL-0 | AF2K-SL-0 | AF2.5K-SL-0 |
| ***Battery (charge/discharge)*** | | | | |
| Battery type | Li-ion / lead acid etc. | | | |
| Battery Nominal Voltage (V) | 51.2 | | | |
| Battery Voltage Range (V) | 40-60 | | | |
| Max. Charge/Discharge Current (A) | 25 | 40 | 50 | 63 |
| Max. Charge/Discharge Power (W) | 1000 | 1500 | 2000 | 2500 |
| ***AC Grid (input and output)*** | | | | |
| Nominal Voltage (V) | L/N/PE. 230Vac | | | |
| Nominal Frequency (Hz) | 50 | | | |
| Max. con Current (A) | 5 | 7 | 10 | 12 |
| Nominal Power (W) | 1000 | 1500 | 2000 | 2500 |
| Max. Power (W) | 1000 | 1500 | 2000 | 2500 |
| Max. apparent Power (VA) | 1000 | 1500 | 2000 | 2500 |
| Power Factor | 1(-0.8~+0.8 adjustable) | | | |
| ***AC Load output*** | | | | |
| Nominal Output Voltage (V) | L/N/PE. 230Vac | | | |
| Nominal Frequency (Hz) | 50 | | | |
| Max. cont. current (A) | 5 | 7 | 10 | 12 |
| Nominal Output Power(W) | 1000 | 1500 | 2000 | 2500 |
| Max. Output Power (W) | 1000 | 1500 | 2000 | 2500 |
| Max. apparent Power (VA) | 1000 | 1500 | 2000 | 2500 |
| Power Factor | 1 | | | |
| ***Others*** | | | | |
| Ingress protection (IP) | IP65 | | | |
| Temperature (°C) | -25°C to +60°C (Derating 45°C) | | | |
| Inverter Isolation | Non-isolated | | | |
| Software version | V06 | | | |

| Specifications table | | | | |
|---|---|---|---|---|
| **Model** | AF3K-SL-0 | AF3.6K-SL-0 | AF4K-SL-0 | AF4.6K-SL-0 |
| ***Battery (charge/discharge)*** | | | | |
| Battery type | Li-ion / lead acid etc. | | | |
| Battery Nominal Voltage (V) | 51.2 | | | |
| Battery Voltage Range (V) | 40-60 | | | |
| Max. Charge/Discharge Current (A) | 80 | 80 | 80 | 80 |
| Max. Charge/Discharge Power (W) | 3000 | 3600 | 4000 | 4600 |
| ***AC Grid (input and output)*** | | | | |
| Nominal Voltage (V) | L/N/PE. 230Vac | | | |
| Nominal Frequency (Hz) | 50 | | | |
| Max. con Current (A) | 14 | 17 | 19 | 22 |
| Nominal Power (W) | 3000 | 3600 | 4000 | 4600 |
| Max. Power (W) | 3000 | 3600 | 4000 | 4600 |
| Max. apparent Power (VA) | 3000 | 3600 | 4000 | 4600 |
| Power Factor | 1(-0.8~+0.8 adjustable) | | | |
| ***AC Load output*** | | | | |
| Nominal Output Voltage (V) | L/N/PE. 230Vac | | | |
| Nominal Frequency (Hz) | 50 | | | |
| Max. cont. current (A) | 14 | 17 | 19 | 22 |
| Nominal Output Power(W) | 3000 | 3600 | 4000 | 4600 |
| Max. Output Power (W) | 3000 | 3600 | 4000 | 4600 |
| Max. apparent Power (VA) | 3000 | 3600 | 4000 | 4600 |
| Power Factor | 1 | | | |
| ***Others*** | | | | |
| Ingress protection (IP) | IP65 | | | |
| Temperature (°C) | -25°C to +60°C (Derating 45°C) | | | |
| Inverter Isolation | Non-isolated | | | |
| Software version | V06 | | | |

| Specifications table | | | | |
|---|---|---|---|---|
| **Model** | AF5K-SL-0 | AF5.5K-SL-0 | AF6K-SL-0 | |
| ***Battery (charge/discharge)*** | | | | |
| Battery type | Li-ion / lead acid etc. | | | |
| Battery Nominal Voltage (V) | 51.2 | | | |
| Battery Voltage Range (V) | 40-60 | | | |
| Max. Charge/Discharge Current (A) | 100 | 120 | 120 | |
| Max. Charge/Discharge Power (W) | 5000 | 5500 | 6000 | |
| ***AC Grid (input and output)*** | | | | |
| Nominal Voltage (V) | L/N/PE. 230Vac | | | |
| Nominal Frequency (Hz) | 50 | | | |
| Max. con Current (A) | 23 | 26 | 28 | |
| Nominal Power (W) | 5000 | 5500 | 6000 | |
| Max. Power (W) | 5000 | 5500 | 6000 | |
| Max. apparent Power (VA) | 5000 | 5500 | 6000 | |
| Power Factor | 1(-0.8~+0.8 adjustable) | | | |
| ***AC Load output*** | | | | |
| Nominal Output Voltage (V) | L/N/PE. 230Vac | | | |
| Nominal Frequency (Hz) | 50 | | | |
| Max. cont. current (A) | 23 | 26 | 28 | |
| Nominal Output Power(W) | 5000 | 5500 | 6000 | |
| Max. Output Power (W) | 5000 | 5500 | 6000 | |
| Max. apparent Power (VA) | 5000 | 5500 | 6000 | |
| Power Factor | 1 | | | |
| ***Others*** | | | | |
| Ingress protection (IP) | IP65 | | | |
| Temperature (°C) | -25°C to +60°C (Derating 45°C) | | | |
| Inverter Isolation | Non-isolated | | | |
| Software version | V06 | | | |

**Summary of testing:**

**Tests performed (name of test and test clause):**

| EN 50549-1 | Test Description |
|---|---|
| 4.4.2 | Operating frequency range |
| 4.4.3 | Minimal requirements for active power delivery at underfrequency |
| 4.4.4 | Continuous voltage operation range |
| 4.5.2 | Rate of change of frequency (ROCOF) |
| 4.5.3 | UVRT |
| 4.5.4 | OVRT |
| 4.6.1 | Power response to over frequency |
| 4.6.2 | Power response to underfrequency |
| 4.7.2.2 | Q Capabilites (Power Factor) & Q(U) Capabilities |
| 4.7.2.3.3 | Q Control. Voltage related control mode |
| 4.7.2.3.4 | Q Control Power related control modes |
| 4.7.3 | Voltage control by active power |
| 4.7.4 | Zero current mode |
| 4.9.3 | Interface protection |
| 4.9.4. | Islanding |
| 4.10.2 | Reconnection after tripping |
| 4.10.3 | Starting to generate electrical power |
| 4.11 | Active power reduction by setpoint and ceasing active power (Logic interface) |
| 4.13 | Single fault tolerance of interface protection and interface switch |

Remark:

Other than special notice, the model AF6k-SL-0 is type tested and valid for other models.

**Testing location:**

Building No.86, 1198 Qinzhou Road (North), Shanghai 200233, China

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|---|---|
| **Test item particulars**..... : | |
| Temperature range .....: | -25°C ~60°C (Derating 45 °C) |
| IP protection class .....: | IP 65 |
| **Possible test case verdicts:** | |
| - test case does not apply to the test object.....: | N/A |
| - test object does meet the requirement .....: | P(Pass) |
| - test object does not meet the requirement .....: | F(Fail) |
| **Testing**.....: | |
| Date of receipt of test item.....: | 2022-09-08 |
| Date (s) of performance of tests.....: | 2022-09-09 to 2022-09-20 |

**General remarks:**

**The test results presented in this report are only to the object (single power inverter unit) tested and base on Low Voltage connected on small power station.**

**Installer and relevant persons shall comply with EN 50549-1:2019, Local code and Grid Code in EN 50549-1:2019.**

This report shall not be reproduced, except in full, without the written approval of the Issuing testing laboratory.
"(see Enclosure #)" refers to additional information appended to the report.
"(see appended table)" refers to a table appended to the report.
Throughout this report a point is used as the decimal separator.

Determination of the test conclusion is based on IEC Guide 115 in consideration of measurement uncertainty.

Determination of the test result includes consideration of measurement uncertainty from the test equipment and methods.

The test results presented in this report relate only to the item tested. The results indicate that the specimen partially complies with standard" EN 50549-1:2019". See general product information next for details information.

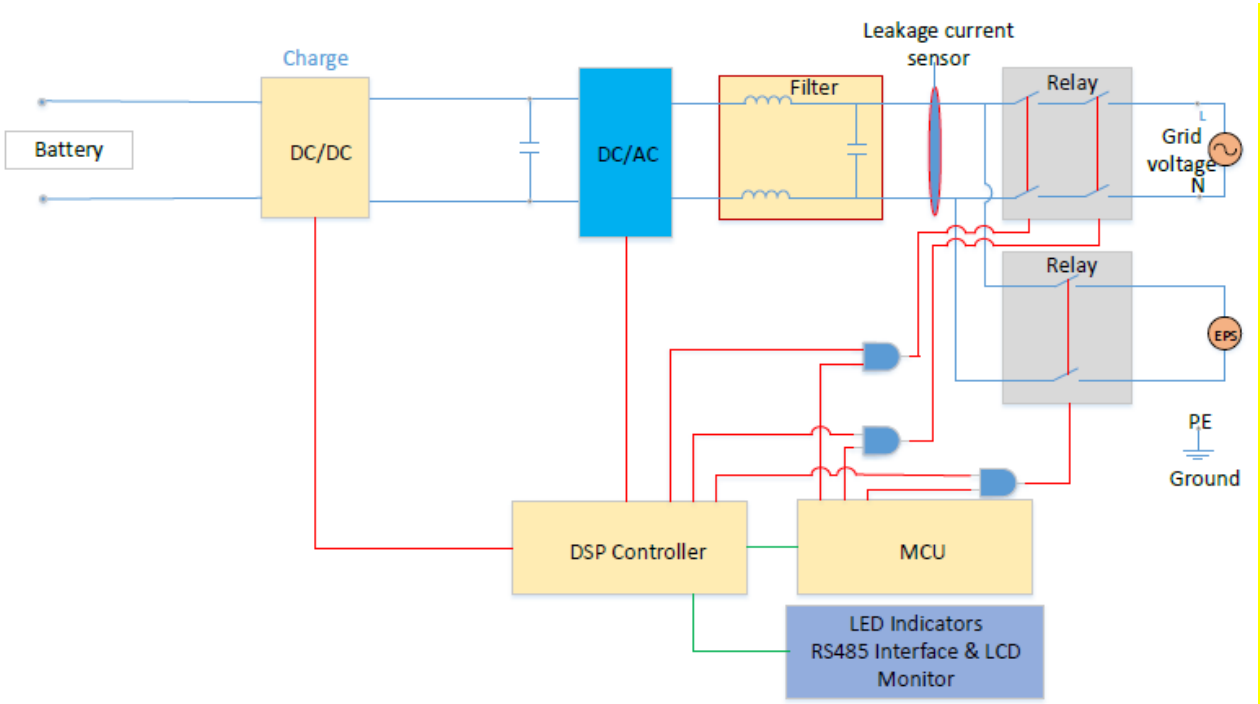
**General product information:**

The testing item is an AC coupled inverter for indoor or outdoor installation.

The relays are designed to redundant structure that controlled by separately.

The master controller and slave controller are used together to control relay open or close, if the single fault on one controller, the other controller can be capable to open the relay, so that still providing safety means.

The topology diagram as following:




**Model differences:**

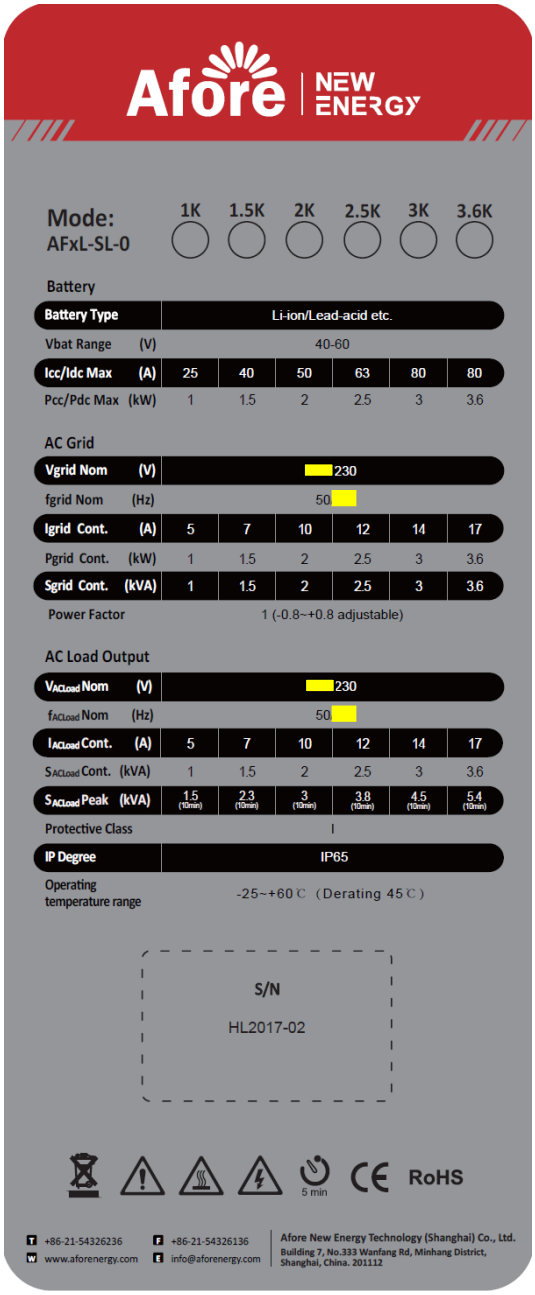
All models are identical with hardware version and software version, the output power is derating by software.

**Factory information:**

Afore New Energy Technology (Shanghai) Co., Ltd.

Build No.7, 333 Wanfang Road, Minhang District, Shanghai. China. 201112

**Copy of marking plate**




**Note:**

1. The above markings are the minimum requirements required by the safety standard. For the final production samples, the additional markings which do not give rise to misunderstanding may be added.
2. Marking plate is attached on the side surface of enclosure and visible after installation
3. Other marking plate are identical to above, except the model's name and ratings
4. The information covered by [ ] on marking plate was irrelevant to this report.
5. The model name: AFx-SL-0, x means 1K, 1.5K, 2K, 2.5K, 3K, 3.6K, 4K, 4.6K, 5K, 5.5K, 6K

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4 | Requirements on generating plants | | P |
| 4.1 | **General** | This report is only evaluated and tested for generating unit; The generating plant incorporated with the generating unit shall further consider this clause and sub-clause. | N/A |
| 4.2 | **Connection scheme** | Shall consider in final PGS | N/A |
| 4.3 | **Choice of switchgear** | | P |
| 4.3.1 | **General**<br>Switches shall be chosen based on the characteristics of the power system in which they are intendedto be installed. For this purpose, the short circuit current at the installation point shall be assessed, taking into account, inter alia, the short circuit current contribution of the generating plant. | | P |
| 4.3.2 | **Interface switch**<br>Switches shall be power relays, contactors or mechanical circuit breakers each having a breaking and making capacity corresponding to the rated current of the generating plant and corresponding to the short circuit contribution of the generating plant. The short- time withstand current of the switching devices shall be coordinated with rated short circuit power at the point of connection. In case of loss of auxiliary supply power to the switchgear, a secure disconnection of the switch is required immediately.<br>Where means of isolation (according to HD 60364-5-551) is not required to be accessible to the DSO at all times, automatic disconnection with single fault tolerance according to 4.13 shall be provided. The function of the interface switch might be combined with either the main switch or the generating unit switch in a single switching device. In case of a combination, the single switching device shall be compliant to the requirements of both, the interface switch and the combined main switch or generating unit switch. As a consequence, at least two switches in series shall be present between any generating unit and the POC**.** | The interface switch is constructed of redundancy, made up of two series relays and power and control separately. | P |
| 4.4 | **Normal operating range** | | P |
| 4.4.1 | **General**<br>Generating plants when generating power shall have the capability to operate in the operating ranges specified below regardless of the topology and the settings of the interface protection. | | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.4.2 | **Operating frequency range**<br>The generating plant shall be capable of operating continuously when the frequency at the point of connection stays within the range of 49 Hz to 51 Hz.<br>In the frequency range from 47 Hz to 52 Hz the generating plant should be capable of operating until the interface protection trips. Therefore, the generating plant shall at least be capable of operating in the frequency ranges, for the duration and for the minimum requirement as indicated in Table 1.<br>Respecting the legal framework, it is possible that for some synchronous areas more stringent time periods and/or frequency ranges will be required by the DSO and the responsible party. Nevertheless, they are expected to be within the boundaries of the stringent requirement as indicated in Table 1 unless producer, DSO, TSO and responsible party agree on wider frequency ranges and longer durations. | See appended table 4.4.2 | P |
| 4.4.3 | **Minimal requirement for active power delivery at underfrequency**<br>A generating plant shall be resilient to the reduction of frequency at the point of connection while reducing the maximum active power as little as possible.<br>The admissible active power reduction due to underfrequency is limited by the full line in Figure 5 and is characterized by a maximum allowed reduction rate of 10 % of $P_{max}$ per 1 Hz for frequencies below 49,5 Hz.<br>It is possible that a more stringent power reduction characteristic is required by the responsible party. Nevertheless this requirement is expected to be limited to an admissible active power reduction represented by the dotted line in Figure 5 which is characterised by a reduction rate of 2 % of the maximum power $P_{max}$ per 1 Hz for frequencies below 49 Hz.<br>If any technologies intrinsic design or ambient conditions have influence on the power reduction behaviour of the system, the manufacturer shall specify at which ambient conditions the requirements can be fulfilled and eventual limitations. The information can be provided in the format of a graph<br>showing the intrinsic behaviour of the generating unit for example at different ambient conditions. The power reduction and the ambient conditions shall comply with the specification given by the responsible party. If the generating unit does not meet the power reduction at the specified ambient conditions, the producer and the responsible party shall agree on acceptable ambient conditions**.** | See appended table 4.4.3 | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.4.4 | **Continuous operating voltage range**<br>When generating power, the generating plant shall be capable of operating continuously when the voltage at the point of connection stays within the range of 85 % $U_n$ to 110 % $U_n$. Beyond these values the under and over voltage ride through immunity limits as specified in clause 4.5.3 and 4.5.4 shall apply.<br>In case of voltages below $U_n$, it is allowed to reduce the apparent power to maintain the current limits of the generating plant. The reduction shall be as small as technically feasible.<br>For this requirement all phase to phase voltages and in case a neutral is connected, additionally all phase to neutral voltages shall be evaluated. | See appended table 4.4.4 | P |
| 4.5 | Immunity to disturbances | | P |
| 4.5.1 | **General**<br>In general, generating plants should contribute to overall power system stability by providing immunity towards dynamic voltage changes unless safety standards require a disconnection.<br>The following clauses describe the required immunity for generating plants taking into account the connection technology of the generating modules.<br>The following withstand capabilities shall be provided regardless of the settings of the interface protection. | | P |
| 4.5.2 | **Rate of change of frequency (ROCOF) immunity**<br>ROCOF immunity of a power generating plant means that the generating modules in this plant stay connected with the distribution network and are able to operate when the frequency on the distribution network changes with a specified ROCOF. The generating units and all elements in the generating plant that might cause their disconnection or impact their behaviour shall have this same level of immunity.<br>The generating modules in a generating plant shall have ROCOF immunity for a ROCOF equal or exceeding the value specified by the responsible party. If no ROCOF immunity value is specified, the following ROCOF immunity shall apply, making distinction between generating technologies:<br>• Non-synchronous generating technology: at least 2 Hz/s<br>• Synchronous generating technology: at least 1 Hz/s | See appended table 4.5.2 | P |
| 4.5.3 | **Under-voltage ride through (UVRT)** | | P |
| 4.5.3.1 | **General**<br>Generating modules classified as type B modules according to COMMISSION REGULATION 2016/631 shall comply with the requirements of 4.5.3.2 and 4.5.3.3. Generating modules classified as type A and smaller according to COMMISSION REGULATION 2016/631 should comply with these requirements. The actual behaviour of type A modules and smaller shall be specified in the connection agreement.<br>The requirements apply to all kinds of faults (1ph, 2ph and 3ph). | | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.5.3.2 | **Generating plant with non-synchronous generating technology**<br>Generating modules shall be capable of remaining connected to the distribution network as long as the voltage at the point of connection remains above the voltage-time curve of Figure 6. The voltage is relative to $U_n$. The smallest phase to neutral voltage, or if no neutral is present, the smallest phase to phase voltage shall be evaluated.<br>The responsible party may define a different UVRT characteristic. Nevertheless, this requirement is expected to be limited to the most stringent curve as indicated in Figure 6. This means that the whole generating module has to comply with the UVRT requirement. This includes all elements in a generating plant: the generating units and all elements that might cause their disconnection.<br>For the generating unit, this requirement is considered to be fulfilled if it stays connected to the distribution grid as long as the voltage at its terminals remains above the defined voltage-time diagram.<br>After the voltage returns to continuous operating voltage range, 90 % of pre-fault power or available power whichever is the smallest shall be resumed as fast as possible, but at the latest within 1 s unless the DSO and the responsible party requires another value. | See appended table 4.5.3 | P |
| 4.5.3.3 | **Generating plant with synchronous generating technology** | | N/A |
| 4.5.4 | **Over-voltage ride through (OVRT)**<br>Generating modules, except for micro-generating plants, shall be capable of staying connected to the distribution network as long as the voltage at the point of connection remains below the voltage-time curve of Figure 8.<br>The highest phase to neutral voltage or if no neutral is present the highest phase to phase voltage shall be evaluated.<br>This means that not only the generating units shall comply with this OVRT requirement but also all elements in a generating plant that might cause its disconnection. | See appended table 4.5.4 | P |
| 4.6 | **Active response to frequency deviation** | | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.6.1 | **Power response to overfrequency**<br>Generating plants shall be capable of activating active power response to overfrequency at a programmable frequency threshold $f_1$ at least between and including 50,2 Hz and 52 Hz with a programmable droop in a range of at least s=2 % to s=12 %. The droop reference is $P_{ref}$. Unless defined differently by the responsible party: • $P_{ref}=P_{max}$, in the case of synchronous generating technology and electrical energy storage systems. • $P_{ref}=P_M$, the actual AC output power at the instant when the frequency reaches the threshold $f_1$, in the case of all other non-synchronous generating technology<br>The power value calculated according to the droop is a maximum power limit. If e.g. the available primary power decreases during a high frequency period below the power defined by the droop function, lower power values are permitted.<br>The generating plant shall be capable of activating active power response to overfrequency as fast as technically feasible with an intrinsic dead time that shall be as short as possible with a maximum of 2 s and with a step response time of maximum 30 s, unless another value is defined by the relevant party.<br>An intentional delay shall be programmable to adjust the dead time to a value between the intrinsic dead time and 2 s. After activation, the active power frequency response shall use the actual frequency at any time, reacting to any frequency increase or decrease according to the programmed droop with an accuracy of ± 10 % of the nominal power (see Figure 9). The resolution of the frequency measurement shall<br>be ± 10 mHz or less. The accuracy is evaluated with a 1 min average value. At POC, loads if present in the producer's network might interfere with the response of the generating plant. The effect of loads is not considered for the evaluation of the accuracy, only the behaviour of the generating plant is relevant. | See appended table 4.6.1 | P |
| | Generating plants reaching their minimum regulating level shall, in the event of further frequency increase, maintain this power level constant unless the DSO and the responsible party requires to disconnect the complete plant or if the plant consists of multiple units by disconnecting individual units. The active power frequency response is only deactivated if the frequency falls below the frequency threshold f1.<br>If required by the DSO and the responsible party an additional deactivation threshold frequency $f_{stop}$ shall be programmable in the range of at least 50 Hz to $f_1$. If $f_{stop}$ is configured to a frequency below $f_1$ there shall be no response according to the droop in case of a frequency decrease (see Figure 10).<br>The output power is kept constant until the frequency falls below $f_{stop}$ for a configurable time $t_{stop}$. | | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| | If at the time of deactivation of the active power frequency response the momentary active power PM is below the available active power PA, the active power increase of the generating plant shall not exceed the gradient defined in 4.10.2.<br>Settings for the threshold frequency $f_1$, the droop and the intentional delay are provided by the DSO and the responsible party. If no settings are provided, the default settings in Table 2 should be applied. | | P |
| | The enabling and disabling of the function and its settings shall be field adjustable and means shall be provided to protect these from unpermitted interference (e.g. password or seal) if required by the DSO and the responsible party. | | P |
| | Alternatively for the droop function described above, the following procedure is allowed for generating modules if permitted by the DSO and the responsible party:<br>• the generating units shall disconnect at randomized frequencies, ideally uniformly distributed between the frequency threshold $f_1$ and 52 Hz;<br>• in case the frequency decreases again, the generating unit shall start its reconnection procedure once the frequency falls below the specific frequency that initiated the disconnection; for this procedure, the connection conditions described in 4.10 do not apply;<br>• the randomization shall either be at unit level by changing the threshold over time, or on plant level by choosing different values for each unit within a plant, or on distribution system level if the DSO specifies a specific threshold for each plant or unit connected to its distribution system. | | P |
| | EES units that are in charging mode at the time the frequency passes the threshold $f_1$ shall not reduce the charging power below $P_M$ until frequency returns below $f_1$. Storage units should increase the charging power according to the configured droop. In case the maximum charging capacity is reached or to prevent any other risk of injury or damage of equipment, a reduction of charging power is permitted. | | Pass |
| 4.6.2 | **Power response to underfrequency**<br>EES units shall be capable of activating active power response to underfrequency. Other generating units/plants should be capable of activating active power response to underfrequency. If active power to underfrequency is provided by a generating plant/unit, the function shall comply with the<br>requirements below.<br>Active power response to underfrequency shall be provided when all of the following conditions are met:<br>• when generating, the generating unit is operating at active power below its maximum active power Pmax;<br>• when generating, the generating unit is operating at active power below the available active power PA;<br>• the voltages at the point of connection of the generating plant are within the continuous operating<br>voltage range;<br>• when generating, the generating unit is operating with currents lower than its current limit.<br>In the case of EES units, active power frequency response to underfrequency shall be provided in charging and generating mode. | See appended table 4.6.2 | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| | The active power response to underfrequency shall be delivered at a programmable frequency threshold $f_1$ at least between and including 49,8 Hz and 46,0 Hz with a programmable droop in a range of at least 2 % to 12 %. The droop reference $P_{ref}$ is $P_{max}$. If the available primary power or a local set value increases during an underfrequency period above the power defined by the droop function, higher power values are permitted. The power value calculated according to the droop is therefore a minimum limit.<br>The generating unit shall be capable of activating active power response to underfrequency as fast as technically feasible with an intrinsic dead time that shall be as short as possible with a maximum of 2 s and with a step response time of maximum 30 s unless another value is defined by the relevant party.<br>An intentional initial delay shall be programmable to adjust the dead time to a value between the intrinsic dead time and 2 s. | | P |
| | After activation, the active power frequency response shall use the actual frequency at any time, reacting to any frequency increase or decrease according to the programmed droop with an accuracy of ± 10 % of the nominal power. The accuracy is evaluated with a 1 min average value. The resolution of the frequency measurement shall be ± 10 mHz or less. At POC loads, if present in the producer's<br>network, might interfere with the response of the generating plant. The effect of loads is not considered for the evaluation of the accuracy, only the behaviour of the generating plant is relevant. | | P |
| | Generating modules reaching any of the conditions above during the provision of active power frequency response shall, in the event of further frequency decrease, maintain this power level constant.<br>The active power frequency response is only deactivated if the frequency increases above the frequency threshold f1. | | P |
| | Settings for the threshold frequency $f_1$, the droop and the intentional delay are defined by the DSO and the responsible party, if no settings are provided, the function shall be disabled. | | P |
| | The activation and deactivation of the function and its settings shall be field adjustable and means shall be provided to protect these from unpermitted interference (e.g. password or seal) if required by the DSO and the responsible party. | | P |
| 4.7 | **Power response to voltage changes** | | P |
| 4.7.1 | **General**<br>When the contribution to voltage support is required by the DSO and the responsible party, the generating plant shall be designed to have the capability of managing reactive and/or active power generation according to the requirements of this clause. | | P |
| 4.7.2 | **Voltage support by reactive power** | | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.7.2.1 | **General**<br>Generating plants shall not lead to voltage changes out of acceptable limits. These limits should be defined by national regulation. Generating units and plants shall be able to contribute to meet this requirement during normal network operation. Throughout the continuous operating frequency (see 4.4.2) and voltage (see 4.4.4) range, the generating plant shall be capable to deliver the requirements stipulated below. Outside these ranges, the generating plant shall follow the requirements as good as technically feasible although there is no specified accuracy required. | | P |
| 4.7.2.2 | **Capabilities**<br>Unless specified differently below, for specific generating technologies, generating plants shall be able to operate with active factors as defined by the DSO and the responsible party from active factor = $0{,}90_{underexcited}$ to active factor=$0{,}90_{overexcited}$ The reactive power capability shall be evaluated at the terminals of the/each generating unit | | P |
| | CHP generating units with a capacity ≤ 150 kVA shall be able to operate with active factors as defined by the DSO from cos φ = $0{,}95_{underexcited}$ to cos φ = $0{,}95_{overexcited}$ Generating units with an induction generator coupled directly to the grid and used in generating plants above micro generating level, shall be able to operate with active factors as defined by the DSO from cos φ = $0{,}95_{underexcited}$ to cos φ = 1 at the terminals of the unit. Deviating from 4.7.2.3 only the cos φ set point mode is required. Deviating from the accuracy requirements below, the accuracy is only required at active power PD. | | N/A |
| | Generating units with an induction generator coupled directly to the grid and used in micro generating plants shall operate with an active factor above 0,95 at the terminals of the generating unit. A controlled voltage support by reactive power is not required from this technology. | | N/A |
| | Generating units with linear generators, coupled directly and synchronously to the grid shall operate with an active factor above 0,95 at the terminals of the generating unit, and therefore a controlled voltage support by reactive power is not required from this technology. | | N/A |
| | In case of different generating technologies with different requirements in one generating plant, each unit shall provide voltage support by reactive power as required for its specific technology. A compensation of one technology to reach the general plant requirement is not expected.<br>The DSO and the responsible party may relax the above requirements. This relaxation might be general or specific for a certain generating plant or generating technology. | | N/A |

| EN 50549-1:2019 | | | |
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| Clause | Requirement - Test | Result - Remark | Verdict |
| | All involved parties can expect to have access to information documenting the actual choices regarding active power capabilities relative to reactive power requirements and related to the power rating in the operating voltage range (see further in this clause). A P-Q Diagram shall be included in the product documentation of a generating unit.<br>When operating above the apparent power threshold $S_{min}$ equal to 10 % of the maximum apparent power $S_{max}$ or the minimum regulating level of the generating plant, whichever is the higher value, the reactive power capability shall be provided with an accuracy of ± 2 % $S_{max}$. Up to this apparent power threshold $S_{min}$, deviations above 2 % are permissible; nevertheless the accuracy shall always be as good as technically feasible and the exchange of uncontrolled reactive power in this low-power operation mode shall not exceed 10 % of the maximum apparent power $S_{max}$. At POC loads, if present in the producer's network might interfere with the response of the generating plant. The effect of loads is not considered for the evaluation of the accuracy, only the behaviour of the generating plant is relevant.<br>For generating units with a reactive power capability according Figure 12 the reactive power capability at active power $P_D$ shall be at least according Figure 13. For generating units with a reduced reactive power capability Figure 13 is only applicable up to the maximum reactive power capability. | | P |
| 4.7.2.3 | **Control modes** | | P |
| 4.7.2.3.1 | **General**<br>Where required, the form of the contribution to voltage control shall be specified by the DSO.<br>The control shall refer to the terminals of the generating units<br>The generating plant/unit shall be capable of operating in the control modes specified below within the limits specified in 4.7.2.2. The control modes are exclusive; only one mode may be active at a time.<br>• Q setpoint mode<br>• Q (U)<br>• Cos φ setpoint mode<br>• Cos φ (P)<br>For mass market products, it is recommended to implement all control modes. In case of site specific generating plant design, only the control modes required by the DSO need to be implemented.<br>The configuration, activation and deactivation of the control modes shall be field adjustable. For field adjustable configurations and activation of the active control mode, means shall be provided to protect the settings from unpermitted interference (e.g. password or seal) if required by the DSO. Which control modes are available in a product and how they are configured shall be stated in the product documentation. | | P |
| 4.7.2.3.2 | **Setpoint control modes**<br>Q setpoint mode and cos φ setpoint mode control the reactive power output and the cos φ of the output respectively, according to a set point set in the control of the generating plant/unit.<br>In the case of change of the set point local or by remote control the settling time for the new set point shall be less than one minute. | See appended table 4.7.2 | P |

| EN 50549-1:2019 | | | |
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| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.7.2.3.3 | **Voltage related control mode**<br>The voltage related control mode Q (U) controls the reactive power output as a function of the voltage.<br>There is no preferred state of the art for evaluating the voltage. Therefore it is the responsibility of the generating plant designer to choose a method. One of the following methods should be used:<br>• the positive sequence component of the fundamental.<br>• the average of the voltages measured independently for each phase to neutral or phase to phase.<br>• phase independently the voltage of every phase to determine the reactive power for every phase. | Method 2 used | p |
| | For voltage related control modes, a characteristic with a minimum and maximum value and three connected lines according to Figure 16 shall be configurable.<br>In addition to the characteristic, further parameters shall be configurable:<br>• The dynamics of the control shall correspond with a first order filter having a time constant that is configurable in the range of 3 s to 60 s. | See appended table 4.7.2 | P |
| | To limit the reactive power at low active power two methods shall be configurable:<br>• a minimal cos φ shall be configurable in the range of 0-0,95;<br>• two active power levels shall be configurable both at least in the range of 0 % to 100 % of $P_D$. The lock-in value turns the Q(U) mode on, the lock-out value turns Q(U) off. If lock-in is larger than lock-out a hysteresis is given. See also Figure 14.<br>The static accuracy shall be in accordance with 4.7.2.2. The dynamic accuracy shall be in accordance with Figure 15 with a maximum tolerance of +/- 5% of $P_D$ plus a time delay of up to 3 seconds deviating from an ideal first order filter response. | | P |
| 4.7.2.3.4 | **Power related control mode**<br>The power related control mode cos φ (P) controls the cos φ of the output as a function of the active power output.<br>For power related control modes, a characteristic with a minimum and maximum value and three connected lines shall be configurable in accordance with Figure 16.<br>Resulting from a change in active power output a new cos φ set point is defined according to the set characteristic. The response to a new cos φ set value shall be as fast as technically feasible to allow the change in reactive power to be in synchrony with the change in active power. The new reactive power set value shall be reached at the latest within 10 s after the end value of the active power is reached. The static accuracy of each cos φ set point shall be according to 4.7.2.2. | See appended table 4.7.2 | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.7.3 | **Voltage related active power reduction**<br>In order to avoid disconnection due to overvoltage protection (see 4.9.2.3 and 4.9.2.4), generating plants/units are allowed to reduce active power output as a function of this rising voltage. The final implemented logic can be chosen by the manufacturer. Nevertheless, this logic shall not cause steps or oscillations in the output power. The power reduction caused by such a function may not be faster than an equivalent of a time constant tau = 3 s (= 33%/s at a 100% change). The enabling and disabling of the function shall be field adjustable and means have to be provided to protect the setting from unpermitted interference (e.g. password or seal) if required by the DSO. | See appended table 4.7.3 | P |
| 4.7.4 | Short circuit current requirements on generating plants | | P |
| 4.7.4.1 | **General**<br>The following clauses describe the required short circuit current contribution for generating plants taking into account the connection technology of the generating modules. Generating modules classified as type B modules according to COMMISSION REGULATION 2016/631 shall comply with the requirements of 4.7.4.2 and 4.7.4.3. Generating modules classified as type A according to COMMISSION REGULATION 2016/631 should comply with these requirements.<br>The actual behaviour of type A modules shall be specified in the connection agreement. | | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.7.4.2 | **Generating plant with non-synchronous generating technology** | | P |
| 4.7.4.2.1 | **Voltage support during faults and voltage steps**<br>In general no voltage support during faults and voltage steps is required from generating plants connected in LV distribution networks as the additional reactive current is expected to interfere with grid protection equipment. If the responsible party requires voltage support during faults and voltage steps for generating plants of type B connected to LV distribution grids, the clause 4.7.4 of EN 50549-2 applies. | Only EN 50549-1 applies, if required by the responsible party for additional reactive current, the EN 50549-2 shall be applied | P |
| 4.7.4.2.2 | **Zero current mode for converter connected generating technology**<br>If UVRT capability (see 4.5.3) is provided additional to the requirements of 4.5, generating units connected to the grid by a converter shall have the capability to reduce their current as fast as technically feasible down to or below 10 % of the rated current when the voltage is outside of a static voltage range. Generating units based on a doubly fed induction machine can only reduce the positive sequence current below 10 % of the rated current. Negative sequence current shall be tolerated during unbalanced faults. In case this current reduction is not sufficient, the DSO should choose suitable interface protection settings.<br>The static voltage range shall be adjustable from 20 % to 100 % of $U_n$ for the undervoltage boundary and from 100 % to 130 % of $U_n$ for the overvoltage boundary. The default setting shall be 50% of $U_n$ for the undervoltage boundary and 120% of $U_n$ for the overvoltage boundary. Each phase to neutral<br>voltage or if no neutral is present each phase to phase voltage shall be evaluated. At voltage re-entry into the voltage range, 90% of pre-fault power or available power, whichever is the smallest, shall be resumed as fast as possible, but at the latest according to 4.5.3 and 4.5.4.<br>All described settings are defined by the DSO and the responsible party. If no settings are provided, the function shall be disabled.<br>The enabling and disabling and the settings shall be field adjustable and means have to be provided to protect these from unpermitted interference (e.g. password or seal) if required by the DSO**.** | Test with 4.5.3 | P |
| 4.7.4.2.3 | **Induction generator based units**<br>In general no voltage support during faults and voltage steps is required from generating plants connected in LV distribution networks as the additional reactive current is expected to interfere with grid protection equipment. | | N/A |

| EN 50549-1:2019 | | | |
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| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.7.4.3 | **Generating plant with synchronous generating technology - Synchronous generator based units**<br>In general no voltage support during faults and voltage steps is required from generating plants connected in LV distribution networks as the additional reactive current is expected to interfere with grid protection equipment. If the responsible party requires voltage support during faults and voltage steps for generating plants of type B connected to LV distribution grids, the clause 4.7.4 of EN50549-2 applies. | | P |
| 4.8 | **EMC and power quality**<br>Similar to any other apparatus or fixed installation, generating units shall comply with the requirements on electromagnetic compatibility established in Directive 2014/30/EU or 2014/53/EU, whichever applies. EMC limits and tests, described in EN 61000 series, have been traditionally developed for loads, without taking into account the particularities of generating units, such as their capability to create overvoltages or high frequency disturbances due to the presence of power converters, which were either impossible or less frequent in case of loads. | | P |
| 4.9 | **Interface protection** | | P |
| 4.9.1 | **General**<br>According to HD 60364-5-551:2010, 551.7.4, means of automatic switching shall be provided to disconnect the generating plant from the distribution network in the event of loss of that supply or deviation of the voltage or frequency at the supply terminals from values declared for normal supply. This automatic means of disconnection has following main objectives:<br>• prevent the power production of the generating plant to cause an overvoltage situation in the distribution network it is connected to. Such overvoltages could result in damages to the equipment connected to the distribution network as well as the distribution network itself;<br>• detect unintentional island situations and disconnect the generating plant in this case. This is contributing to prevent damage to other equipment, both in the producers' installations and the distribution network due to out of phase re-closing and to allow for maintenance work after an intentional disconnection of a section of the distribution network.<br>• assist in bringing the distribution network to a controlled state in case of voltage or frequency deviations beyond corresponding regulation values. | | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| | • disconnect the generating plant from the distribution network in case of faults internal to the power generating plant. Protection against internal faults (short-circuits) shall be coordinated with network protection, according to DSO protection criteria. Protection against e.g. overload, electric shock and against fire hazards shall be implemented additionally according to HD 60364-1 and local requirements.<br>• prevent damages to the generating unit due to incidents (e.g. short circuits) on the distribution network Interface protections may contribute to preventing damage to the generating units due to out-of-phase reclosing of automatic reclosing which may happen after some hundreds of ms. However, in some countries some technologies of generating units are explicitly required to have an appropriate immunity level against the consequences of out-of-phase reclosing. The type of protection and the sensitivity and operating times depend upon the protection and the characteristics of the distribution network. A wide variety of approaches to achieve the above mentioned objectives is used throughout Europe. Besides the passive observation of voltage and frequency other active and passive methods are available and used to detect island situations. The requirements given in this clause are intended to provide the necessary functions for all known approaches as well as to give guidance in their use.<br>Which functions are available in a product shall be stated in the product documentation. | | P |
| | The interface protection system shall comply with the requirements of this European Standard, the available functions and configured settings shall comply with the requirements of the DSO and the responsible party. In any case, the settings defined shall be understood as the values for the interface protection system, i.e. where there is a wider technical capability of the generation module, it shall not be withheld by the settings of the protections (other than the interface protection).<br>For micro generating plants, the interface protection system and the point of measurement might be integrated into the generating units. For generating plants with nominal current above 16 A the DSO may define a threshold above which the interface protection system shall be realized as a dedicated device and not integrated into the generating units. | Integrated into the generating units<br>If specified by country requirement, the interface protection shall not be integrated | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| | to place the protection system as close to the point of connection as possible, to avoid tripping due to overvoltages resulting from the voltage rise within the producer's network;<br>• to allow for periodic field tests. In some countries periodic field tests are not required if the protection system meets the requirements of single fault safety.<br>The interface protection relay acts on the interface switch.<br>The DSO may require that the interface protection relay acts additionally on another switch with a proper delay in case the interface switch fails to operate.<br>In case of failure of the power supply of the interface protection, the interface protection shall trigger the interface switch without delay. An uninterruptible power supply may be required by the DSO, for instance in case of UVRT capability, delay in protection etc.<br>In case of field adjustable settings of threshold and operation time, means shall be provided to protect the settings from unpermitted interference (e.g. password or seal) if required by the DSO. | | P |
| 4.9.2 | **Void** | | N/A |
| 4.9.3 | **Requirements on voltage and frequency protection** | See appended table 4.9.3 | P |
| 4.9.3.1 | **General**<br>Part or all of the following described functions may be required by the DSO and the responsible party.<br>In case of three phase generating units/plants and in all cases when the protection system is implemented as an external protection system in a three phase power supply system, all phase to phase voltages and, if a neutral conductor is present, all phase to neutral voltages shall be evaluated.<br>The frequency shall be evaluated on at least one of the voltages. | | P |
| | If multiple signals (e.g. 3 phase to phase voltages) are to be evaluated by one protection function, this function shall evaluate all of the signals separately. The output of each evaluation shall be OR connected, so that if one signal passes the threshold of a function, the function shall trip the protection in the specified time.<br>The minimum required accuracy for protection is:<br>• for frequency measurement ± 0,05 Hz;<br>• for voltage measurement ± 1 % of Un.<br>• The reset time shall be ≤50ms<br>• The interface protection relay shall not conduct continuous starting and disengaging operations of the interface protection relay. Therefore a reasonable reset ratio shall be implemented which shall not be zero but be below 2% of nominal value for voltage and below 0,2Hz for frequency. | | P |

| EN 50549-1:2019 | | | |
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| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.9.3.2 | **Undervoltage protection [27]**<br>The protection shall comply with EN 60255-127. The evaluation of the r.m.s. or the fundamental value is allowed. Undervoltage protection may be implemented with two completely independent protection thresholds, each one able to be activated or not. The standard adjustment ranges are as follows.<br>Undervoltage threshold stage 1 [27 < ]:<br>• Threshold (0,2 – 1) $U_n$ adjustable by steps of 0,01 $U_n$<br>• Operate time (0,1 – 100) s adjustable in steps of 0,1 s<br>Undervoltage threshold stage 2 [27 < < ]:<br>• Threshold (0,2 – 1) $U_n$ adjustable by steps of 0,01 $U_n$<br>• Operate time (0,1 – 5) s adjustable in steps of 0,05 s<br>The undervoltage threshold stage 2 is not applicable for micro-generating plants | See appended table 4.9.3.2 | P |
| **4.9.3.3** | **Overvoltage protection [59]**<br>The protection shall comply with EN 60255-127. The evaluation of the r.m.s. or the fundamental value is allowed. Overvoltage protection may be implemented with two completely independent protection thresholds, each one able to be activated or not. The standard adjustment ranges are as follows.<br>Overvoltage threshold stage 1 [59 > ]:<br>• Threshold (1,0 – 1,2) $U_n$ adjustable by steps of 0,01 $U_n$<br>• Operate time (0,1 – 100) s adjustable in steps of 0,1 s<br>Overvoltage threshold stage 2 [59 > > ]:<br>• Threshold (1,0 – 1,30) $U_n$ adjustable by steps of 0,01 $U_n$<br>• Operate time (0,1 – 5) s adjustable in steps of 0,05 s | See appended table 4.9.3.3 | P |
| 4.9.3.4 | **Overvoltage 10 min mean protection**<br>The calculation of the 10 min value shall comply with the 10 min aggregation of EN 61000-4-30 Class S, but deviating from EN 61000-4-30 as a moving window is used. Therefore the function shall be based on the calculation of the square root of the arithmetic mean of the squared input values over 10 min. The calculation of a new 10 min value at least every 3 s is sufficient, which is then to be compared with the threshold value.<br>• Threshold (1,0 – 1,15) $U_n$ adjustable by steps of 0,01 $U_n$<br>• Start time ≤ 3s not adjustable<br>• **Time delay setting = 0 ms** | See appended table 4.9.3.4 | P |
| 4.9.3.5 | **Underfrequency protection [81 < ]**<br>Underfrequency protection may be implemented with two completely independent protection thresholds, each one able to be activated or not. The standard adjustment ranges are as follows. Underfrequency threshold stage 1 [81 < ]:<br>• Threshold (47,0 – 50,0) Hz adjustment by steps of 0,1 Hz<br>• Operate time (0,1 – 100) s adjustable in steps of 0,1 s<br>Underfrequency threshold stage 2 [81 < < ]:<br>• Threshold (47,0 – 50,0) Hz adjustment by steps of 0,1 Hz<br>• Operate time (0,1 – 5) s adjustable in steps of 0,05 s<br>In order to use narrow frequency thresholds for islanding detection (see 4.9.3.3) it may be required to have the ability to activate and deactivate a stage by an external signal.<br>The frequency protection shall function correctly in the input voltage range between 20 % $U_n$ and 120 % $U_n$ and shall be inhibited for input voltages of less than 20 % $U_n$.<br>Under 0,2 $U_n$ the frequency protection is inhibited.<br>Disconnection may only happen based on undervoltage protection. | See appended table 4.9.3.5 | P |

| EN 50549-1:2019 | | | |
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| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.9.3.6 | **Overfrequency protection [81 > ]**<br>Overfrequency protection may be implemented with two completely independent protection thresholds, each one able to be activated or not. The standard adjustment ranges are as follows.<br>Overfrequency threshold stage 1 [81 > ]:<br>• Threshold (50,0 - 52,0) Hz adjustment by steps of 0,1 Hz<br>• Operate time (0,1 – 100) s adjustable in steps of 0,1 s<br>Overfrequency threshold stage 2 [81 > > ]:<br>• Threshold (50,0 - 52,0) Hz adjustment by steps of 0,1 Hz<br>• Operate time (0,1 - 5) s adjustable in steps of 0,05 s<br>In order to use narrow frequency thresholds for islanding detection (see4.9.3.3) it may be required to have the ability to activate and deactivate a stage by an external signal.<br>The frequency protection shall function correctly in the input voltage range between 20 % $U_n$ and 120 % Un and shall be inhibited for input voltages of less than 20 % Un. | See appended table 4.9.3.6 | P |
| 4.9.4 | Means to detect island situation | | P |
| 4.9.4.1 | **General**<br>sides the passive observation of voltage and frequency further means to detect an island may be required by the DSO. Detecting islanding situations shall not be contradictory to the immunity requirements of 4.5. Commonly used functions include:<br>• Active methods tested with a resonant circuit;<br>• ROCOF tripping;<br>• Switch to narrow frequency band;<br>• Vector shift<br>• Transfer trip.<br>Only some of the methods above rely on standards. Namely for ROCOF tripping and for the detection of a vector shift, also called a vector jump, currently no European Standard is available. | | P |
| 4.9.4.2 | **Active methods tested with a resonant circuit**<br>These are methods which pass the resonant circuit test for PV inverters according to EN 62116 | See appended table 4.9.4 | P |
| 4.9.4.3 | **Switch to narrow frequency band (see Annex E and Annex F)**<br>In case of local phenomena (e.g. a fault or the opening of circuit breaker along the line) the DSO in coordination with the responsible party may require a switch to a narrow frequency band to increase the interface protection relay sensitivity. In the event of a local fault it is possible to enable activation of the restrictive frequency window (using the two underfrequency/overfrequency thresholds described in 4.9.2.5 and 4.9.2.6) correlating its activation with another additional protection function.<br>If required by the DSO, a digital input according to 4.9.4 shall be available to allow the DSO the activation of a restrictive frequency window by communication. | | P |
| 4.9.5 | **Digital input to the interface protection**<br>If required by the DSO, the interface protection shall have at least two configurable digital inputs.<br>These inputs can for example be used to allow transfer trip or the switching to the narrow frequency band. | | P |
| 4.10 | **Connection and starting to generate electrical power** | | P |

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| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.10.1 | **General**<br>Connection and starting to generate electrical power is only allowed after voltage and frequency are within the allowed voltage and frequency ranges for at least the specified observation time. It shall not be possible to overrule these conditions.<br>Within these voltage and frequency ranges, the generating plant shall be capable of connecting and starting to generate electrical power.<br>The setting of the conditions depends on whether the connection is due to a normal operational startup or an automatic reconnection after tripping of the interface protection. In case the settings for automatic reconnection after tripping and starting to generate power are not distinct in a generating plant, the tighter range and the start-up gradient shall be used.<br>The frequency range, the voltage range, the observation time and the power gradient shall be field adjustable.<br>For field adjustable settings, means shall be provided to protect the settings from unpermitted interference (e.g. password or seal) if required by the DSO. | | P |
| 4.10.2 | **Automatic reconnection after tripping**<br>The frequency range, the voltage range, the observation time shall be adjustable in the range according to Table 3 column 2. If no settings are specified by the DSO and the responsible party, the default settings for the reconnection after tripping of the interface protection are according to Table 3 column 3.<br>After reconnection, the active power generated by the generating plant shall not exceed a specified gradient expressed as a percentage of the active nominal power of the unit per minute. If no gradient is specified by the DSO and the responsible party, the default setting is 10 % $P_n$/min.<br>Generating modules for which it is technically not feasible to increase the power respecting the specified gradient over the full power range may connect after 1 min to 10 min (randomized value, uniformly distributed) or later. | See appended table 4.10.2 | P |
| 4.10.3 | **Starting to generate electrical power**<br>The frequency range, the voltage range, the observation time shall be adjustable in the range according to Table 4 column 2. If no settings are specified by the DSO and the responsible party, the default settings for connection or starting to generate electrical power due to normal operational startup or activity are according to Table 4 column 3.<br>If applicable, the power gradient shall not exceed the maximum gradient specified by the DSO and the responsible party. Heat driven CHP generating units do not need to keep a maximum gradient, since the start up is randomized by the nature of the heat demand.<br>For manual operations performed on site (e.g. for the purpose of initial start-up or maintenance) it is permitted to deviate from the observation time and ramp rate. | See appended table 4.10.3<br>Default settings are applied | P |
| 4.10.4 | **Synchronization**<br>Synchronizing a generating plant/unit with the distribution network shall be fully automatic i.e. it shall not be possible to manually close the switch between the two systems to carry out synchronization. | | P |
| 4.11 | **Ceasing and reduction of active power on set point** | | P |

| EN 50549-1:2019 | | | |
|---|---|---|---|
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.11.1 | **Ceasing active power**<br>Generating plants with a maximum capacity of 0,8 kW or more shall be equipped with a logic interface (input port) in order to cease active power output within five seconds following an instruction being received at the input port. If required by the DSO and the responsible party, this includes remote operation. | See appended table 4.11 | p |
| 4.11.2 | **Reduction of active power on set point**<br>For generating modules of type B, a generating plant shall be capable of reducing its active power to a limit value provided remotely by the DSO. The limit value shall be adjustable in the complete operating range from the maximum active power to minimum regulating level.<br>The adjustment of the limit value shall be possible with a maximum increment of 10% of nominal power.<br>A generation unit/plant shall be capable of carrying out the power output reduction to the respective limit within an envelope of not faster than 0,66 % $P_n$/ s and not slower than 0,33 % $P_n$/ s with an accuracy of 5 % of nominal power.<br>Generating plants are permitted to disconnect from the network at a limit value below it minimum regulating level. If required by the DSO, this includes remote operation. | See appended table 4.11 | P |
| 4.12 | **Remote information exchange**<br>Generating plants whose power is above a threshold to be determined by the DSO and the responsible party shall have the capacity to be monitored by the DSO or TSO control centre or control centres as well as receive operation parameter settings for the functions specified in this European<br>Standard from the DSO or TSO control centre or control centres. | | N/A |

| EN 50549-1:2019 | | | |
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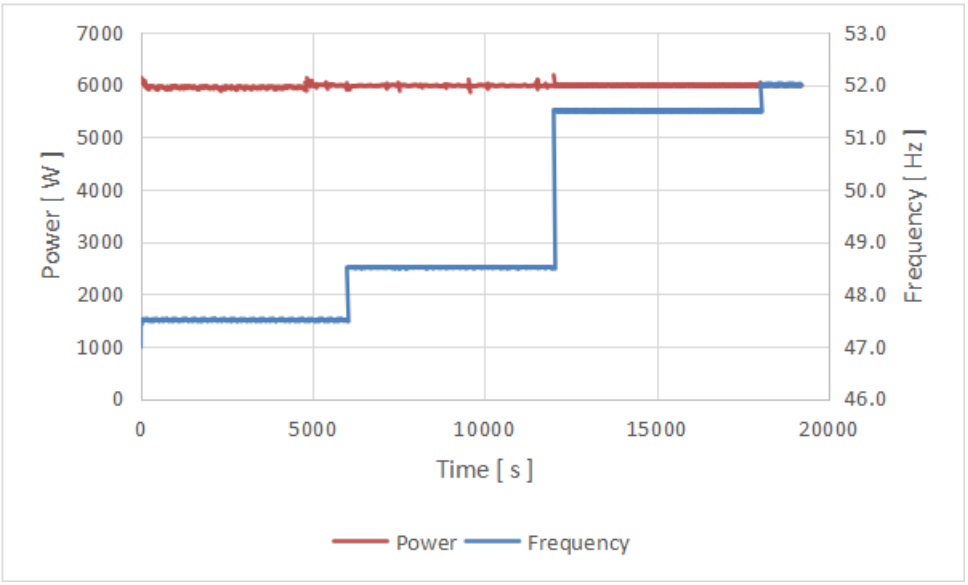
| Clause | Requirement - Test | Result - Remark | Verdict |
| 4.13 | **Requirements regarding single fault tolerance of interface protection system and interface switch**<br>If required in 4.3.2, the interface protection system and the interface switch shall meet the requirements of single fault tolerance.<br>A single fault shall not lead to a loss of the safety functions.<br>Faults of common cause shall be taken into account if the probability for the occurrence of such a fault is significant.<br>Whenever reasonably practical, the individual fault shall be displayed and lead to the disconnection of the power generating unit or system.<br>Series-connected switches shall each have a independent breaking capacity corresponding to the rated current of the generating unit and corresponding to the short circuit contribution of the generating unit.<br>The short-time withstand current of the switching devices shall be coordinated with maximum short circuit power at the connection point.<br>At least one of the switches shall be a switch-disconnector suitable for overvoltage category 2. For single-phase generating units, the switch shall have one contact of this overvoltage category for both the neutral conductor and the line conductor. For poly-phase generating units, it is required to have one contact of this overvoltage category for all active conductors. The second switch may be formed of electronic switching components from an inverter bridge or another circuit provided that the electronic switching components can be switched off by control signals and that it is ensured that a failure is detected and leads to prevention of the operation at the latest at the next reconnection.<br>For PV-inverters without simple separation between the network and the PV generating unit (e.g. PV Inverter without transformer) both switches mentioned in the paragraph above shall be switchdisconnectors with the requirements described therein, although one switching device is permitted to be located between PV array and PV inverter. | | P |
| Annex A | **Interconnection guidance** | | Info |
| Annex B | **Void** | | Info |
| Annex C | **Parameter Table** | | Info |
| Annex D | **List of national requirements applicable for generating plants** | | Info |
| Annex E | **Loss of Mains and overall power system security** | | Info |
| Annex F | **Examples of protection strategies** | | Info |
| Annex H | **Relationship between this European standard and the COMMISSION REGULATION (EU) 2016/631** | | Info |

## Appendices Table-Testing Result

| Table 4.4.2 Operating frequency range | | | P |
|---|---|---|---|
| **Requirement** | **Frequency range** | **Time period for operation Minimum requirement** | **Time period for operation stringent requirement** |
| | 47.0 Hz – 47.5 Hz | Not required | 20s |
| | 47.5 Hz - 48.5Hz | 30 min [a] | 90 min |
| | 48.5 Hz - 49.0 Hz | 30 min [a] | 90 min [a] |
| | 49.0 Hz - 51.0 Hz | Unlimited | Unlimited |
| | 51.0 Hz - 51.5 Hz | 30 min [a] | 90 min |
| | 51.5 Hz - 52.0 Hz | Not required | 15 min |
| | a: Respecting the legal framework, it is possible that longer time periods are required by The responsible party in some synchronous areas, | | |

| Frequency (Hz) | F (Hz)- measure | Time (S)-limit | Time (S) | Result |
|---|---|---|---|---|
| 47.00 | 47.000 | 20s | >20s | Pass |
| 47.50 | 47.500 | 90min | >90min | Pass |
| 48.50 | 48.500 | 90min | >90min | Pass |
| 51.00 | 51.500 | 90min | >90min | Pass |
| 51.50 | 52.000 | 90min | >90min | Pass |
| 52.00 | 47.000 | 15min | >15min | Pass |



| Table 4.4.3 Minimal requirement for active power delivery at underfrequency | P |
|---|---|

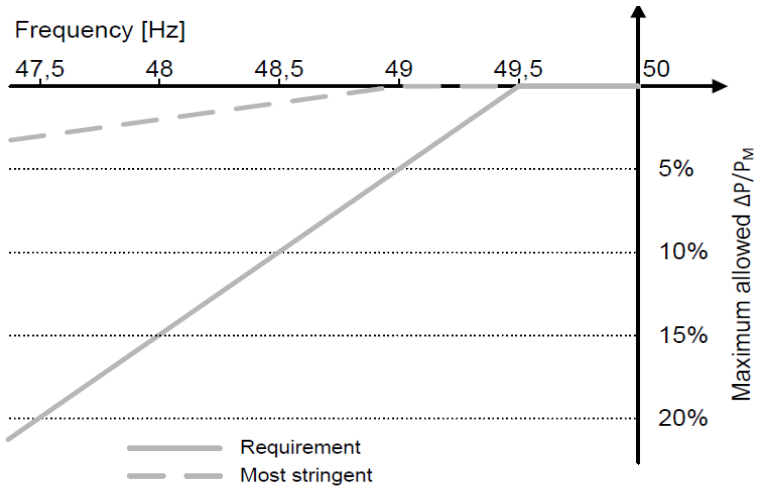
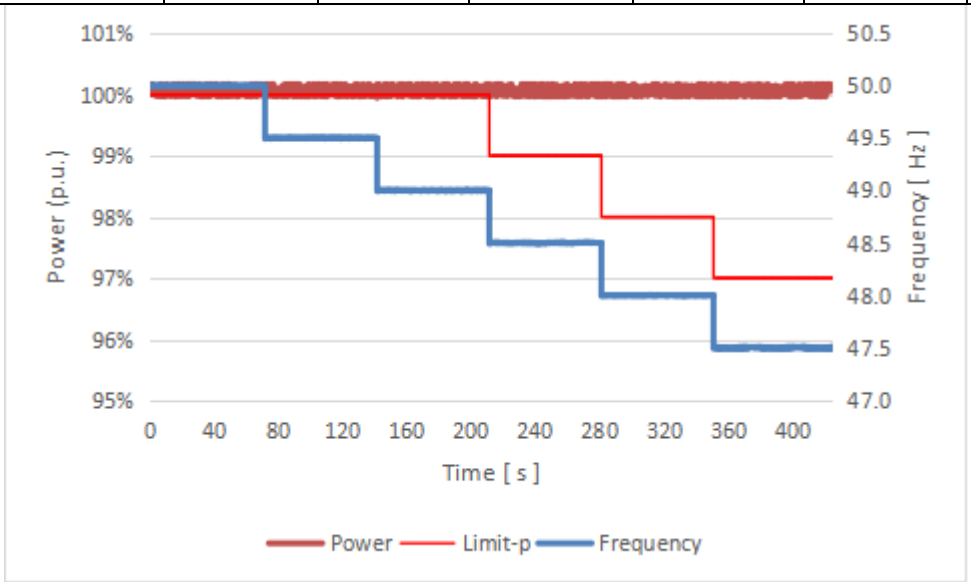


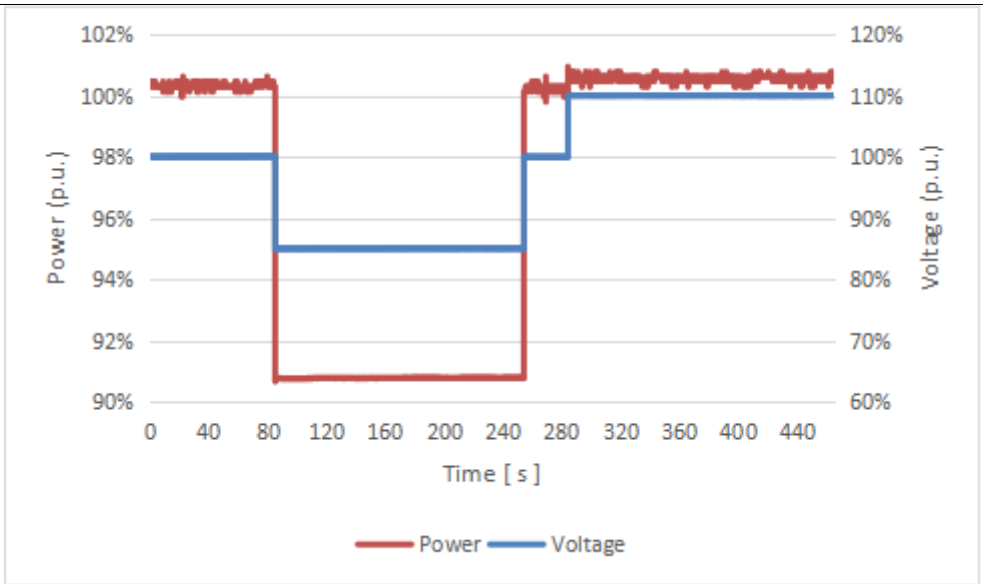

**Figure 5 — Maximum allowable power reduction in case of underfrequency**

**Test result**

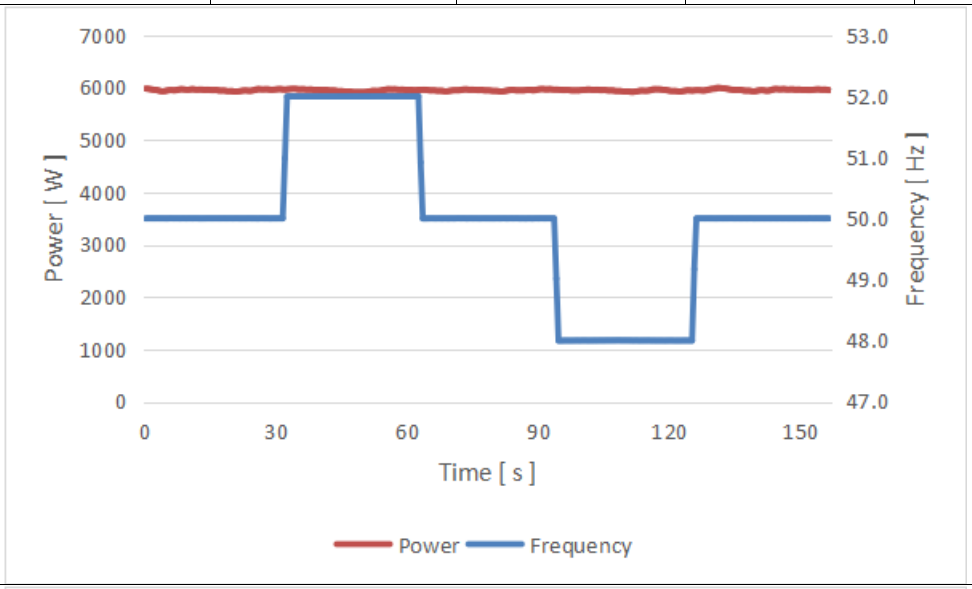
| Step | f (Hz) | fmea. (Hz) | T (s) | T meas. (s) | P (%) - max | P (%) - min | P meas. (%) |
|---|---|---|---|---|---|---|---|
| 1 | 50.00 ± 0.05 | 50.00 | >60 | 70 | 100% | 100% | 100.61% |
| 2 | 49.50 ± 0.05 | 49.50 | >60 | 70 | 100% | 100% | 100.63% |
| 3 | 49.00 ± 0.05 | 49.00 | >60 | 70 | 100% | 100% | 100.59% |
| 4 | 48.50 ± 0.05 | 48.50 | >60 | 70 | 100% | 99% | 100.55% |
| 5 | 48.00 ± 0.05 | 48.00 | >60 | 70 | 100% | 98% | 100.57% |
| 6 | 47.50 ± 0.05 | 47.50 | >60 | 70 | 100% | 97% | 100.59% |

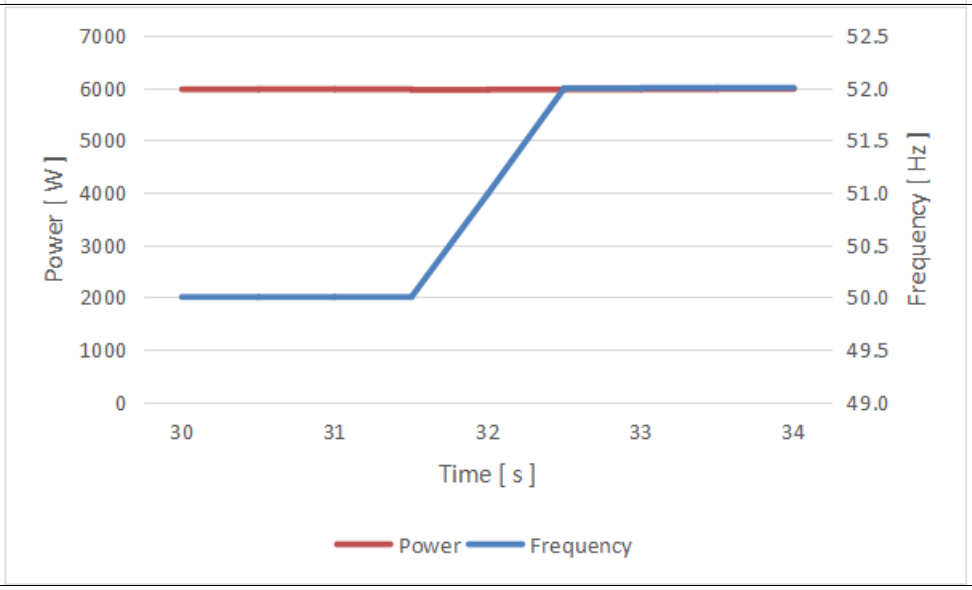


| Table 4.4.4 Continuous voltage operation range | | | | | P |
|---|---|---|---|---|---|
| **Test result** | | | | | |
| Step | Voltage (%) | P (%) | P meas. (%) | Time (s) | T meas (s) |
| 1 | 100 | 100 | 100.32 | >60 | 85 |
| 2 | 85 | 100 (*) | 90.77 | >120 | 170 |
| 3 | 100 | 100 | 100.23 | >5 | 30 |
| 4 | 110 | 100 | 100.57 | >120 | 180 |
| (*) Active power reduction is allowed due to current limitation. | | | | | |

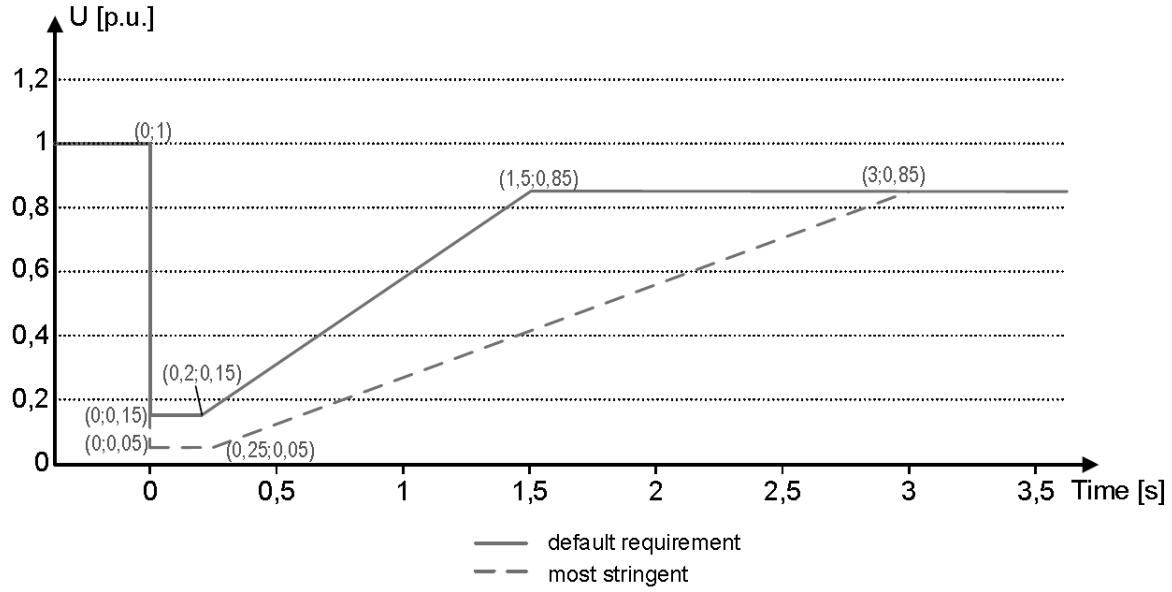


| Table 4.5.2 Rate of change of frequency (ROCOF) | | | | | P |
|---|---|---|---|---|---|
| **Test result** | | | | | |
| Steps | f (Hz) | Δt (s) step change | Step time | f meas. (Hz) | t meas. (s) |
| 1 | 50.00 ± 0.05 | -- | >10 s | 50.00 | 30 |
| 2 | 52.00 ± 0.05 | < 1 s | >10 s | 52.00 | 30 |
| 3 | 50.00 ± 0.05 | < 1 s | >10 s | 50.00 | 30 |
| 4 | 48.00 ± 0.05 | < 1 s | >10 s | 48.00 | 30 |
| 5 | 50.00 ± 0.05 | < 1 s | >10 s | 50.00 | 30 |



| Table 4.5.3 UVRT | P |
|---|---|

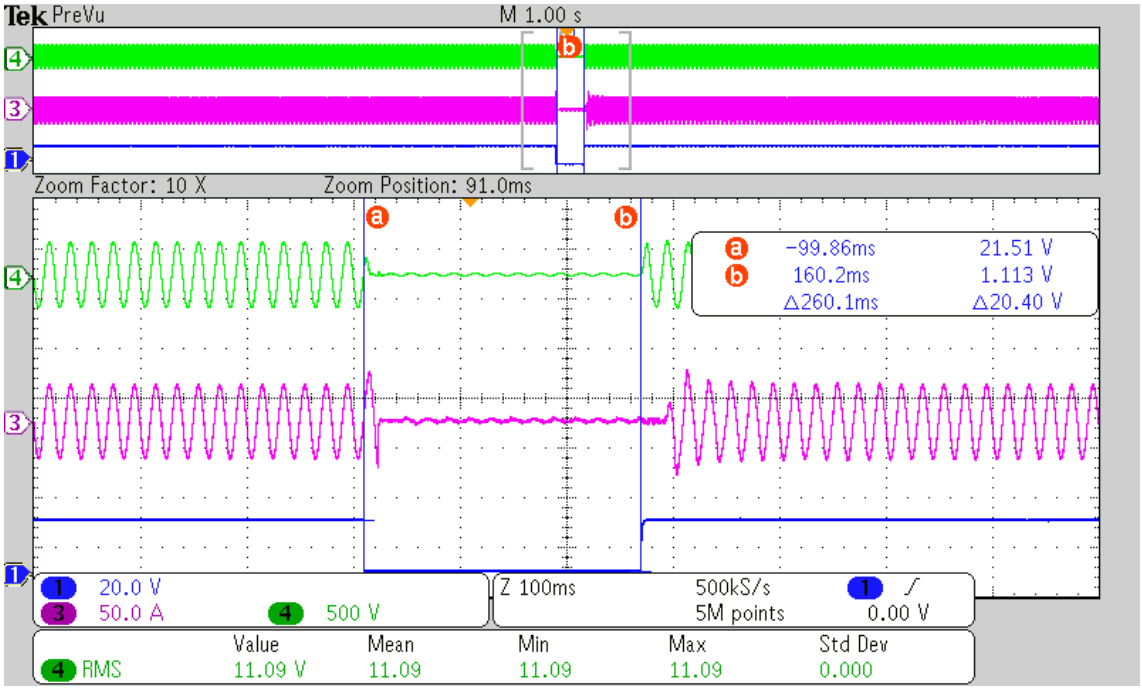



**Test result**

**Test at full load (>90%)**

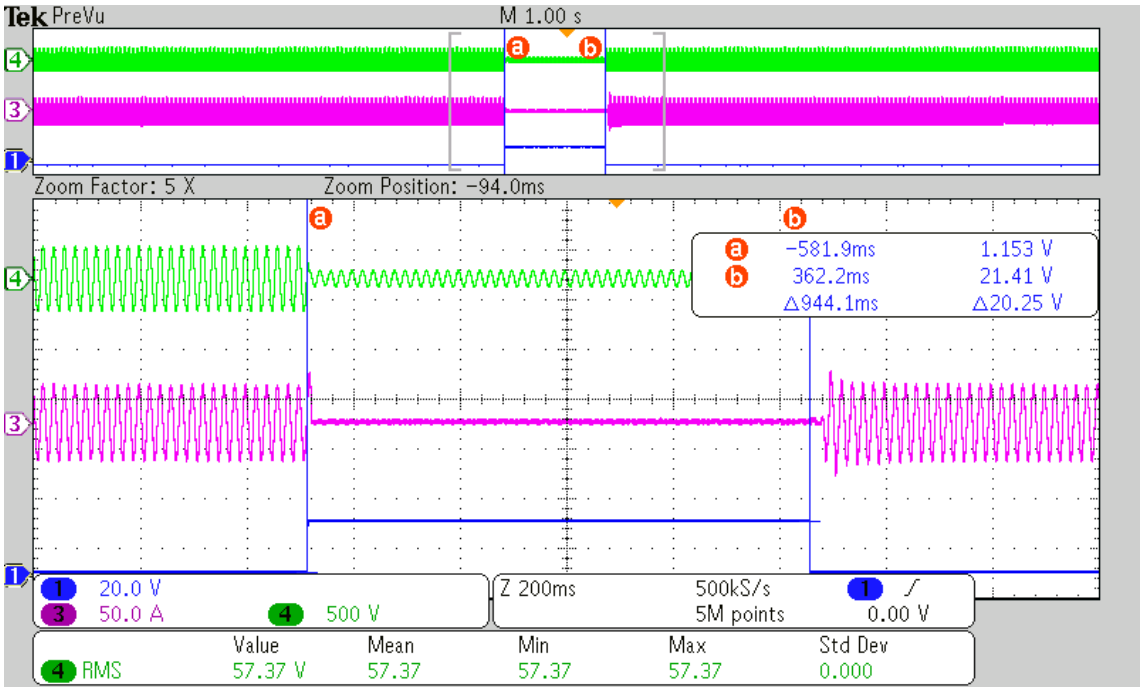
| Udip | t min (ms) | U meas. (V) | T meas. (ms) | P recover (s) |
|---|---|---|---|---|
| 5% | 250 | 4.82% | 260.1 | 0.064 |
| 25% | 938 | 24.94% | 944.1 | 0.070 |
| 50% | 1797 | 49.74% | 1803.0 | 0.062 |
| 75% | 2656 | 74.91% | 2663.0 | 0.042 |

Remark:
The tests are performed together with clause 4.7.4.2.2 Zero current mode and enabling of default setting: Undervoltage of 50%Un.

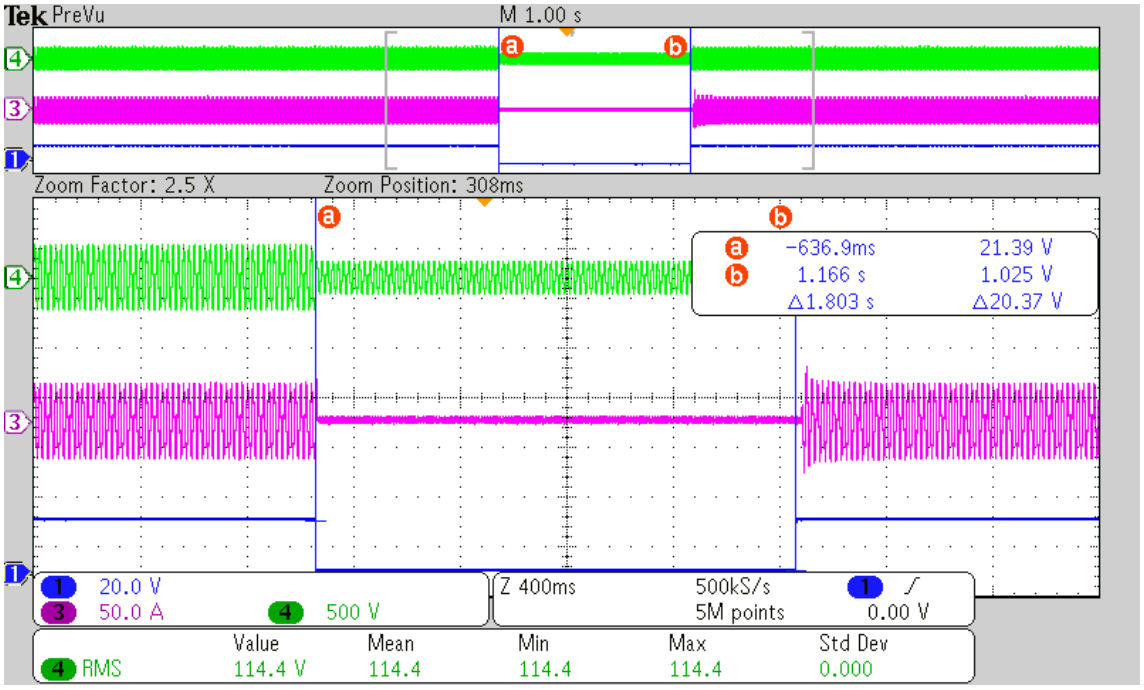



Graph_5%

| Table 4.5.3 UVRT | P |
|---|---|

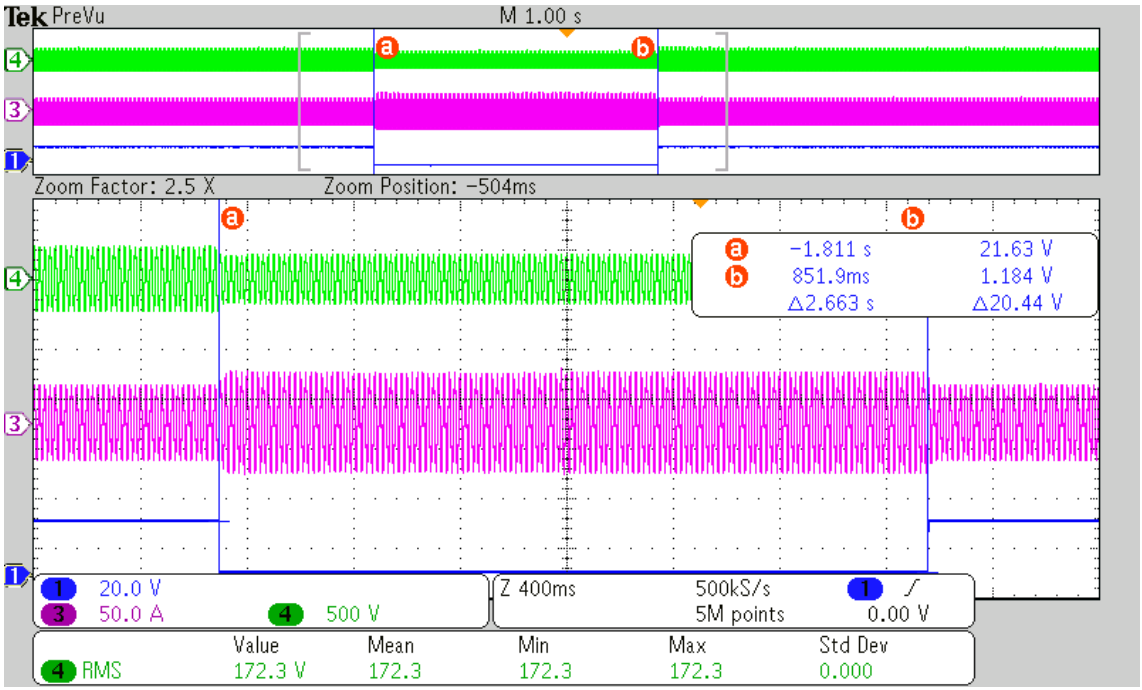



Graph_25%




Graph_50%

| Table 4.5.3 UVRT | P |
|---|---|




Graph_75%

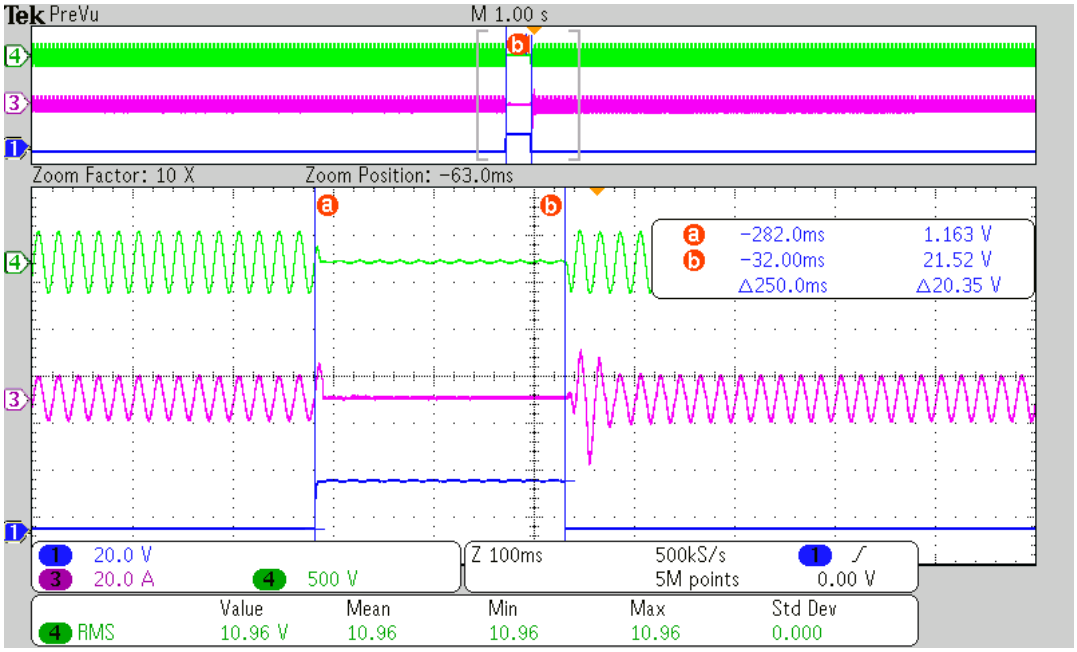
| Table 4.5.3 UVRT | P |
|---|---|

**Test result**

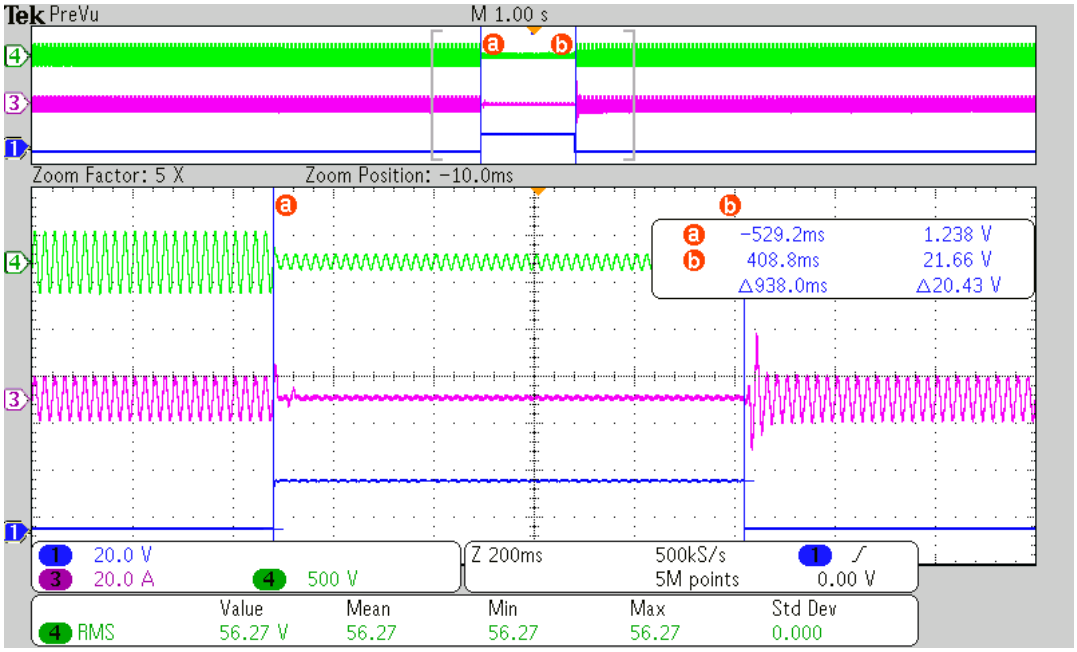
**Test at partial load (30%)**

| Udip | t min (ms) | U meas. (V) | T meas. (ms) | P recover (s) |
|---|---|---|---|---|
| 5% | 250 | 4.77% | 250.0 | 0.012 |
| 25% | 938 | 24.47% | 938.0 | 0.042 |
| 50% | 1797 | 49.39% | 1797.0 | 0.036 |
| 75% | 2656 | 74.87% | 2666.0 | 0.018 |

Remark:
The tests are performed together with clause 4.7.4.2.2 Zero current mode and enabling of default setting: Undervoltage of 50%Un.

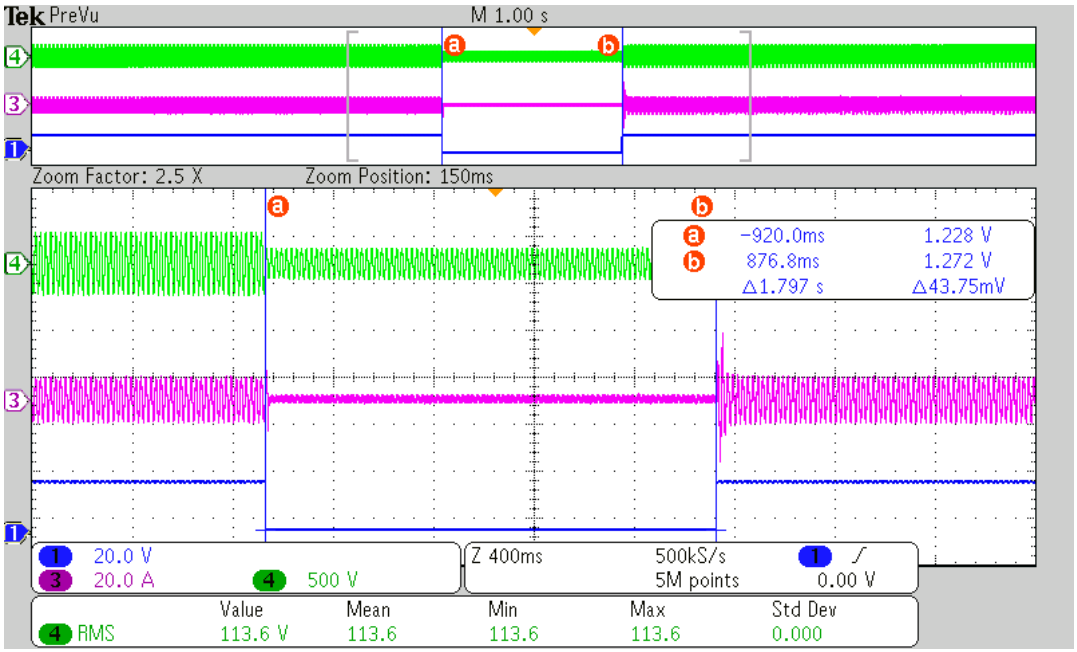



Graph_5%

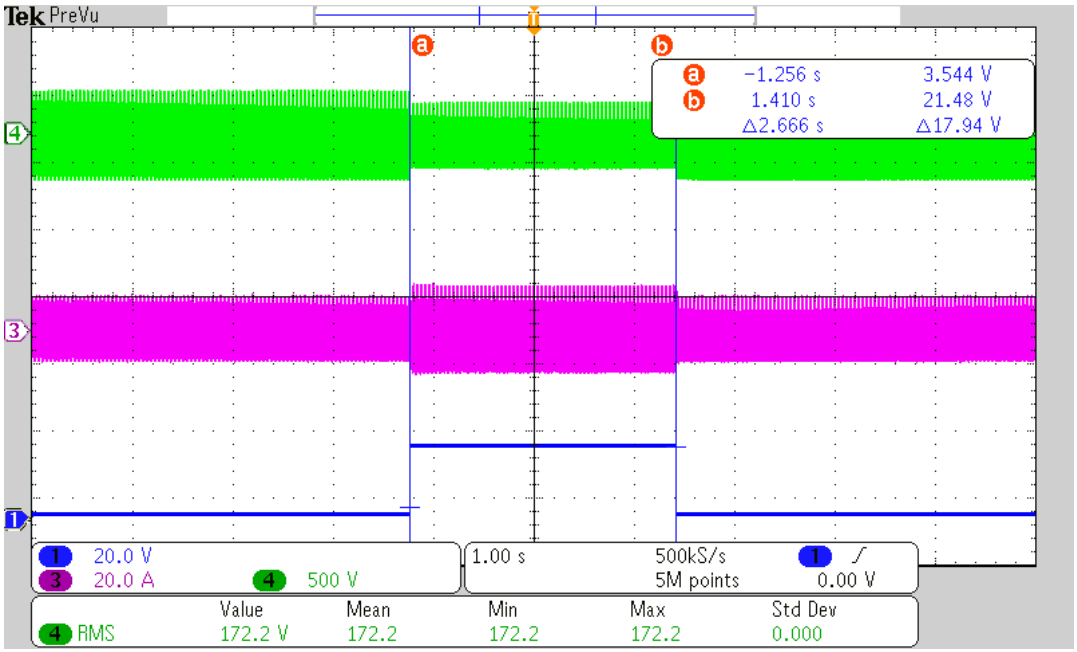



Graph_25%

| Table 4.5.3 UVRT | P |
|---|---|




Graph_50%




Graph_75%

| Table 4.5.4 OVRT | P |
|---|---|

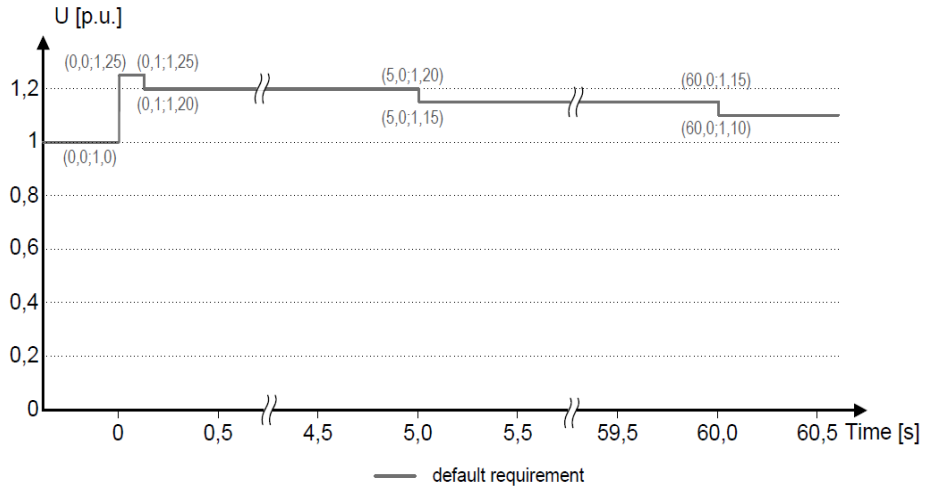


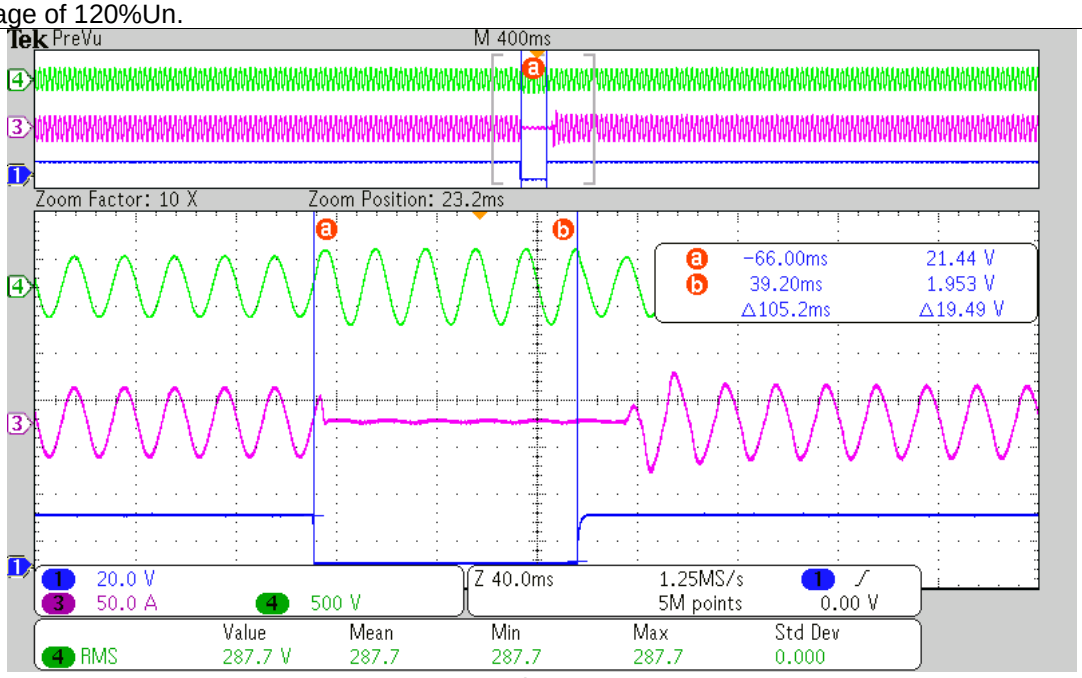

**Figure 8 — Over-voltage ride through capability**

**Test result**

**Test at full load (>90%)**

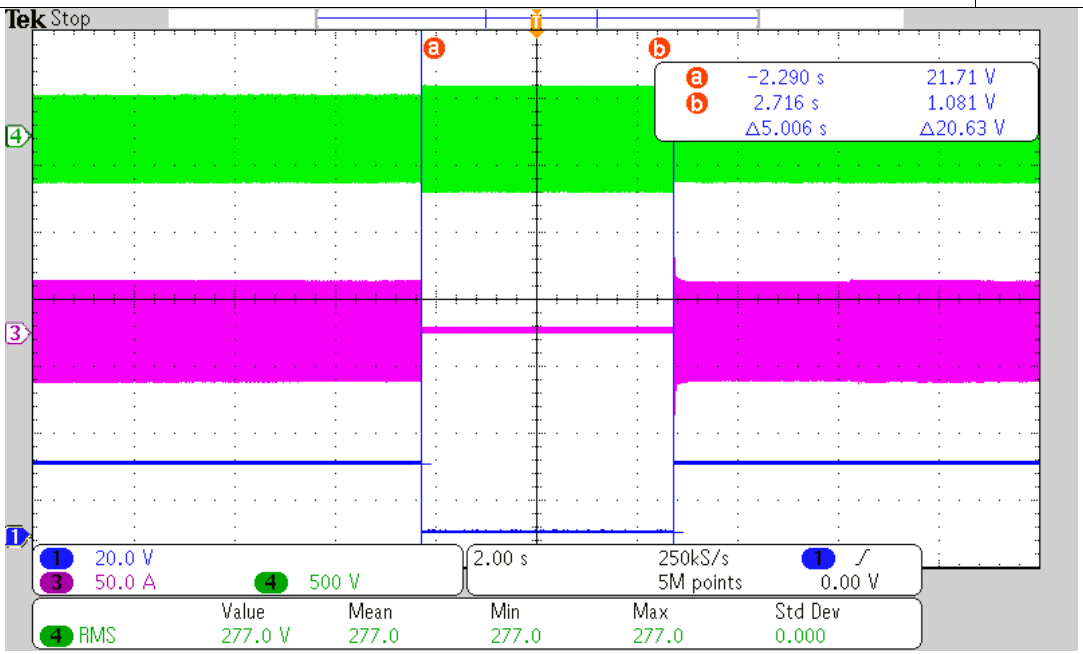
| Udip | t min (ms) | U meas. (%) | T meas. (ms) | P recover (s) |
|---|---|---|---|---|
| 125% | 100 | 125.09% | 105.2 | 0.059 |
| 120% | 5000 | 120.43% | 5006 | 0.064 |
| 115% | 60000 | 115.48% | 60040 | 0.045 |

Remark:
The tests are performed together with clause 4.7.4.2.2 Zero current mode and enabling of default setting: Overvoltage of 120%Un.

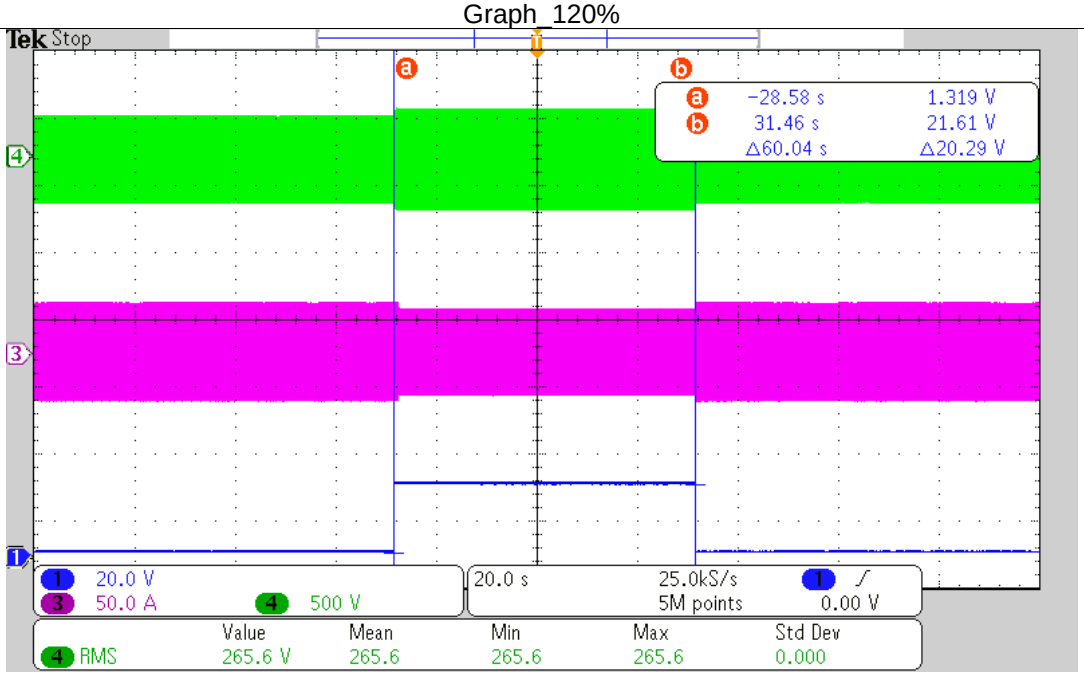



Graph_125%

| Table 4.5.4 OVRT | P |
|---|---|




Graph_120%



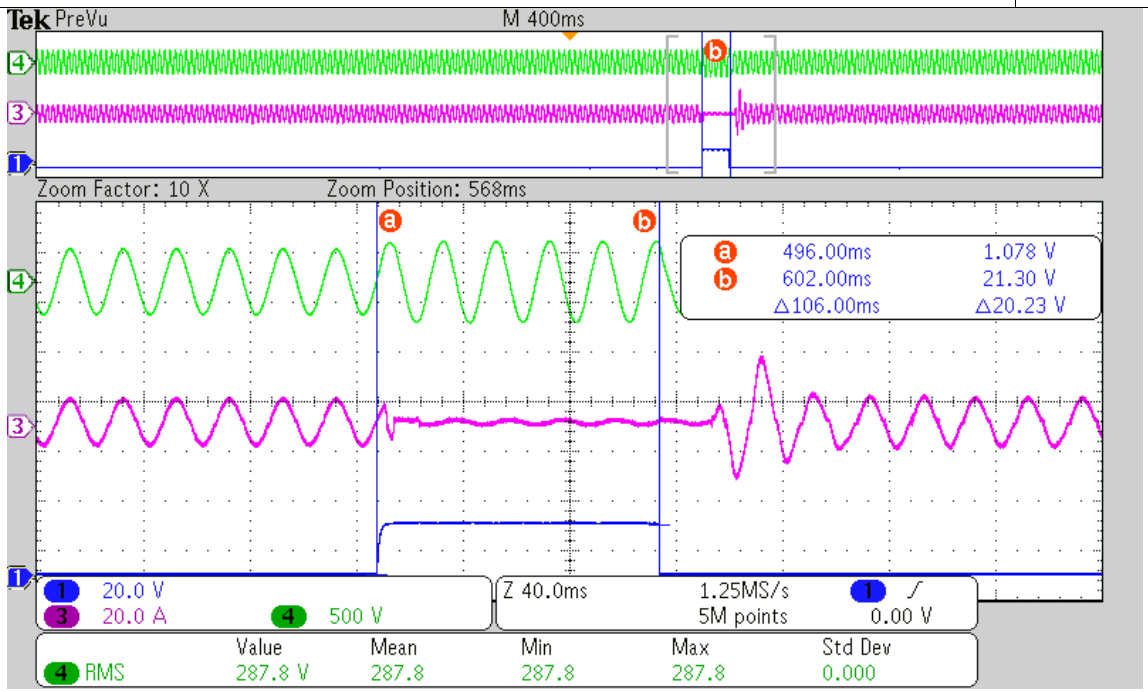

Graph_115%

**Test at partial load (20%Pn)**

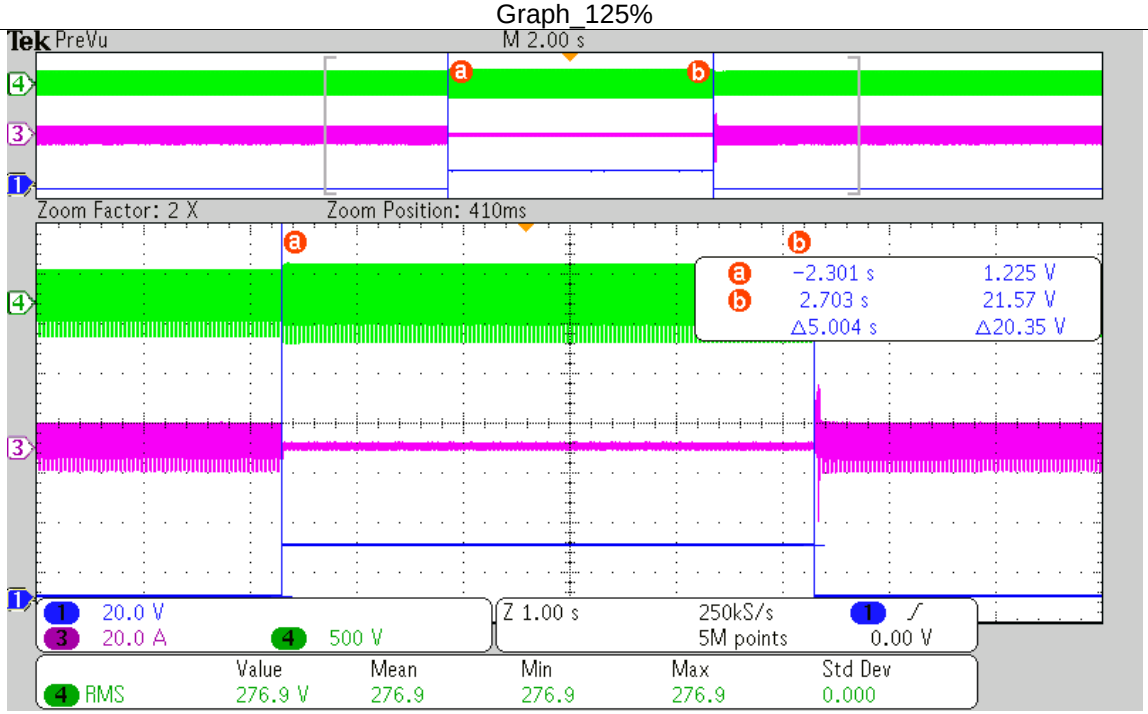
| Udip | T min (ms) | U meas. (%) | T meas. (ms) | P recover (s) |
|---|---|---|---|---|
| 125% | 100 | 125.13% | 106.0 | 0.058 |
| 120% | 5000 | 120.39% | 5004.0 | 0.064 |
| 115% | 60000 | 115.30% | 60040.0 | 0.044 |

Remark:
The tests are performed together with clause 4.7.4.2.2 Zero current mode and enabling of default setting: Overvoltage of 120%Un.

| Table 4.5.4 OVRT | P |
|---|---|

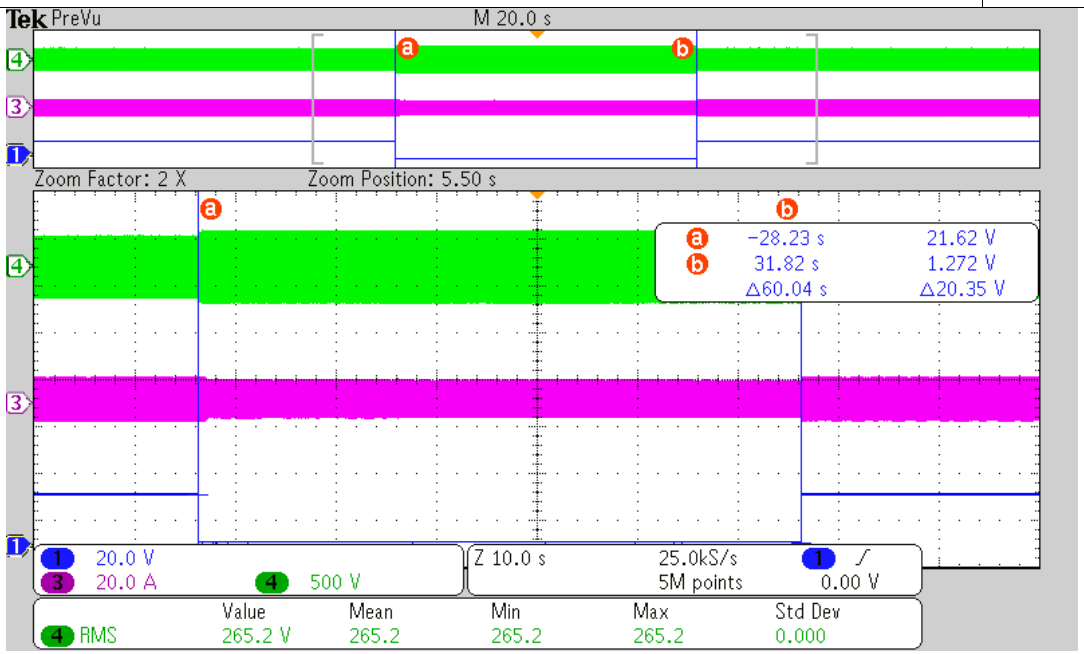



Graph_125%




Graph_120%

| Table 4.5.4 OVRT | P |
|---|---|




Graph_115%

| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|

**Discharging and Grid tied mode**

| Test 1 | 100% Pn, f1 =50.2Hz; droop=12%; f-stop deactivated, with delay of 2 s | | | | | | |
|---|---|---|---|---|---|---|---|
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | 6003.92 | 6000.00 | -- | -- | -- | -- |
| 50.2Hz ± 0.01Hz | 50.20 | 5997.35 | 6000.00 | -- | -- | -- | -- |
| 50.70Hz ± 0.01Hz | 50.70 | 5546.15 | 5500.00 | 46.15 | ± 600 | 1.4s | 1.4s |
| 51.15Hz ± 0.01Hz | 51.15 | 5128.12 | 5050.00 | 78.12 | ± 600 | 0.4s | 0.6s |
| 52.0Hz ± 0.01Hz | 52.00 | 4277.14 | 4200.00 | 77.14 | ± 600 | 0.2s | 0.4s |
| 51.15Hz ± 0.01Hz | 51.15 | 5127.64 | 5050.00 | 77.64 | ± 600 | 0.4s | 0.4s |
| 50.70Hz ± 0.01Hz | 50.70 | 5536.42 | 5500.00 | 36.42 | ± 600 | 0.2s | 0.4s |
| 50.2Hz ± 0.01Hz | 50.20 | 5998.31 | 6000.00 | -- | -- | 0.4s | 0.6s |
| 50Hz ± 0.01Hz | 50.00 | 6006.04 | 6000.00 | -- | -- | -- | -- |
| Test 2 | 100% Pn, f1 =50.2Hz; droop=2%; f-stop deactivated, no delay | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | 6007.54 | -- | -- | -- | -- | -- |
| 50.2Hz ± 0.01Hz | 50.20 | 5966.27 | -- | -- | -- | -- | -- |
| 50.70Hz ± 0.01Hz | 50.70 | 3022.82 | 3000.00 | 22.82 | ± 600 | 0.4s | 0.4s |
| 51.15Hz ± 0.01Hz | 51.15 | 455.90 | 300.00 | 155.90 | ± 600 | 0.2s | 0.4s |
| 52.0Hz ± 0.01Hz | 52.00 | 23.53 | 0.00 | 23.53 | ± 600 | 0.4s | 0.4s |
| 51.15Hz ± 0.01Hz | 51.15 | 471.70 | 300.00 | 171.70 | ± 600 | 0.2s | 0.4s |
| 50.70Hz ± 0.01Hz | 50.70 | 3071.37 | 3000.00 | 71.37 | ± 600 | 0.4s | 0.4s |
| 50.2Hz ± 0.01Hz | 50.20 | 5999.88 | -- | -- | -- | 0.4s | 0.4s |
| 50Hz ± 0.01Hz | 50.00 | 6004.92 | -- | -- | -- | -- | -- |

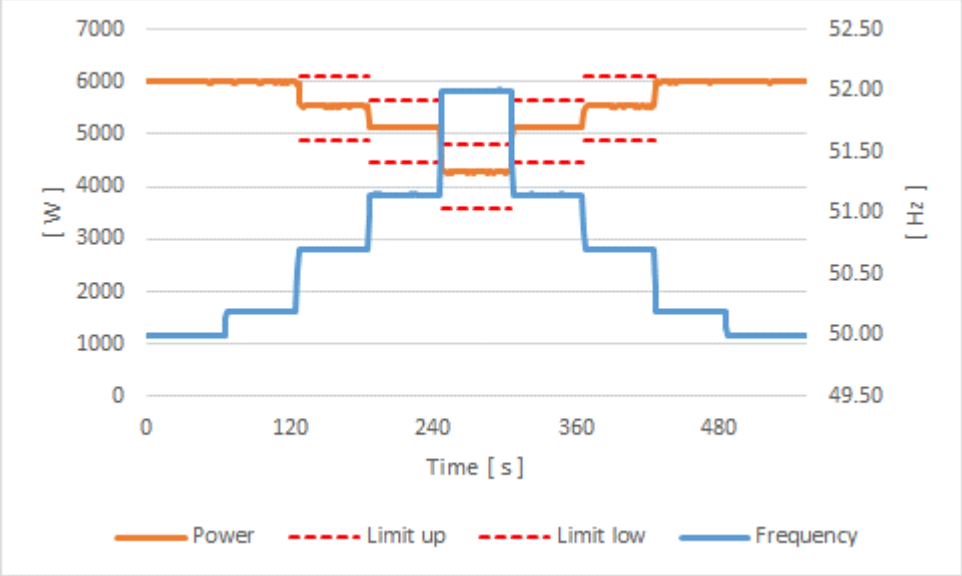
| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|

**Discharging and Grid tied mode**

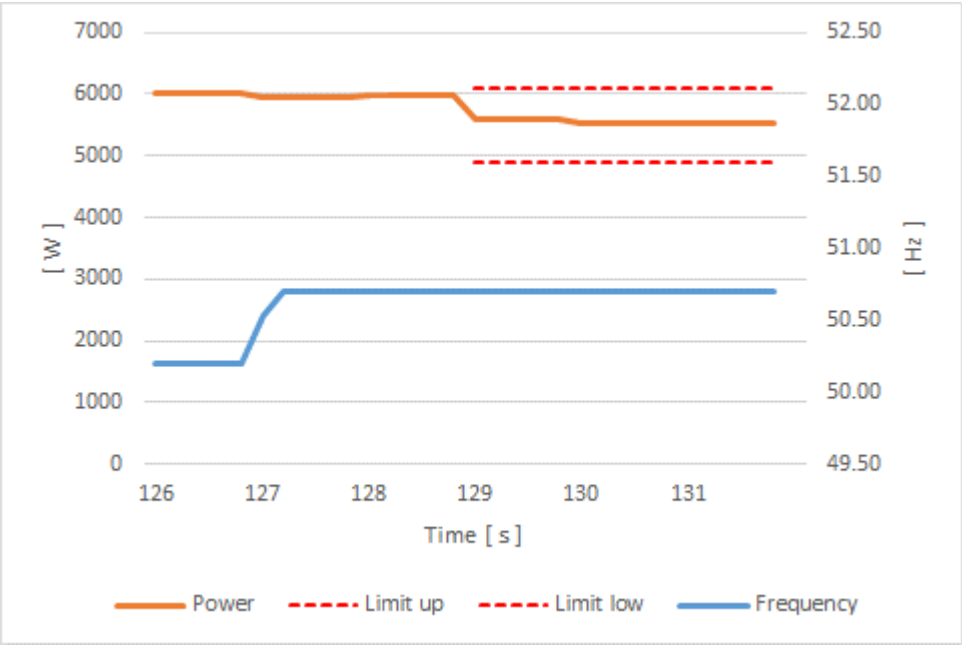
| Test 3 | 50% Pn, f1 =52.0Hz; droop=5%; f-stop deactivated, no delay | | | | | | |
|---|---|---|---|---|---|---|---|
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | 3039.09 | -- | -- | -- | -- | -- |
| 51.0Hz ± 0.01Hz | 51.00 | 3045.32 | 3000.00 | 45.32 | ± 600 | -- | -- |
| 51.70Hz ± 0.01Hz | 51.70 | 3044.51 | 3000.00 | 44.51 | ± 600 | -- | -- |
| 52.0Hz ± 0.01Hz | 52.00 | 3047.25 | 3000.00 | 47.25 | ± 600 | -- | -- |
| 51.70Hz ± 0.01Hz | 51.70 | 3047.03 | 3000.00 | 47.03 | ± 600 | -- | -- |
| 51.00Hz ± 0.01Hz | 51.00 | 3047.15 | 3000.00 | 47.15 | ± 600 | -- | -- |
| 50Hz ± 0.01Hz | 50.00 | 3040.88 | -- | -- | -- | -- | -- |
| Test 4 | 100% Pn, f1 =50.2Hz; droop=5%; f-stop =50.1, no delay, Deactivation time $t_{stop}$ 30s | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | 5997.84 | 6000 | -- | -- | -- | -- |
| 50.2Hz ± 0.01Hz | 50.20 | 5988.50 | 6000 | -- | -- | -- | -- |
| 50.70Hz ± 0.01Hz | 50.70 | 4702.30 | 4800 | -97.70 | ± 600 | 0.4s | 0.4s |
| 51.15Hz ± 0.01Hz | 51.15 | 3667.42 | 3720 | -52.58 | ± 600 | 0.2s | 0.4s |
| 52.0Hz ± 0.01Hz | 52.00 | 1710.10 | 1680 | 30.10 | ± 600 | 0.4s | 0.4s |
| 51.15Hz ± 0.01Hz | 51.15 | 1698.12 | 1680 | 18.12 | ± 600 | -- | -- |
| 50.70Hz ± 0.01Hz | 50.70 | 1698.43 | 1680 | 18.43 | ± 600 | -- | -- |
| 50.2Hz ± 0.01Hz | 50.20 | 1698.29 | 1680 | -- | ± 600 | -- | -- |
| 50Hz ± 0.01Hz | 50.00 | 6003.97 | 6000 | -- | -- | -- | -- |

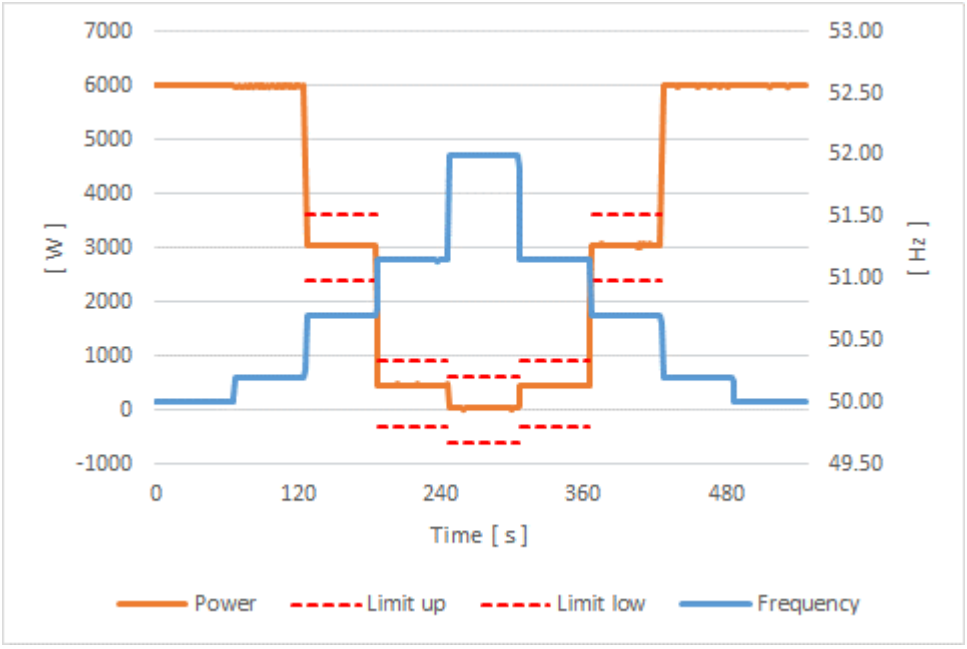
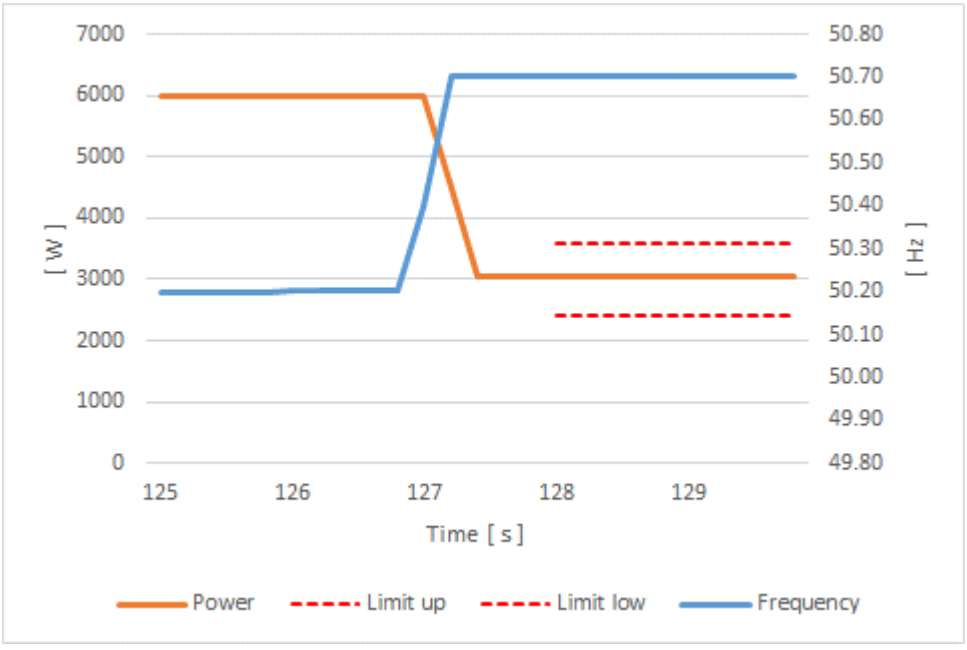
| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|
| **Discharging and Grid tied mode** | | |

Test 1_Graph




Intentional delay time (2s)

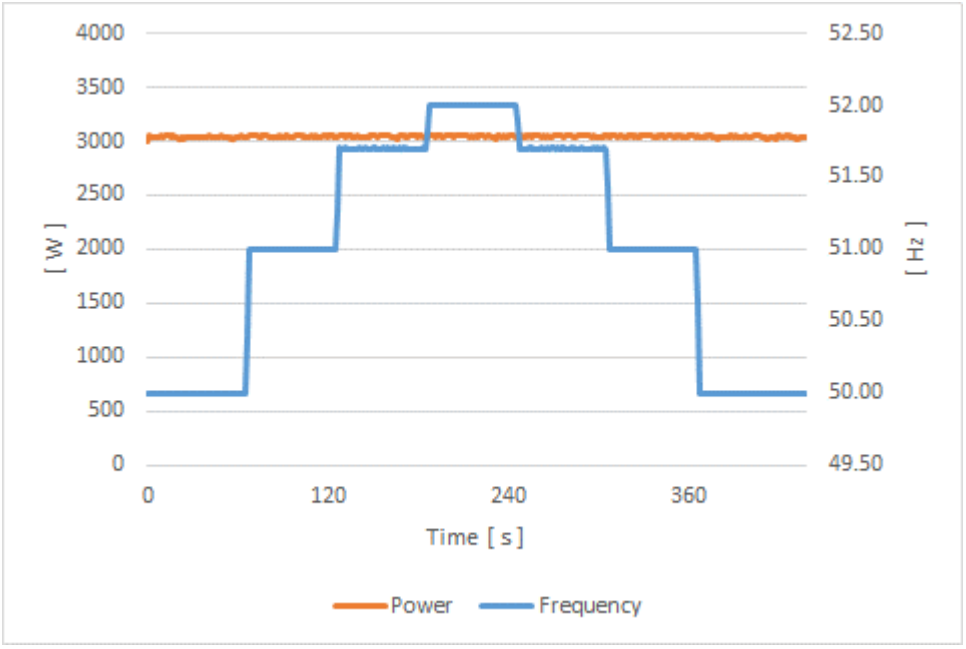


| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|
| **Discharging and Grid tied mode** | | |
| Test 2_Graph | | |
|  | | |
| Step response time (T≤2s) | | |
|  | | |

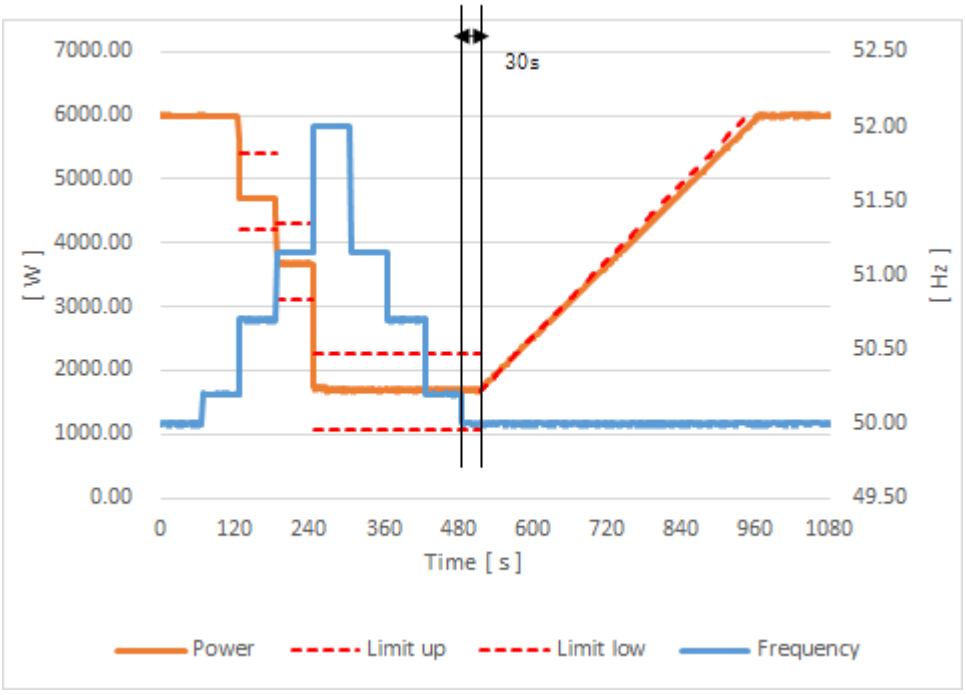
| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|

**Discharging and Grid tied mode**

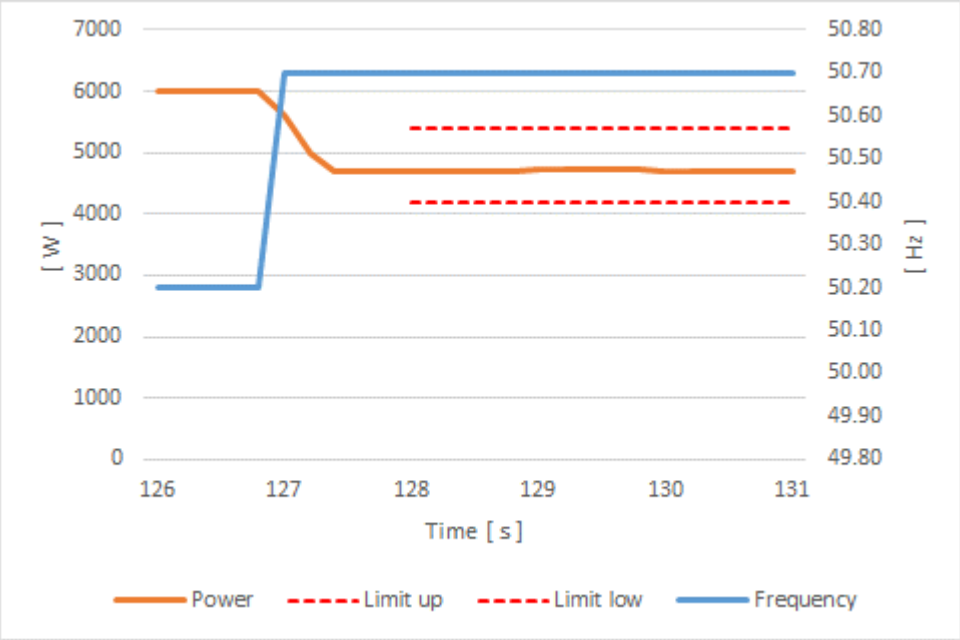
Test 3_Graph




Test 4_Graph



| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|
| **Discharging and Grid tied mode** | | |
| Step response time (T≤2s) | | |



| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|

**Charging mode**

| Test 1 | -50% Pn, f1 =50.2Hz; droop=12%; f-stop deactivated, with delay of 2 s | | | | | | |
|---|---|---|---|---|---|---|---|
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -3016.89 | -3000 | -- | -- | -- | -- |
| 50.2Hz ± 0.01Hz | 50.20 | -3015.60 | -3000 | -- | -- | -- | -- |
| 50.70Hz ± 0.01Hz | 50.70 | -3494.61 | -3500 | 5.39 | ± 600 | 1.2s | 1.4s |
| 51.15Hz ± 0.01Hz | 51.15 | -3935.88 | -3950 | 14.12 | ± 600 | 0.4s | 0.6s |
| 52.0Hz ± 0.01Hz | 52.00 | -4763.58 | -4800 | 36.42 | ± 600 | 0.2s | 0.4s |
| 51.15Hz ± 0.01Hz | 51.15 | -3934.00 | -3950 | 16.00 | ± 600 | 0.2s | 0.4s |
| 50.70Hz ± 0.01Hz | 50.70 | -3497.42 | -3500 | 2.58 | ± 600 | 0.2s | 0.4s |
| 50.2Hz ± 0.01Hz | 50.20 | -3018.73 | -3000 | -- | -- | 0.4s | 0.6s |
| 50Hz ± 0.01Hz | 50.00 | -3017.87 | -3000 | -- | -- | -- | -- |
| Test 2 | -50% Pn, f1 =50.2Hz; droop=2%; f-stop deactivated, no delay | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -3015.94 | -3000 | -- | -- | -- | -- |
| 50.2Hz ± 0.01Hz | 50.20 | -3017.05 | -3000 | -- | -- | -- | -- |
| 50.70Hz ± 0.01Hz | 50.70 | -6030.57 | -6000 | -30.57 | ± 600 | 0.4s | 0.4s |
| 51.15Hz ± 0.01Hz | 51.15 | -6034.58 | -6000 | -34.58 | ± 600 | 0.4s | 0.4s |
| 52.0Hz ± 0.01Hz | 52.00 | -6034.27 | -6000 | -34.27 | ± 600 | 0.1s | 0.1s |
| 51.15Hz ± 0.01Hz | 51.15 | -6036.45 | -6000 | -36.45 | ± 600 | 0.1s | 0.1s |
| 50.70Hz ± 0.01Hz | 50.70 | -6046.50 | -6000 | -46.50 | ± 600 | 0.1s | 0.1s |
| 50.2Hz ± 0.01Hz | 50.20 | -3021.65 | -3000 | -- | -- | 0.4s | 0.6s |
| 50Hz ± 0.01Hz | 50.00 | -3013.62 | -3000 | -- | -- | -- | -- |

| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|

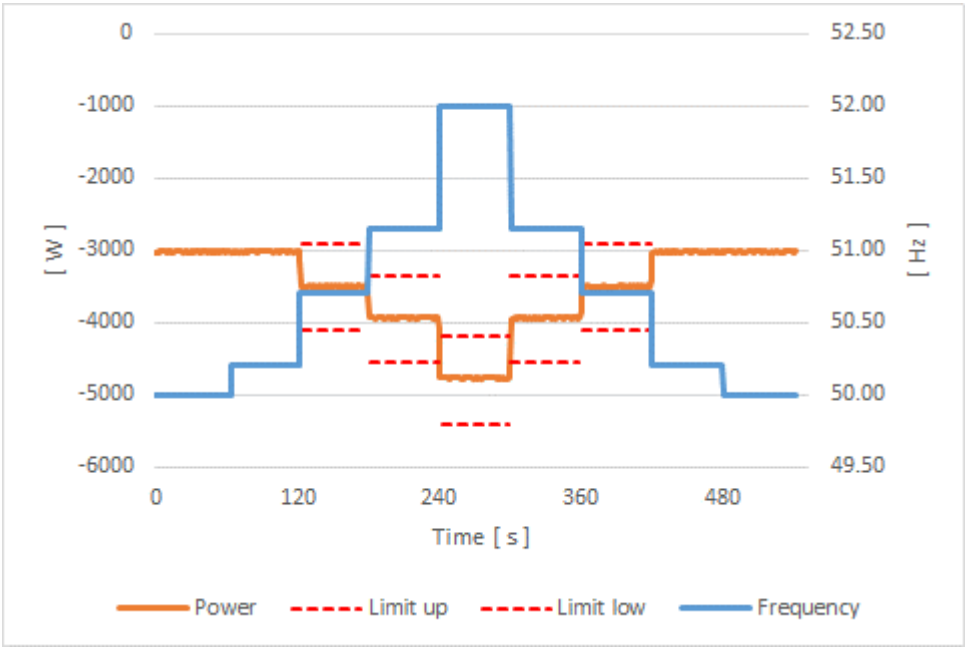
**Charging mode**

| Test 3 | 0% Pn, f1 =52.0Hz; droop=5%; f-stop deactivated, no delay | | | | | | |
|---|---|---|---|---|---|---|---|
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -100.80 | -- | -- | -- | -- | -- |
| 51.0Hz ± 0.01Hz | 51.00 | -101.68 | 0 | -101.68 | ± 600 | -- | -- |
| 51.70Hz ± 0.01Hz | 51.70 | -101.47 | 0 | -101.47 | ± 600 | -- | -- |
| 52.0Hz ± 0.01Hz | 52.00 | -101.02 | 0 | -101.02 | ± 600 | -- | -- |
| 51.70Hz ± 0.01Hz | 51.70 | -100.15 | 0 | -100.15 | ± 600 | -- | -- |
| 51.00Hz ± 0.01Hz | 51.00 | -100.52 | 0 | -100.52 | ± 600 | -- | -- |
| 50Hz ± 0.01Hz | 50.00 | -97.79 | -- | -- | -- | -- | -- |
| Test 4 | 0% Pn, f1 =50.2Hz; droop=5%; f-stop =50.1, no delay, Deactivation time $t_{stop}$ 30s | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -9.98 | 0 | -- | -- | -- | -- |
| 50.2Hz ± 0.01Hz | 50.20 | -10.05 | 0 | -- | -- | -- | -- |
| 50.70Hz ± 0.01Hz | 50.70 | -1230.22 | -1200 | -30.22 | ± 600 | 0.4s | 0.6s |
| 51.15Hz ± 0.01Hz | 51.15 | -2327.22 | -2280 | -47.22 | ± 600 | 0.4s | 0.6s |
| 52.0Hz ± 0.01Hz | 52.00 | -4350.08 | -4320 | -30.08 | ± 600 | 0.4s | 0.6s |
| 51.15Hz ± 0.01Hz | 51.15 | -4365.18 | -4320 | -45.18 | ± 600 | -- | -- |
| 50.70Hz ± 0.01Hz | 50.70 | -4368.10 | -4320 | -48.10 | ± 600 | -- | -- |
| 50.2Hz ± 0.01Hz | 50.20 | -4368.46 | -4320 | -- | -- | -- | -- |
| 50Hz ± 0.01Hz | 50.00 | -10.03 | 0 | -- | -- | -- | -- |

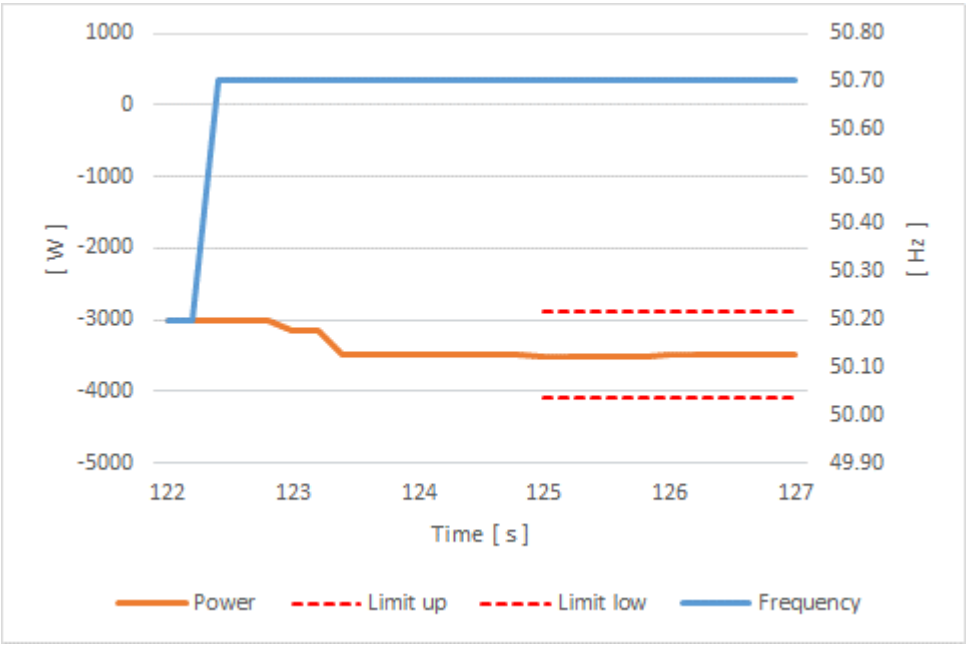
| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|

**Charging mode**

Test 1_Graph



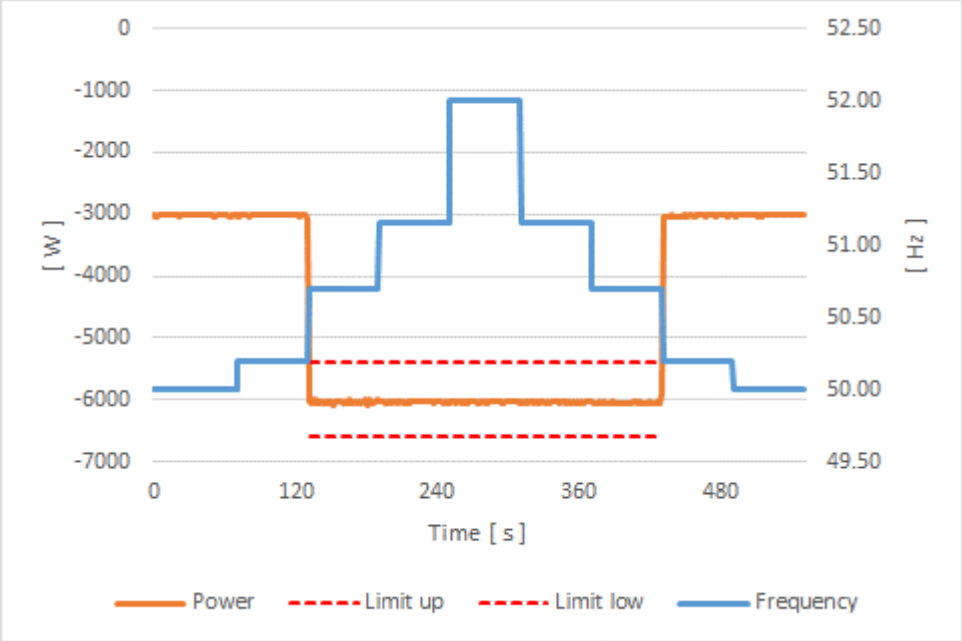

Intentional delay time (2s)



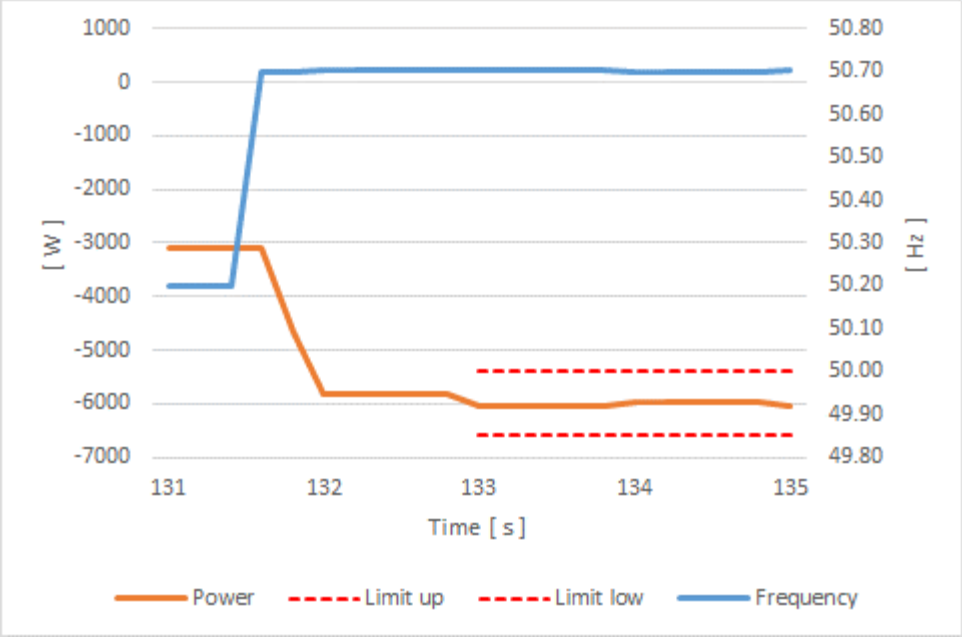
| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|

**Charging mode**

Test 2_Graph



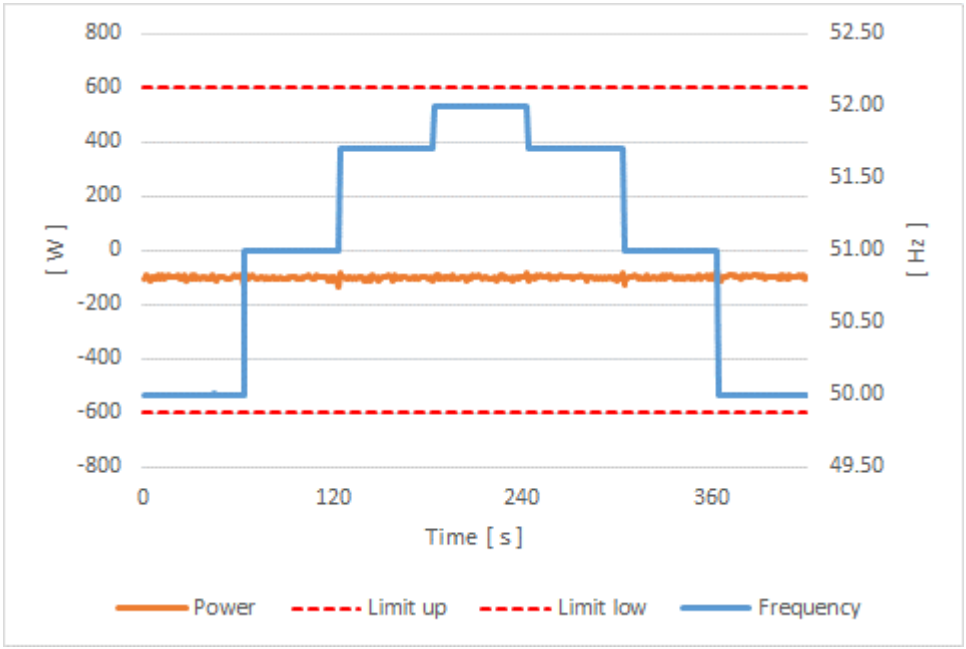

Step response time (T≤2s)



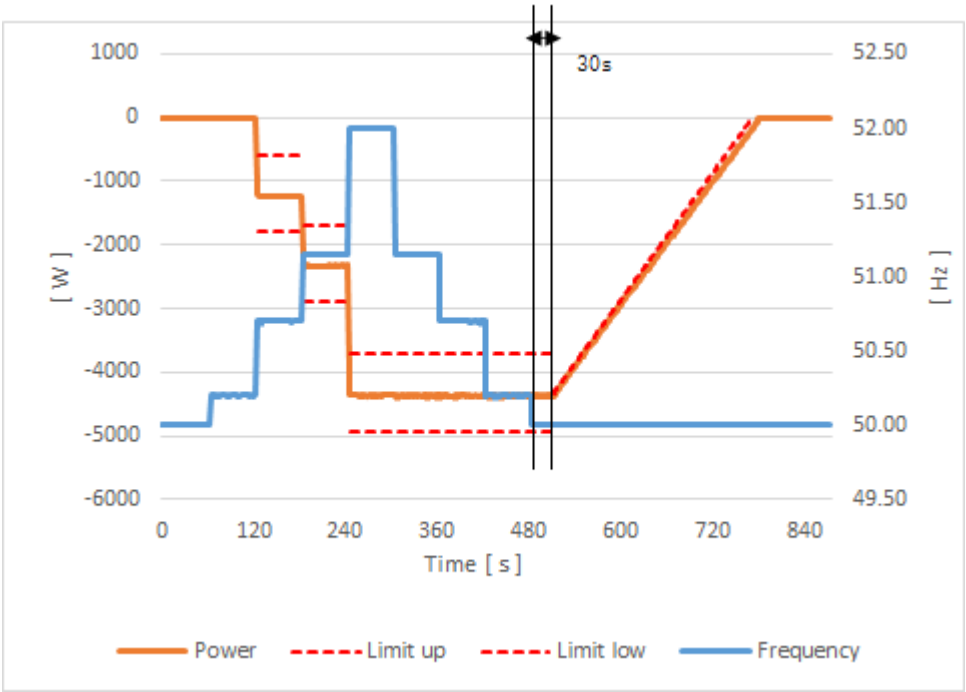
| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|

**Charging mode**

Test 3_Graph

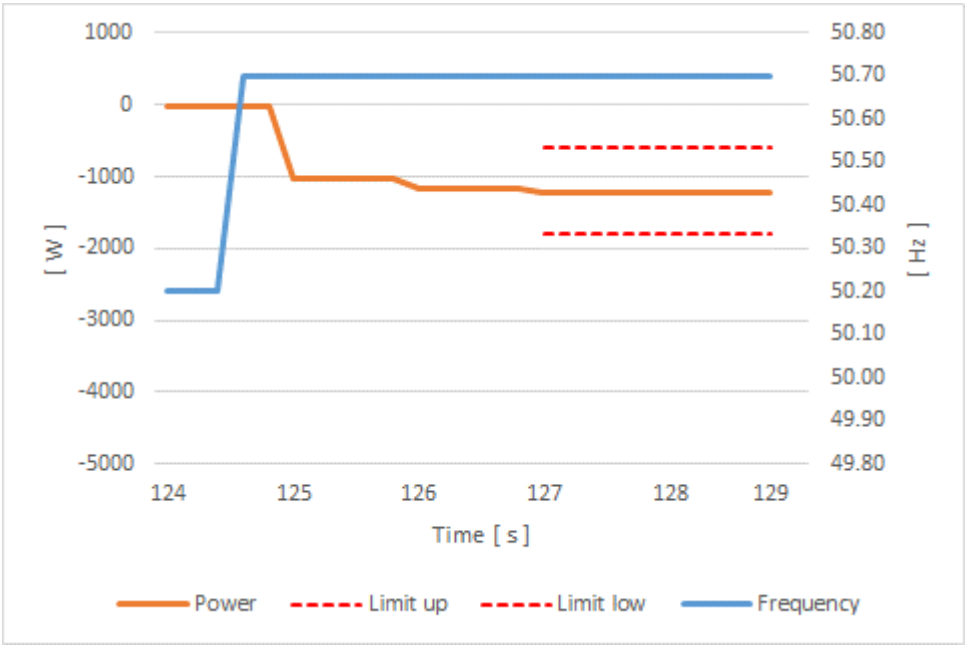



Test 4_Graph



| 4.6.1 | Table: Power response to over frequency | P |
|---|---|---|
| **Charging mode** | | |

Step response time (T≤2s)

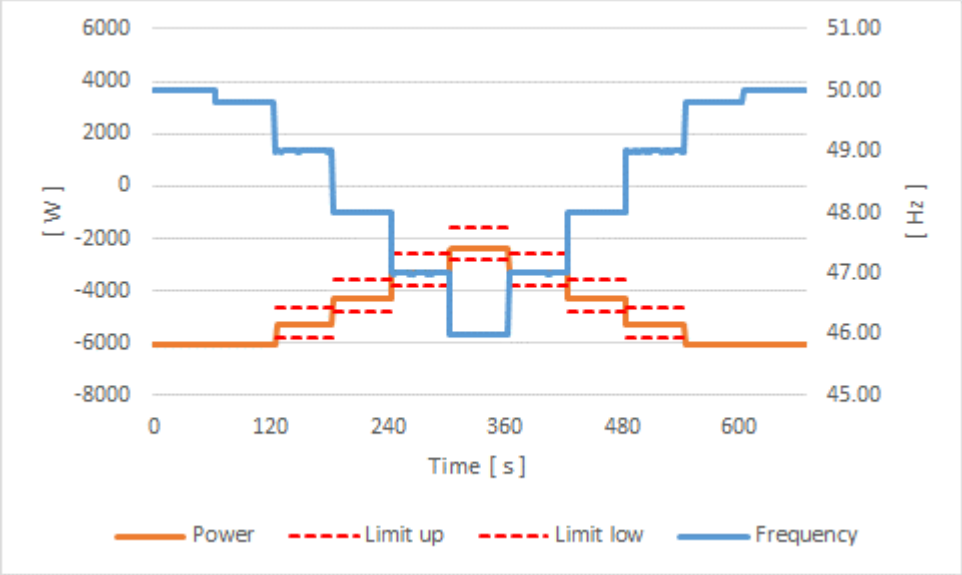


| 4.6.2 | Table: Power response to under frequency | | | | | | P |
|---|---|---|---|---|---|---|---|
| Test 1 | -100% Pn, f1 =49.8Hz; droop=12%; with delay of 2 s | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -6043.41 | -- | -- | -- | -- | -- |
| 49.8Hz ± 0.01Hz | 49.80 | -6042.25 | -6000.00 | -42.25 | ± 600 | -- | -- |
| 49.0Hz ± 0.01z | 49.00 | -5302.35 | -5200.00 | -102.35 | ± 600 | 1.2s | 1.4s |
| 48.0Hz ± 0.01z | 48.00 | -4299.75 | -4200.00 | -99.75 | ± 600 | 0.4s | 0.6s |
| 47.0Hz ± 0.01z | 47.00 | -3324.00 | -3200.00 | -124.00 | ± 600 | 0.2s | 0.4s |
| 46.0Hz ± 0.01z | 46.00 | -2393.65 | -2200.00 | -193.65 | ± 600 | 0.4s | 0.6s |
| 47.0Hz ± 0.01z | 47.00 | -3310.73 | -3200.00 | -110.73 | ± 600 | 0.4s | 0.6s |
| 48.0Hz ± 0.01z | 48.00 | -4299.25 | -4200.00 | -99.25 | ± 600 | 0.4s | 0.4s |
| 49.0Hz ± 0.01z | 49.00 | -5274.68 | -5200.00 | -74.68 | ± 600 | 0.4s | 0.6s |
| 49.8Hz ± 0.01Hz | 49.80 | -6050.17 | -6000.00 | -50.17 | ± 600 | 0.4s | 0.4s |
| 50.0Hz ± 0.01Hz | 50.00 | -6058.66 | -- | -- | -- | -- | -- |
| Test 2 | -100% Pn, f1 =49.8Hz; droop=2%; no delay | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -6059.19 | -- | -- | -- | -- | -- |
| 49.8Hz ± 0.01Hz | 49.80 | -6017.38 | -6000.00 | -17.38 | ± 600 | -- | -- |
| 49.0Hz ± 0.01Hz | 49.00 | -1264.73 | -1200.00 | -64.73 | ± 600 | 0.2s | 0.6s |
| 48.0Hz ± 0.01Hz | 48.00 | 4808.48 | 4800.00 | 8.48 | ± 600 | 0.4s | 0.6s |
| 47.0Hz ± 0.01Hz | 47.00 | 6033.30 | 6000.00 | 33.30 | ± 600 | 0.4s | 0.4s |
| 46.0Hz ± 0.01Hz | 46.00 | 6017.27 | 6000.00 | 17.27 | ± 600 | -- | -- |
| 47.0Hz ± 0.01Hz | 47.00 | 6026.70 | 6000.00 | 26.70 | ± 600 | -- | -- |
| 48.0Hz ± 0.01Hz | 48.00 | 4831.92 | 4800.00 | 31.92 | ± 600 | 0.4s | 0.4s |
| 49.0Hz ± 0.01Hz | 49.00 | -1215.75 | -1200.00 | -15.75 | ± 600 | 0.2s | 0.4s |
| 49.8Hz ± 0.01Hz | 49.80 | -6003.19 | -6000.00 | -3.19 | ± 600 | 0.6s | 0.8s |
| 50.0Hz ± 0.01Hz | 50.00 | -6046.90 | -- | -- | -- | -- | -- |

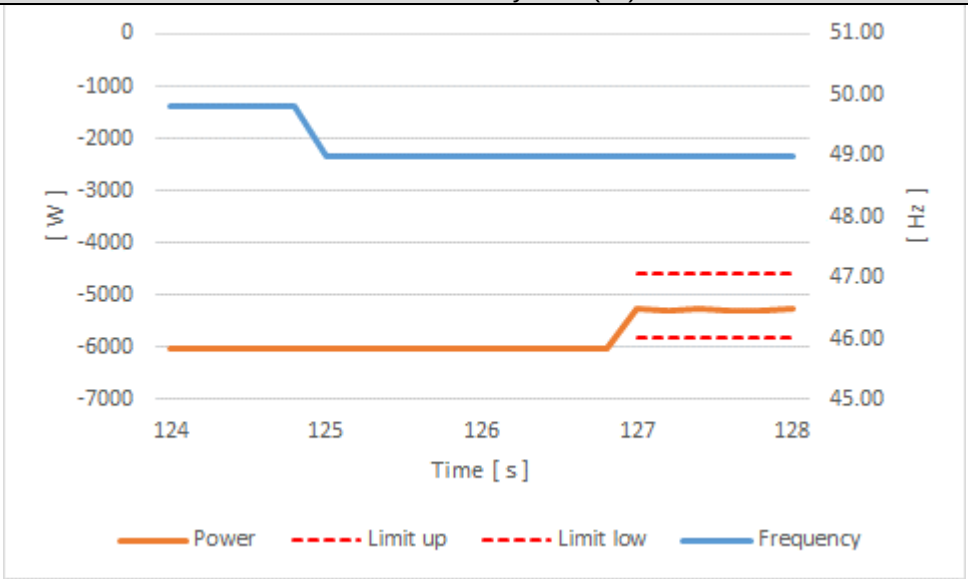
| 4.6.2 | Table: Power response to under frequency | | | | | | P |
|---|---|---|---|---|---|---|---|
| Test 3 | -50% Pn, f1 =46.0Hz; droop=5%; no delay | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -3024.48 | -- | -- | -- | -- | -- |
| 49.0Hz ± 0.01Hz | 49.00 | -3023.55 | -3000.00 | -23.55 | ± 600 | -- | -- |
| 48.0Hz ± 0.01Hz | 48.00 | -3025.10 | -3000.00 | -25.10 | ± 600 | -- | -- |
| 47.0Hz ± 0.01Hz | 47.00 | -3024.00 | -3000.00 | -24.00 | ± 600 | -- | -- |
| 46.0Hz ± 0.01Hz | 46.00 | -3025.22 | -3000.00 | -25.22 | ± 600 | -- | -- |
| 47.0Hz ± 0.01Hz | 47.00 | -3024.73 | -3000.00 | -24.73 | ± 600 | -- | -- |
| 48.0Hz ± 0.01Hz | 48.00 | -3025.13 | -3000.00 | -25.13 | ± 600 | -- | -- |
| 49.0Hz ± 0.01Hz | 49.00 | -3024.77 | -3000.00 | -24.77 | ± 600 | -- | -- |
| 50.0Hz ± 0.01Hz | 50.00 | -3024.75 | -- | -- | -- | -- | -- |
| Test 4 | -50% Pn, f1 =49.8Hz; droop=5%; | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -3024.03 | -- | -- | -- | -- | -- |
| 49.8Hz ± 0.01Hz | 49.80 | -3001.40 | -3000.00 | -1.40 | ± 600 | -- | -- |
| 49.0Hz ± 0.01Hz | 49.00 | -1106.53 | -1080.00 | -26.53 | ± 600 | 0.4s | 0.4s |
| 48.0Hz ± 0.01Hz | 48.00 | 1378.35 | 1320.00 | 58.35 | ± 600 | 0.6s | 0.8s |
| 47.0Hz ± 0.01Hz | 47.00 | 3748.05 | 3720.00 | 28.05 | ± 600 | 0.4s | 0.6s |
| 46.0Hz ± 0.01Hz | 46.00 | 6012.72 | 6000.00 | 12.72 | ± 600 | 0.4s | 0.4s |
| 47.0Hz ± 0.01Hz | 47.00 | 3695.43 | 3720.00 | -24.57 | ± 600 | 0.4s | 0.6s |
| 48.0Hz ± 0.01Hz | 48.00 | 1324.83 | 1320.00 | 4.83 | ± 600 | 0.2s | 0.4s |
| 49.0Hz ± 0.01Hz | 49.00 | -1152.53 | -1080.00 | -72.53 | ± 600 | 0.6s | 0.8s |
| 49.8Hz ± 0.01Hz | 49.80 | -3023.17 | -3000.00 | -23.17 | ± 600 | -- | -- |
| 50.0Hz ± 0.01Hz | 50.00 | -3044.63 | -- | -- | -- | -- | -- |

| 4.6.2 | Table: Power response to under frequency | P |
|---|---|---|

Test 1_Graph

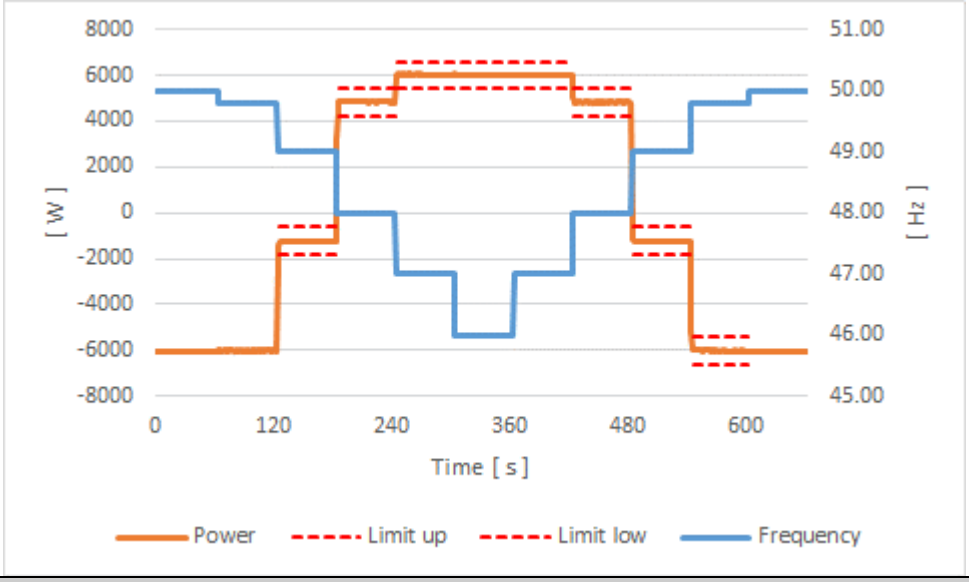



Intentional delay time (2s)

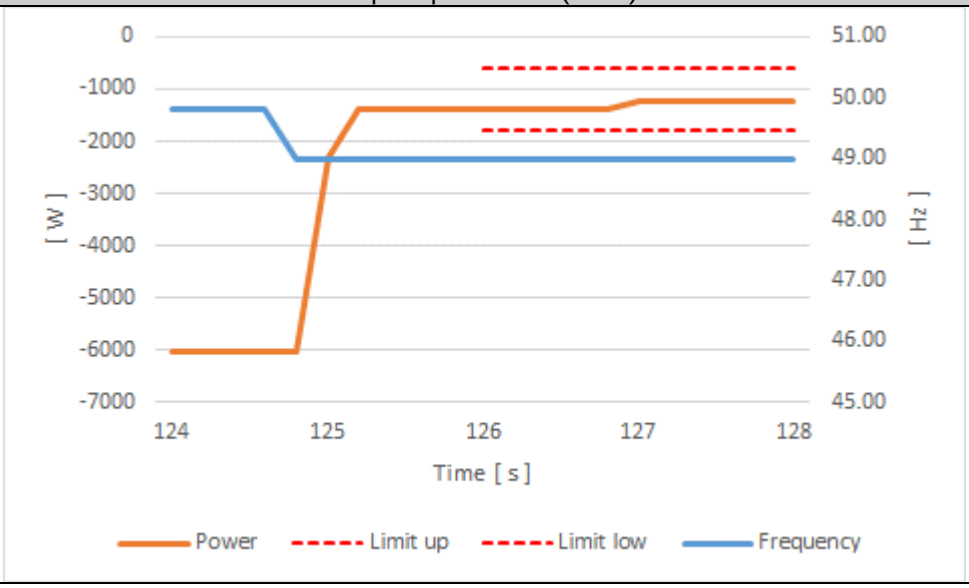


| 4.6.2 | Table: Power response to under frequency | P |
|---|---|---|

Test 2_Graph

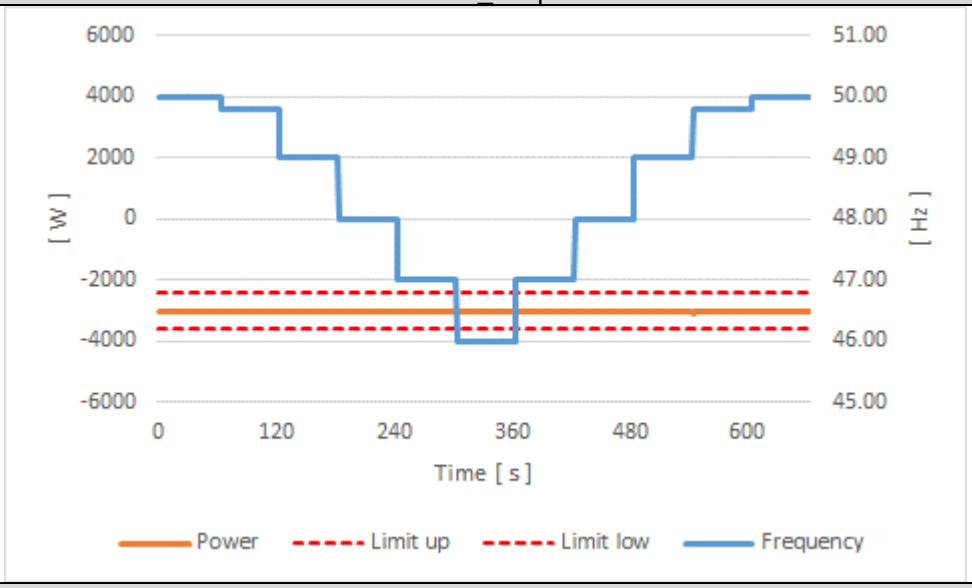



Step response time(T≤2s)

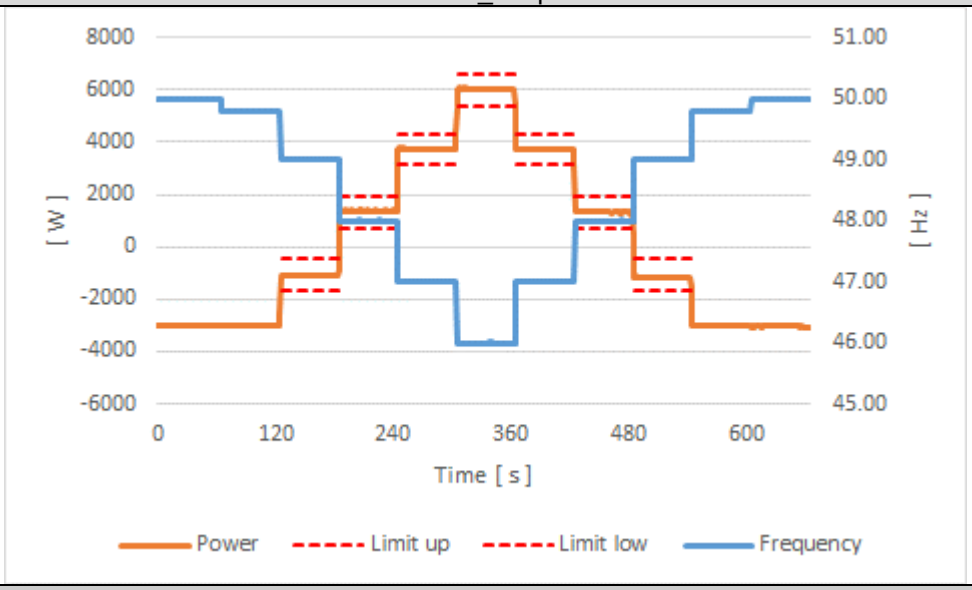


| 4.6.2 | Table: Power response to under frequency | P |
|---|---|---|

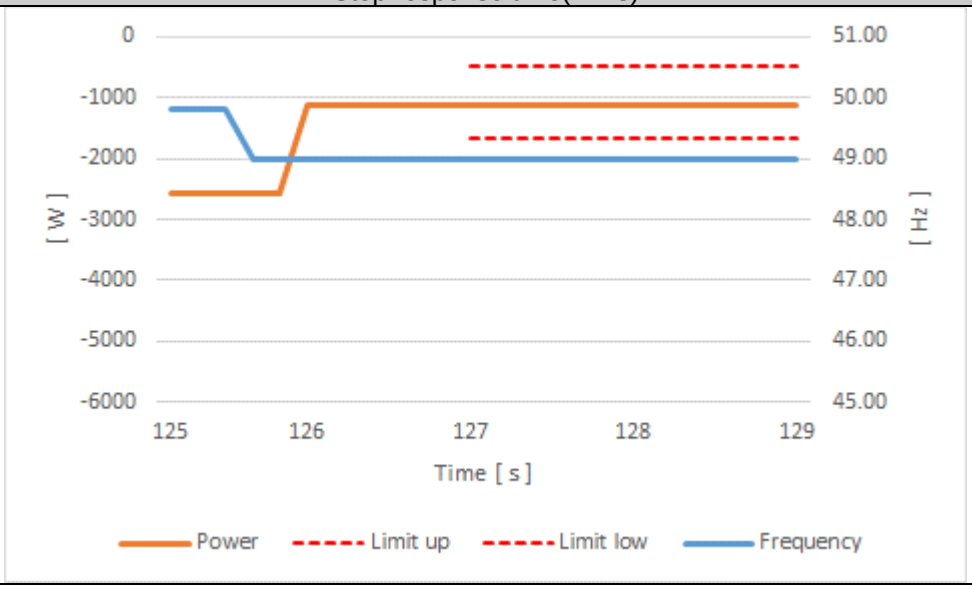
Test 3_Graph




Test 4_Graph




Step response time(T≤2s)

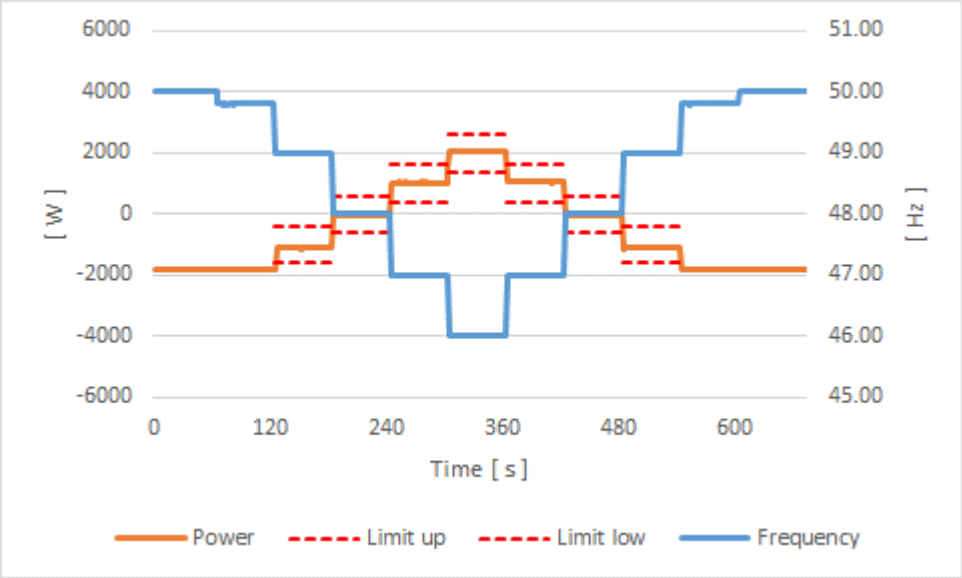


| 4.6.2 | Table: Power response to under frequency | | | | | | P |
|---|---|---|---|---|---|---|---|
| Test 5 | -30% Pn, f1 =49.8Hz; droop=12%; with delay of 2 s | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -1824.45 | -- | -- | -- | -- | -- |
| 49.8Hz ± 0.01Hz | 49.80 | -1812.65 | -1800.00 | -12.65 | ± 600 | -- | -- |
| 49.0Hz ± 0.01z | 49.00 | -1136.10 | -1000.00 | -136.10 | ± 600 | 1.2s | 1.4s |
| 48.0Hz ± 0.01z | 48.00 | -13.03 | 0.00 | -13.03 | ± 600 | 0.8s | 1.0s |
| 47.0Hz ± 0.01z | 47.00 | 1040.22 | 1000.00 | 40.22 | ± 600 | 0.6s | 0.8s |
| 46.0Hz ± 0.01z | 46.00 | 2044.53 | 2000.00 | 44.53 | ± 600 | 0.6s | 0.8s |
| 47.0Hz ± 0.01z | 47.00 | 1051.53 | 1000.00 | 51.53 | ± 600 | 0.2s | 0.4s |
| 48.0Hz ± 0.01z | 48.00 | -13.08 | 0.00 | -13.08 | ± 600 | 0.4s | 0.6s |
| 49.0Hz ± 0.01z | 49.00 | -1106.77 | -1000.00 | -106.77 | ± 600 | 0.6s | 0.8s |
| 49.8Hz ± 0.01Hz | 49.80 | -1794.43 | -1800.00 | 5.57 | ± 600 | 0.4s | 0.6s |
| 50.0Hz ± 0.01Hz | 50.00 | -1794.69 | -- | -- | -- | -- | -- |
| Test 6 | -30% Pn, f1 =49.8Hz; droop=2%; no delay | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -1807.73 | -- | -- | -- | -- | -- |
| 49.8Hz ± 0.01Hz | 49.80 | -1824.12 | -1800.00 | -24.12 | ± 600 | -- | -- |
| 49.0Hz ± 0.01Hz | 49.00 | 3023.59 | 3000.00 | 23.59 | ± 600 | 0.4s | 1.4s |
| 48.0Hz ± 0.01Hz | 48.00 | 6022.81 | 6000.00 | 22.81 | ± 600 | 0.6s | 0.8s |
| 47.0Hz ± 0.01Hz | 47.00 | 5998.05 | 6000.00 | -1.95 | ± 600 | -- | -- |
| 46.0Hz ± 0.01Hz | 46.00 | 6027.46 | 6000.00 | 27.46 | ± 600 | -- | -- |
| 47.0Hz ± 0.01Hz | 47.00 | 6025.56 | 6000.00 | 25.56 | ± 600 | -- | -- |
| 48.0Hz ± 0.01Hz | 48.00 | 6025.10 | 6000.00 | 25.10 | ± 600 | -- | -- |
| 49.0Hz ± 0.01Hz | 49.00 | 3065.42 | 3000.00 | 65.42 | ± 600 | 0.4s | 0.6s |
| 49.8Hz ± 0.01Hz | 49.80 | -1858.20 | -1800.00 | -58.20 | ± 600 | 0.2s | 0.6s |
| 50.0Hz ± 0.01Hz | 50.00 | -1840.16 | -- | -- | -- | -- | -- |

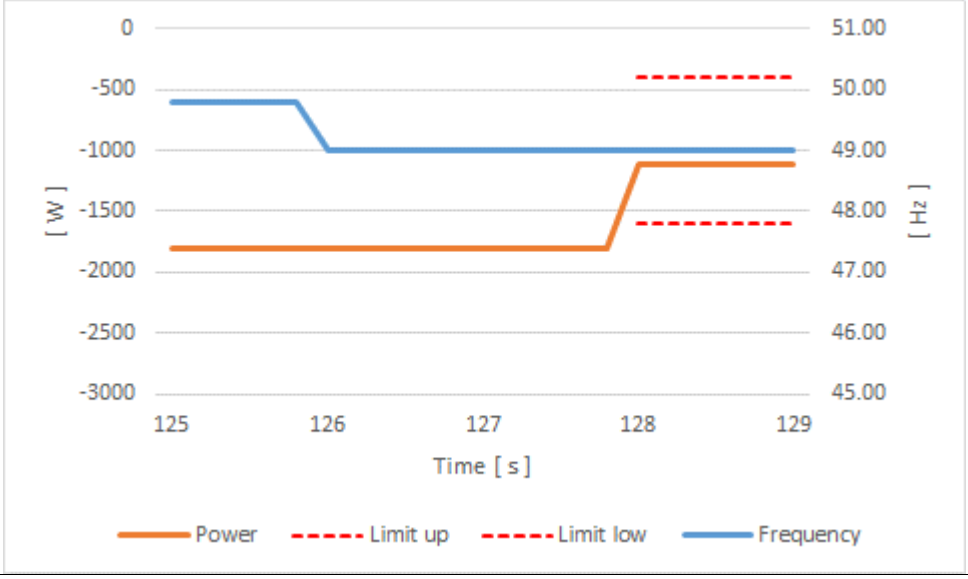
| 4.6.2 | Table: Power response to under frequency | | | | | | P |
|---|---|---|---|---|---|---|---|
| Test 7 | -15% Pn, f1 =46.0Hz; droop=5%; no delay | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -917.54 | -- | -- | -- | -- | -- |
| 49.0Hz ± 0.01Hz | 49.00 | -921.02 | -900.00 | -21.02 | ± 600 | -- | -- |
| 48.0Hz ± 0.01Hz | 48.00 | -919.33 | -900.00 | -19.33 | ± 600 | -- | -- |
| 47.0Hz ± 0.01Hz | 47.00 | -919.76 | -900.00 | -19.76 | ± 600 | -- | -- |
| 46.0Hz ± 0.01Hz | 46.00 | -920.77 | -900.00 | -20.77 | ± 600 | -- | -- |
| 47.0Hz ± 0.01Hz | 47.00 | -920.67 | -900.00 | -20.67 | ± 600 | -- | -- |
| 48.0Hz ± 0.01Hz | 48.00 | -920.12 | -900.00 | -20.12 | ± 600 | -- | -- |
| 49.0Hz ± 0.01Hz | 49.00 | -921.38 | -900.00 | -21.38 | ± 600 | -- | -- |
| 50.0Hz ± 0.01Hz | 50.00 | -921.93 | -- | -- | -- | -- | -- |
| Test 8 | -15% Pn, f1 =49.8Hz; droop=5%; | | | | | | |
| | f (Hz) | Measured output Power (W) | Calculated from standard characteristic curve P (W) | Tolerance between measured P and calculated P (W) | Tolerance Limit (W) | For a reduction of active power of 50% Pmax T≤2s | For a reduction of active power T≤20s |
| 50Hz ± 0.01Hz | 50.00 | -906.65 | -- | -- | -- | -- | -- |
| 49.8Hz ± 0.01Hz | 49.80 | -893.42 | -900.00 | 6.58 | ± 600 | -- | -- |
| 49.0Hz ± 0.01Hz | 49.00 | 1059.75 | 1020.00 | 39.75 | ± 600 | 0.4s | 0.6s |
| 48.0Hz ± 0.01Hz | 48.00 | 3453.97 | 3420.00 | 33.97 | ± 600 | 0.4s | 1.2s |
| 47.0Hz ± 0.01Hz | 47.00 | 5853.92 | 5820.00 | 33.92 | ± 600 | 0.4s | 1.4s |
| 46.0Hz ± 0.01Hz | 46.00 | 6042.03 | 6000.00 | 42.03 | ± 600 | 0.8s | 1.0s |
| 47.0Hz ± 0.01Hz | 47.00 | 5828.53 | 5820.00 | 8.53 | ± 600 | 0.6s | 0.8s |
| 48.0Hz ± 0.01Hz | 48.00 | 3406.80 | 3420.00 | -13.20 | ± 600 | 0.4s | 0.6s |
| 49.0Hz ± 0.01Hz | 49.00 | 1008.92 | 1020.00 | -11.08 | ± 600 | 0.4s | 0.6s |
| 49.8Hz ± 0.01Hz | 49.80 | -919.90 | -900.00 | -19.90 | ± 600 | 0.4s | 0.6s |
| 50.0Hz ± 0.01Hz | 50.00 | -902.60 | -- | -- | -- | -- | -- |

| 4.6.2 | Table: Power response to under frequency | P |
|---|---|---|

**Test 1_Graph**

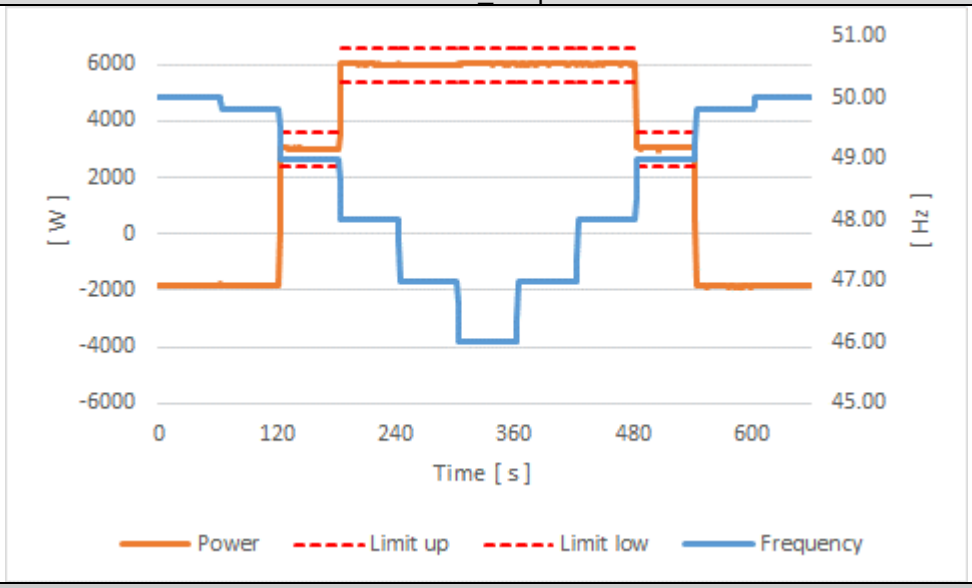



Intentional delay time (2s)

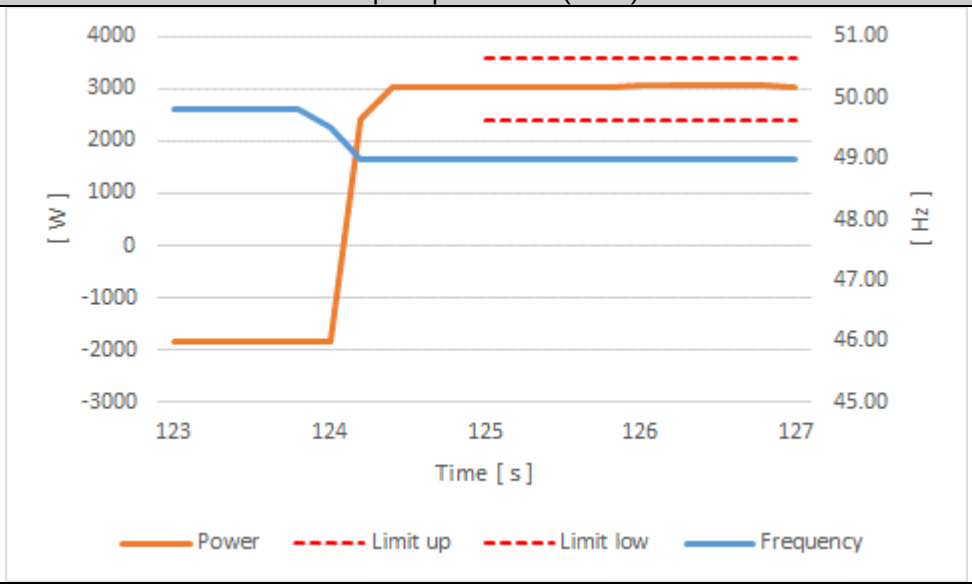


| 4.6.2 | Table: Power response to under frequency | P |
|---|---|---|

Test 2_Graph

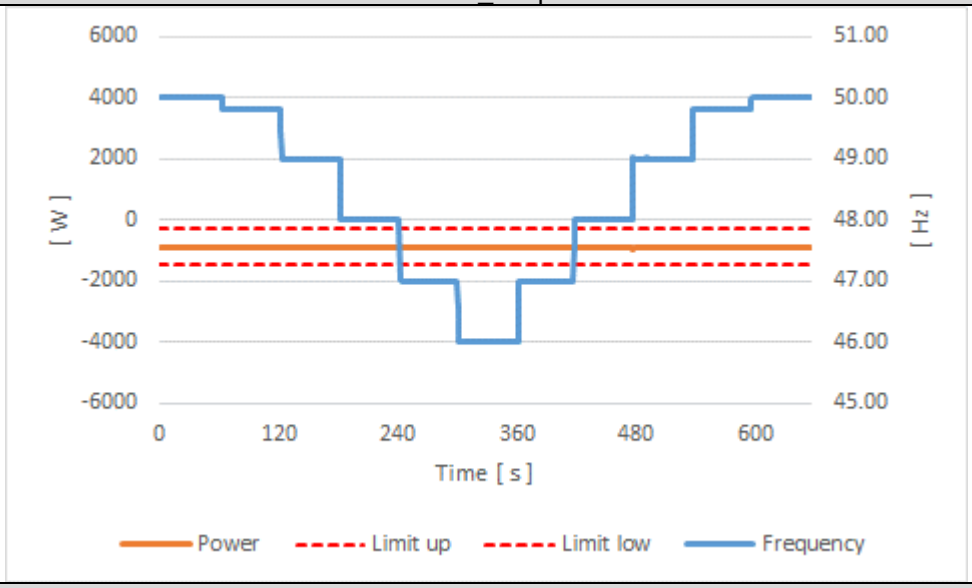



Step response time(T≤2s)

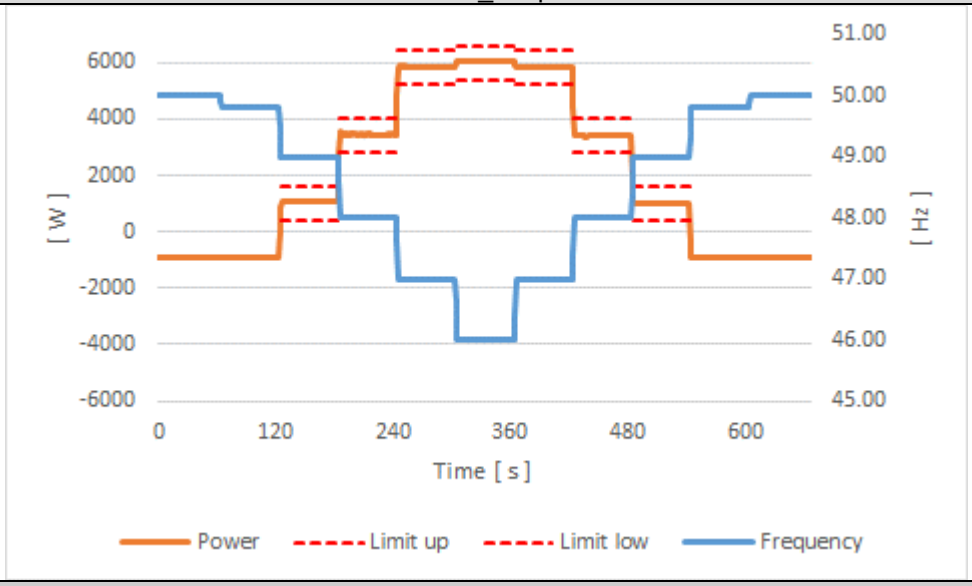


| 4.6.2 | Table: Power response to under frequency | P |
|---|---|---|

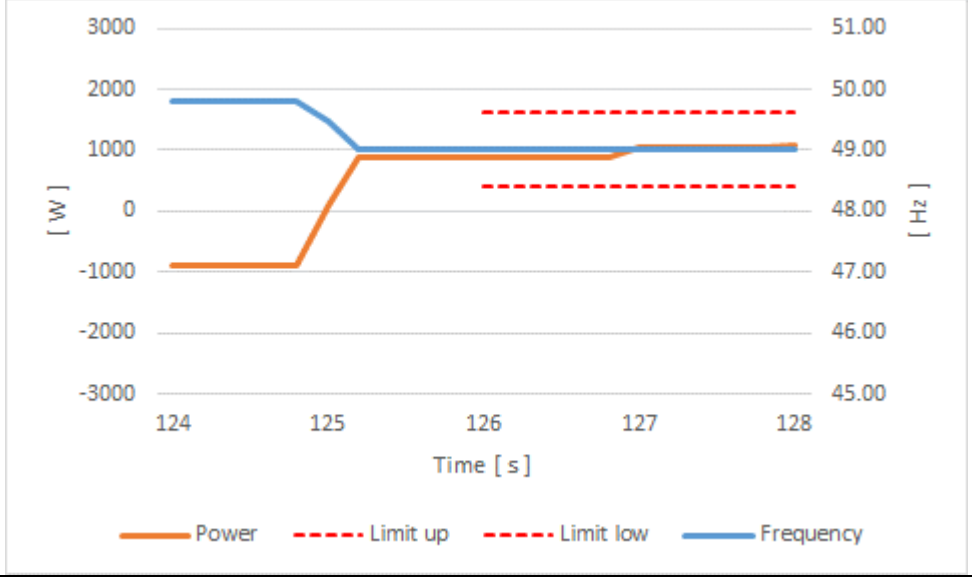
Test 3_Graph



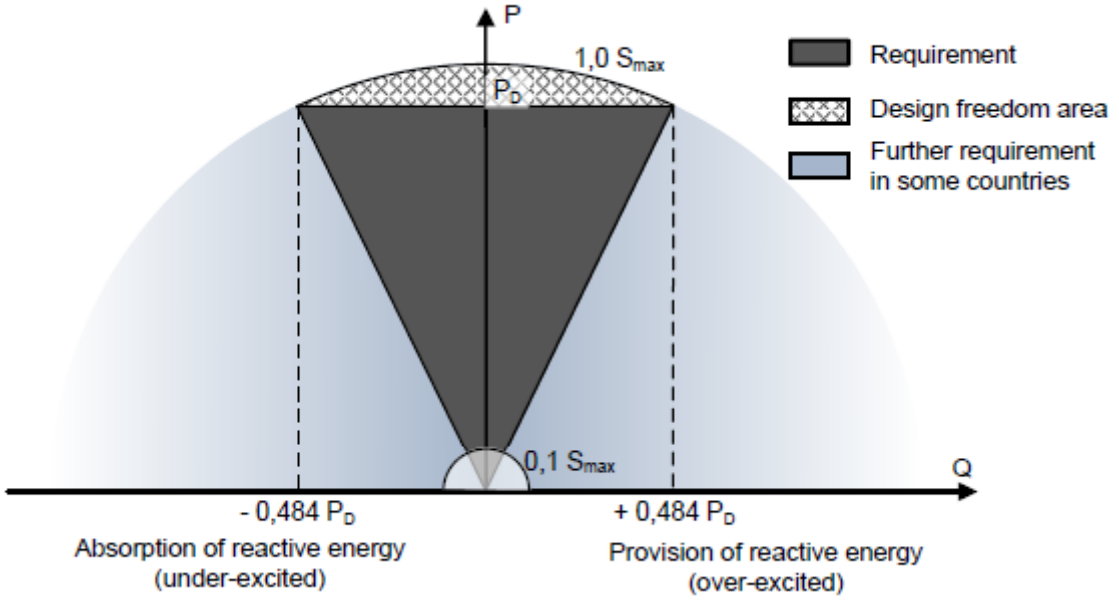

Test 4_Graph




Step response time(T≤2s)



| 4.7.2.2 Q Capabilities (Power Factor) | P |
|---|---|




**Test result:**

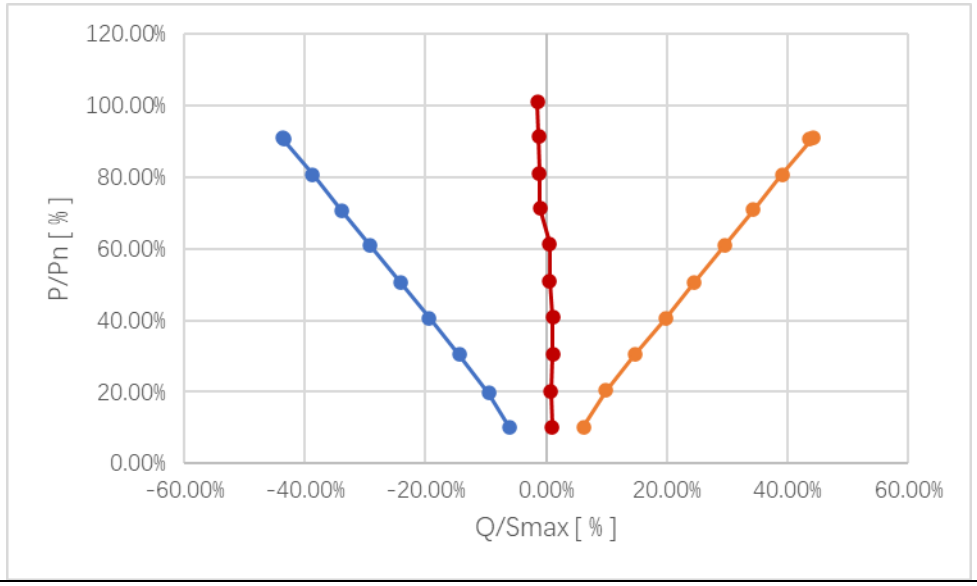
**Leading PF=0.9:**

| $P/P_n$ [%] setpoint | P[W] | Q[Var] | Cos φ | Cos φ Set point | Δcos φ | Q[Var] setpoint | $\Delta Q/S_{max}$ [%] | LIMITE [%] |
|---|---|---|---|---|---|---|---|---|
| 10 | 613.57 | 368.70 | 0.8566 | 0.9 | -0.0434 | 290.59 | 0.13 | ± 2 |
| 20 | 1227.15 | 593.22 | 0.9000 | 0.9 | 0.0000 | 581.19 | 0.04 | ± 2 |
| 30 | 1823.39 | 884.44 | 0.8995 | 0.9 | -0.0005 | 871.78 | 0.06 | ± 2 |
| 40 | 2432.61 | 1186.32 | 0.8986 | 0.9 | -0.0014 | 1162.37 | 0.16 | ± 2 |
| 50 | 3044.39 | 1474.92 | 0.8998 | 0.9 | -0.0002 | 1452.97 | 0.18 | ± 2 |
| 60 | 3656.44 | 1774.31 | 0.8996 | 0.9 | -0.0004 | 1743.56 | 0.31 | ± 2 |
| 70 | 4252.45 | 2063.13 | 0.8996 | 0.9 | -0.0004 | 2034.15 | 0.34 | ± 2 |
| 80 | 4838.40 | 2350.41 | 0.8994 | 0.9 | -0.0006 | 2324.75 | 0.34 | ± 2 |
| 90 | 5456.82 | 2653.45 | 0.8992 | 0.9 | -0.0008 | 2615.34 | 0.57 | ± 2 |
| *100 | 5444.87 | 2613.24 | 0.9015 | 0.9 | 0.0015 | -- | -- | -- |

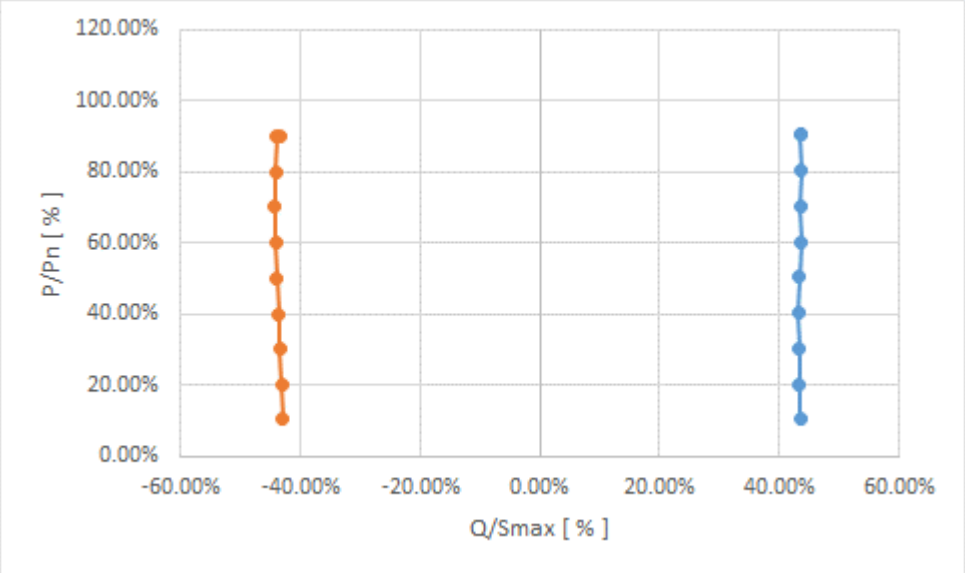
*Remark: Due to the max current limit, the active power can't get to 100%

| 4.7.2.2 Q Capabilities (Power Factor) | | | | | | | | P |
|---|---|---|---|---|---|---|---|---|
| **Lagging PF=-0.9:** | | | | | | | | |
| P/Pn [%] setpoint | P[W] | Q[Var] | Cosφ | Cosφ Set point | Δcosφ | Q[Var] setpoint | ΔQ/$S_{max}$ [%] | LIMITE [%] |
| 10 | 615.85 | -370.49 | 0.8563 | 0.9 | -0.0437 | -290.59 | -0.13 | ± 2 |
| 20 | 1181.75 | -574.85 | 0.8989 | 0.9 | -0.0011 | -581.19 | 0.02 | ± 2 |
| 30 | 1824.82 | -867.72 | 0.9029 | 0.9 | 0.0029 | -871.78 | 0.02 | ± 2 |
| 40 | 2433.74 | -1166.18 | 0.9017 | 0.9 | 0.0017 | -1162.37 | -0.03 | ± 2 |
| 50 | 3041.34 | -1454.33 | 0.9020 | 0.9 | 0.0020 | -1452.97 | -0.01 | ± 2 |
| 60 | 3654.29 | -1751.56 | 0.9017 | 0.9 | 0.0017 | -1743.56 | -0.08 | ± 2 |
| 70 | 4246.50 | -2039.60 | 0.9013 | 0.9 | 0.0013 | -2034.15 | -0.06 | ± 2 |
| 80 | 4838.33 | -2325.79 | 0.9012 | 0.9 | 0.0012 | -2324.75 | -0.01 | ± 2 |
| 90 | 5452.88 | -2624.89 | 0.9010 | 0.9 | 0.0010 | -2615.34 | -0.14 | ± 2 |
| 100 | 5433.85 | -2611.12 | 0.9013 | 0.9 | 0.0013 | -- | -- | -- |
| **Q=0:** | | | | | | | | |
| $P/P_n$[%] setpoint | P[W] | Q[Var] | Cosφ | Cosφ Set point | Δcosφ | Q[Var] setpoint | ΔQ/$S_{max}$ [%] | LIMITE [%] |
| 10 | 616.55 | 67.29 | 0.9939 | 1.0 | -0.0061 | 0.00 | 0.11 | ± 2 |
| 20 | 1208.93 | 55.07 | 0.9989 | 1.0 | -0.0011 | 0.00 | 0.18 | ± 2 |
| 30 | 1832.52 | 57.13 | 0.9995 | 1.0 | -0.0005 | 0.00 | 0.29 | ± 2 |
| 40 | 2446.71 | 66.94 | 0.9996 | 1.0 | -0.0004 | 0.00 | 0.45 | ± 2 |
| 50 | 3060.10 | 29.57 | 0.9997 | 1.0 | -0.0003 | 0.00 | 0.25 | ± 2 |
| 60 | 3673.63 | 31.05 | 0.9998 | 1.0 | -0.0002 | 0.00 | 0.31 | ± 2 |
| 70 | 4273.98 | -59.16 | 0.9999 | 1.0 | -0.0001 | 0.00 | -0.69 | ± 2 |
| 80 | 4864.60 | -67.90 | 0.9999 | 1.0 | -0.0001 | 0.00 | -0.91 | ± 2 |
| 90 | 5483.36 | -76.78 | 0.9999 | 1.0 | -0.0001 | 0.00 | -1.15 | ± 2 |
| 100 | 6059.64 | -84.92 | 0.9999 | 1.0 | -0.0001 | 0.00 | -1.42 | ± 2 |

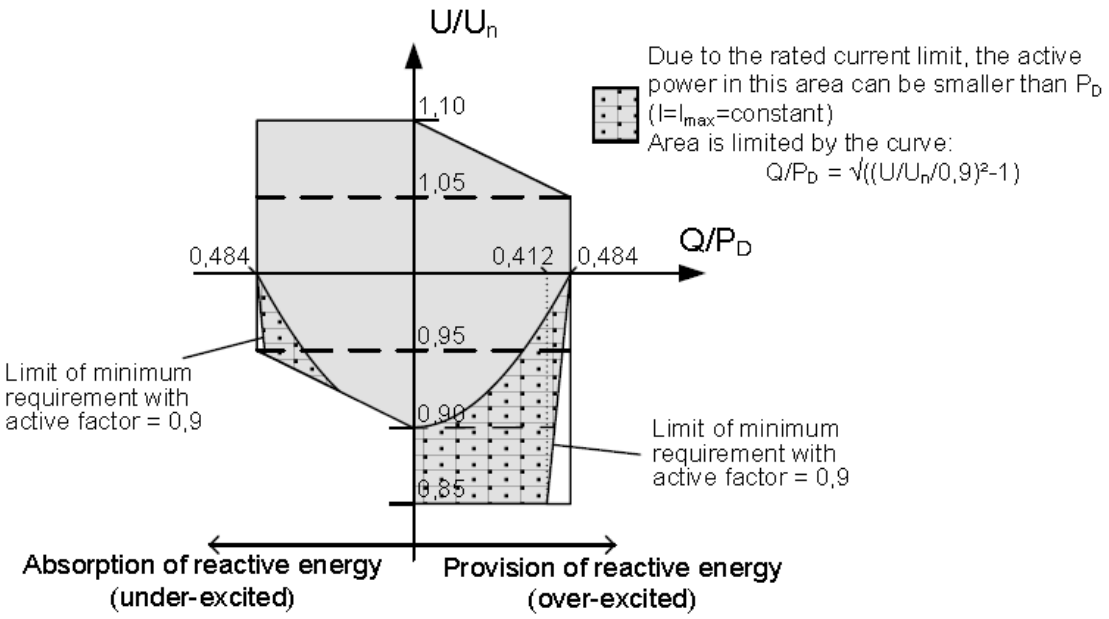
Graph



| 4.7.2.2 Q Capabilities (Power Factor) | | | | | | P |
|---|---|---|---|---|---|---|
| **Q=43.58%Pn** | | | | | | |
| P/Pn [%] setpoint | P[W] | Q[Var] | Cosφ | Q[Var] setpoint | $\Delta Q/S_{max}$ [%] | LIMITE [%] |
| 10 | 621.05 | 2610.17 | 0.2314 | 2614.80 | -0.08 | ± 2 |
| 20 | 1219.64 | 2604.23 | 0.4240 | 2614.80 | -0.18 | ± 2 |
| 30 | 1816.10 | 2602.52 | 0.5721 | 2614.80 | -0.20 | ± 2 |
| 40 | 2413.55 | 2595.52 | 0.6808 | 2614.80 | -0.32 | ± 2 |
| 50 | 3016.30 | 2601.26 | 0.7572 | 2614.80 | -0.23 | ± 2 |
| 60 | 3612.44 | 2622.89 | 0.8091 | 2614.80 | 0.13 | ± 2 |
| 70 | 4210.93 | 2609.79 | 0.8499 | 2614.80 | -0.08 | ± 2 |
| 80 | 4817.69 | 2623.26 | 0.8782 | 2614.80 | 0.14 | ± 2 |
| 90 | 5418.86 | 2609.98 | 0.9009 | 2614.80 | -0.08 | ± 2 |
| 100 | 5419.06 | 2609.95 | 0.9009 | 2614.80 | -0.08 | ± 2 |
| **Q=-43.58%Pn** | | | | | | |
| P/Pn [%] setpoint | P[W] | Q[Var] | Cosφ | Q[Var] setpoint | $\Delta Q/S_{max}$ [%] | LIMITE [%] |
| 10 | 626.69 | -2571.65 | 0.2366 | -2614.80 | 0.72 | ± 2 |
| 20 | 1209.51 | -2590.00 | 0.4225 | -2614.80 | 0.41 | ± 2 |
| 30 | 1809.92 | -2600.82 | 0.5703 | -2614.80 | 0.23 | ± 2 |
| 40 | 2405.08 | -2617.86 | 0.6766 | -2614.80 | -0.05 | ± 2 |
| 50 | 3010.28 | -2635.63 | 0.7528 | -2614.80 | -0.35 | ± 2 |
| 60 | 3614.62 | -2650.00 | 0.8068 | -2614.80 | -0.59 | ± 2 |
| 70 | 4210.00 | -2660.00 | 0.8453 | -2614.80 | -0.75 | ± 2 |
| 80 | 4800.04 | -2643.07 | 0.8760 | -2614.80 | -0.47 | ± 2 |
| 90 | 5400.53 | -2640.00 | 0.8987 | -2614.80 | -0.42 | ± 2 |
| 100* | 5401.40 | -2610.00 | 0.9007 | -2614.80 | 0.08 | ± 2 |
| *Remark: Due to the max current limit, the active power can't get to 100% | | | | | | |
| Graph | | | | | | |



| Table 4.7.2.2 Q(U) Capabilities | P |
|---|---|




**Test result:**

**Over-excited:**

| AC output | | | | Reactive power measured | | |
|---|---|---|---|---|---|---|
| Voltage setting [V/Vn] | Measured | | | Reactive power [Var] | Value [Q/PD] | Limits |
| | Voltage [V] | [V/Vn] | Active power [W] | | | |
| 1.10 | 253.33 | 1.10 | 6026.14 | -83.97 | -0.0139 | ±0.02 |
| 1.08 | 248.96 | 1.08 | 5908.24 | 1142.96 | 0.1935 | 0.194±0.02 |
| 1.05 | 241.93 | 1.05 | 5426.82 | 2608.76 | 0.4807 | 0.484±0.02 |
| 1.00 | 230.58 | 1.00 | 5426.33 | 2613.06 | 0.4816 | 0.484±0.02 |
| 0.95 | 218.96 | 0.95 | 5463.41 | 2631.23 | 0.4816 | -- |
| 0.92 | 211.74 | 0.92 | 5462.95 | 2624.34 | 0.4804 | -- |
| 0.90 | 207.44 | 0.90 | 5463.93 | 2637.18 | 0.4827 | -- |
| 0.85 | 195.77 | 0.85 | 5235.59 | 2527.39 | 0.4827 | -- |

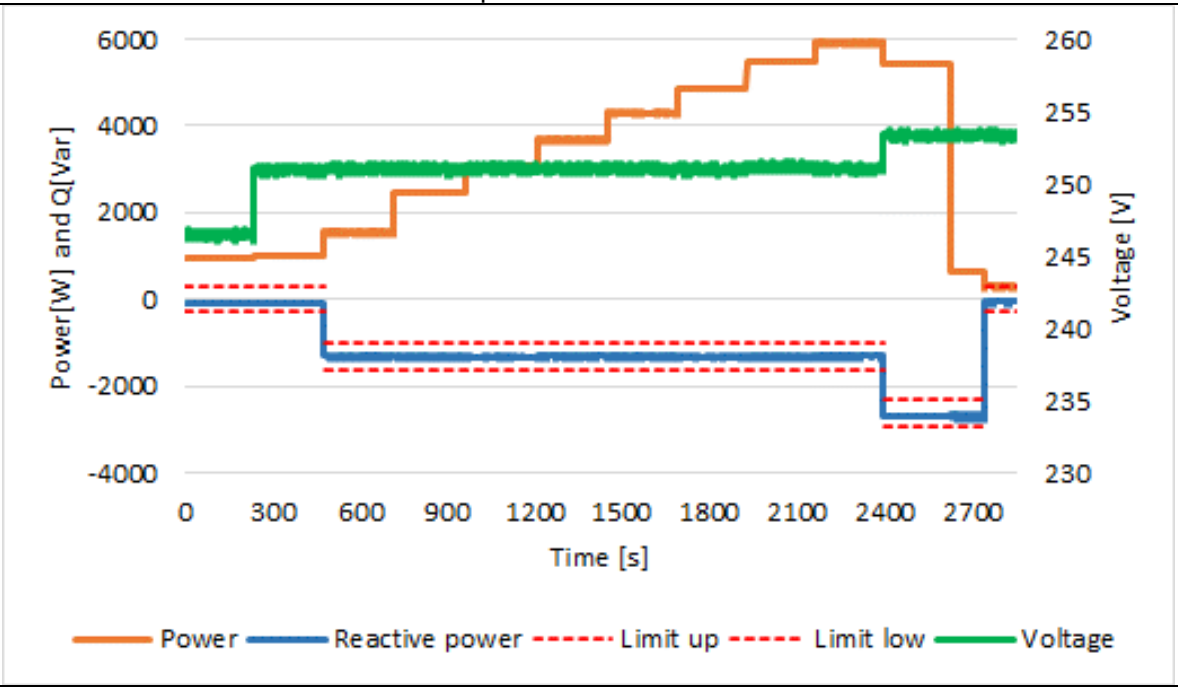
**Under-excited:**

| AC output | | | | Reactive power measured | | |
|---|---|---|---|---|---|---|
| Voltage setting [V/Vn] | Measured | | | Reactive power [Var] | Value [Q/PD] | Limits |
| | Voltage [V] | [V/Vn] | Active power [W] | | | |
| 1.10 | 253.42 | 1.10 | 5461.67 | -2641.43 | -0.4836 | -0.484±0.02 |
| 1.08 | 248.81 | 1.08 | 5441.30 | -2635.28 | -0.4843 | -0.484±0.02 |
| 1.05 | 241.91 | 1.05 | 5403.74 | -2608.82 | -0.4828 | -0.484±0.02 |
| 1.00 | 230.41 | 1.00 | 5426.47 | -2602.22 | -0.4795 | -0.484±0.02 |
| 0.95 | 218.82 | 0.95 | 5463.93 | -2586.13 | -0.4733 | -- |
| 0.92 | 210.93 | 0.92 | 5949.08 | -1143.49 | -0.1922 | -0.194±0.02 |
| 0.90 | 207.31 | 0.90 | 6026.62 | -83.93 | -0.0139 | ±0.02 |

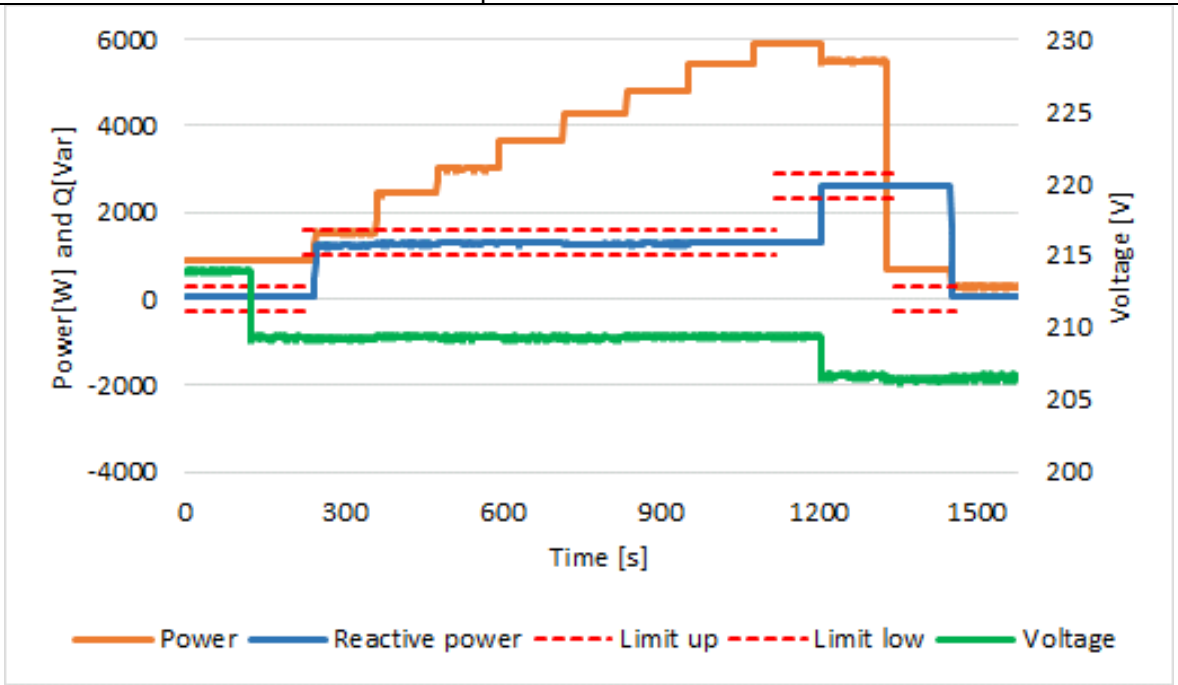
| 4.7.2.3.3 Voltage related control mode Q (U) | | | | | | P |
|---|---|---|---|---|---|---|
| **$P/P_n$ [%] Set-point** | **Vac [V] Set-point** | **$P/P_n$ [%] measured** | **Vac[V] Measured** | **Q [VAr] measured** | **Q [Var] expected** | **Δ Q [Var] (≤ ± 5 % Pn)** |
| < 20 % | 1.07 $V_n$ | 15.95 | 246.51 | -81.17 | ≈0 (< ± 5 % Pn) | -1.35 |
| < 20 % | 1.09 $V_n$ | 16.48 | 250.99 | -82.66 | ≈0 (< ± 5 % Pn) | -1.38 |
| <20 % → 30 % | 1.09 Vn | 25.85 | 251.06 | -1314.13 | -1307.40 (within 10sec) | -0.11 |
| 40 % | 1.09 Vn | 41.07 | 251.03 | -1322.51 | -1307.40 | -0.25 |
| 50 % | 1.09 Vn | 51.40 | 251.09 | -1326.20 | -1307.40 | -0.31 |
| 60 % | 1.09 Vn | 61.43 | 251.07 | -1312.31 | -1307.40 | -0.08 |
| 70 % | 1.09 Vn | 71.71 | 251.07 | -1310.22 | -1307.40 | -0.05 |
| 80 % | 1.09 Vn | 80.73 | 251.03 | -1327.99 | -1307.40 | -0.34 |
| 90 % | 1.09 Vn | 91.08 | 251.19 | -1318.83 | -1307.40 | -0.19 |
| 100 % | 1.09 Vn | 98.72 | 251.05 | -1309.37 | -1307.40 | -0.03 |
| 100 % | 1.10 Vn | 90.41 | 253.35 | -2693.60 | -2614.80 | -1.31 |
| 100 % →10 % | 1.10 Vn | 10.37 | 253.39 | -2690.70 | -2614.80 | -1.26 |
| 10 % → ≤ 5 % | 1.10 Vn | 5.05 | 253.35 | -63.15 | ≈0 (< ± 5 % Pn) | -1.05 |
| Remark: $V1_s$ =1.08 $V_n$. $V2_s$ = 1.1 $V_n$. V1i =0.92 $V_n$. $V2_i$ = 0.9 $V_n$. lock-in value P=0.2$P_n$. lock-out value P=0.05$P_n$. | | | | | | |
| **$P/P_n$ [%] Set-point** | **Vac [V] Set-point** | **$P/P_n$ [%] measured** | **Vac [V] Measured** | **Q [VAr] measured** | **Q [Var] expected** | **Δ Q [Var] (≤ ± 5 %$P_n$)** |
| < 20 % | 0.93 Vn | 15.07 | 213.92 | 60.01 | ≈0 (< ± 5 % Pn) | 1.00 |
| < 20 % | 0.91 Vn | 15.11 | 209.34 | 62.36 | ≈0 (< ± 5 % Pn) | 1.04 |
| <20 % → 30 % | 0.91 Vn | 25.65 | 209.24 | 1221.68 | 1307.40 (within 10sec) | -1.43 |
| 40 % | 0.91 Vn | 40.57 | 209.40 | 1274.79 | 1307.40 | -0.54 |
| 50 % | 0.91 Vn | 50.08 | 209.35 | 1288.11 | 1307.40 | -0.32 |
| 60 % | 0.91 Vn | 60.66 | 209.33 | 1292.69 | 1307.40 | -0.25 |
| 70 % | 0.91 Vn | 71.00 | 209.33 | 1269.33 | 1307.40 | -0.63 |
| 80 % | 0.91 Vn | 80.11 | 209.39 | 1277.21 | 1307.40 | -0.50 |
| 90 % | 0.91 Vn | 90.53 | 209.38 | 1295.42 | 1307.40 | -0.20 |
| 100 % | 0.91 Vn | 98.19 | 209.39 | 1303.32 | 1307.40 | -0.07 |
| 100 % | 0.90 Vn | 91.61 | 206.68 | 2604.76 | 2614.80 | -0.17 |
| 100 % →10 % | 0.90 Vn | 11.15 | 206.42 | 2611.23 | 2614.80 | -0.06 |
| 10 % → ≤ 5 % | 0.91 Vn | 4.79 | 206.56 | 81.75 | ≈0 (< ± 5 % Pn) | 1.36 |
| Remark: $V1_s$ =1.08 $V_n$. $V2_s$ = 1.1 $V_n$. V1i =0.92 $V_n$. $V2_i$ = 0.9 $V_n$. lock-in value P=0.2$P_n$. lock-out value P=0.05$P_n$ | | | | | | |

| 4.7.2.3.3 Voltage related control mode Q (U) | P |
|---|---|

Graph: Lock-in at 1.08Vn




Graph: Lock-in at 0.92Vn

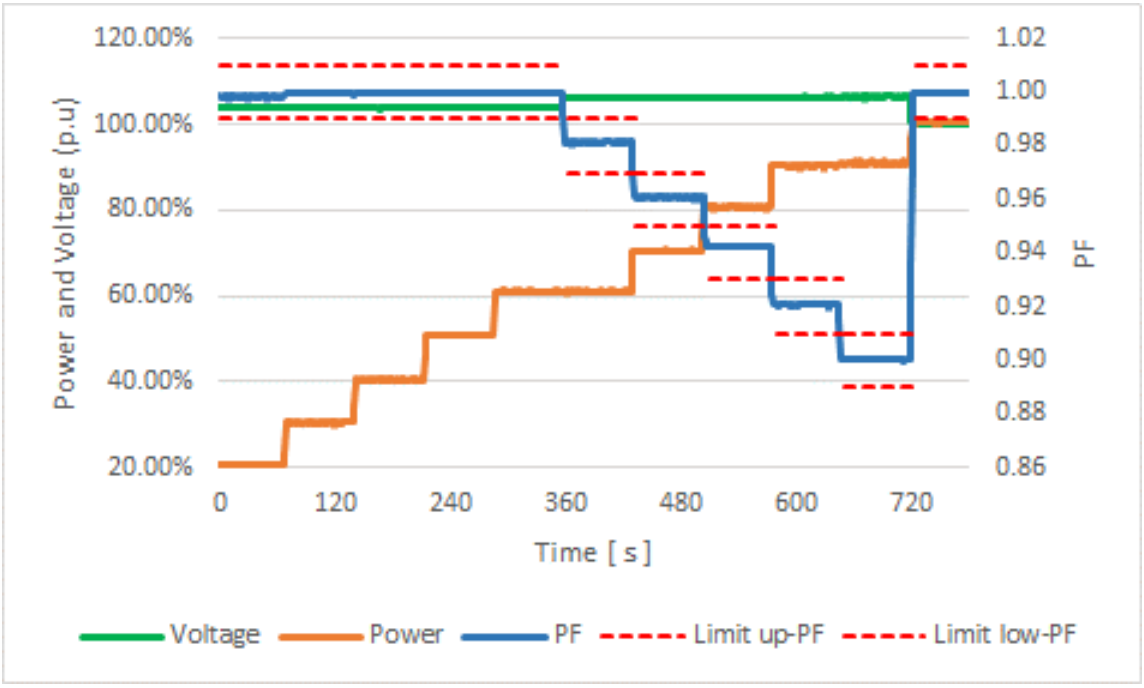


**4.7.2.3.4 Power related control modes**

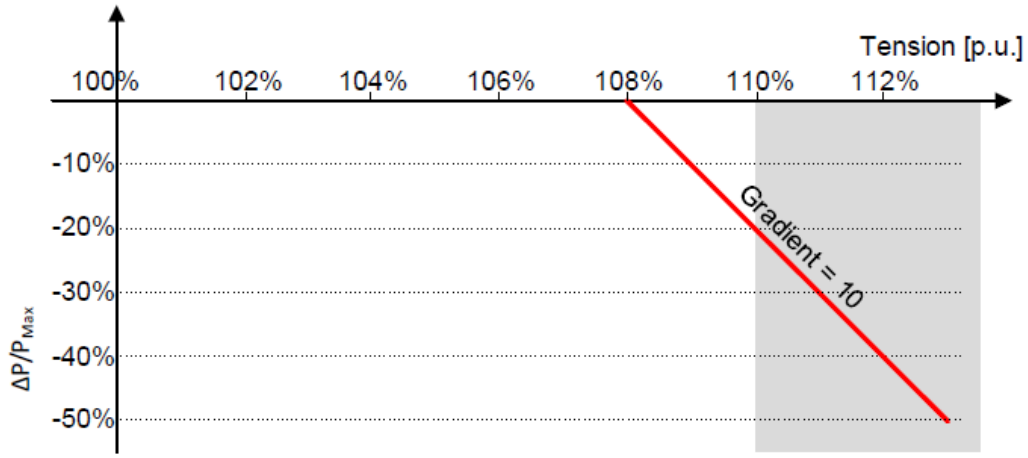
| P Desired (%Sn) | P measured (%Sn) | Q measured (Var) | Voltage Desired (%Un) | Voltage Measured (%Un) | Power Factor desired (cos φ) | Power Factor measured (cos φ) | △Q (%$S_{Max}$) | Limit (%$S_{Max}$) |
|---|---|---|---|---|---|---|---|---|
| 20% | 20.60 | -70.19 | <105% | 103.87 | 1.0000 | 0.9983 | -1.17 | ±2 |
| 30% | 30.49 | -63.42 | <105% | 103.83 | 1.0000 | 0.9994 | -1.06 | ±2 |
| 40% | 40.45 | -75.38 | <105% | 103.73 | 1.0000 | 0.9995 | -1.26 | ±2 |
| 50% | 50.64 | -85.43 | <105% | 103.78 | 1.0000 | 0.9996 | -1.42 | ±2 |
| 60% | 61.04 | -98.54 | <105% | 104.01 | 1.0000 | 0.9996 | -1.64 | ±2 |
| 60% | 61.07 | -715.69 | >105% | 106.01 | 0.9800 | 0.9814 | 0.26 | ±2 |
| 70% | 70.50 | -1216.04 | >105% | 106.13 | 0.9600 | 0.9610 | 0.15 | ±2 |
| 80% | 80.70 | -1711.15 | >105% | 106.21 | 0.9400 | 0.9428 | 0.52 | ±2 |
| 90% | 90.37 | -2295.71 | >105% | 106.34 | 0.9200 | 0.9208 | 0.08 | ±2 |
| 100% | 90.94 | -2639.49 | >105% | 106.42 | 0.9000 | 0.9001 | -0.42 | ±2 |
| 100% | 100.43 | -94.56 | <100% | 100.10 | 1.0000 | 0.9998 | -1.58 | ±2 |

Remark: Tested at lock-in voltage 1.05 Vn and lock-out voltage Vn.

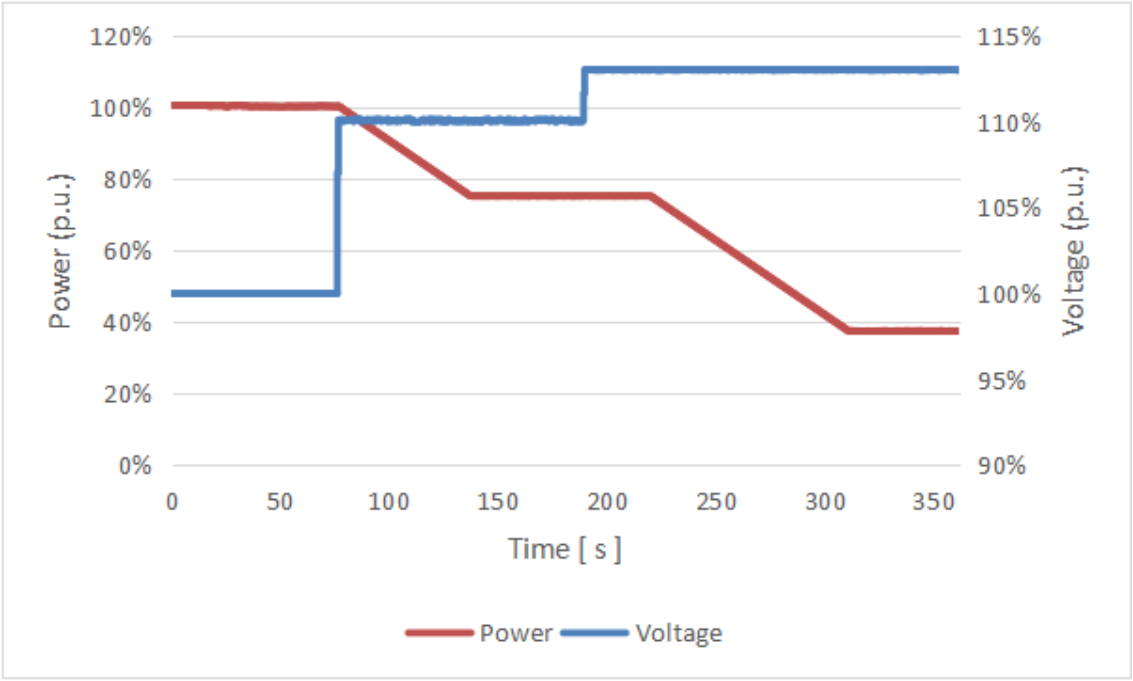
The Lock-in value is adjustable between Vn and 1.1Vn in 0.01V steps, the Lock-out value is adjustable between 0.9Vn and Vn in 0.01V steps



**4.7.3 Voltage related active power reduction P(U)**

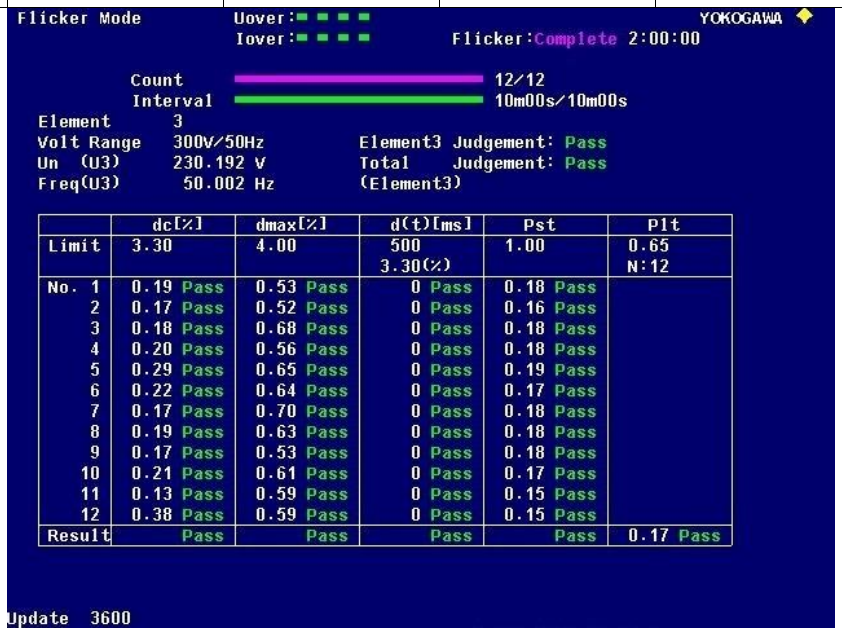



| Step # | Set voltage vaule V/Vn [%] | Measured voltage vaule V/Vn [%] | Measured power values [W] | Measured power bin [%] | Limit [%] |
|---|---|---|---|---|---|
| 1 | 100 | 100.01 | 6019.76 | 100.19 | -- |
| 2 | 110 | 110.01 | 4512.47 | 75.21 | -- |
| 3 | 113 | 113.01 | 2255.30 | 37.59 | <50 |



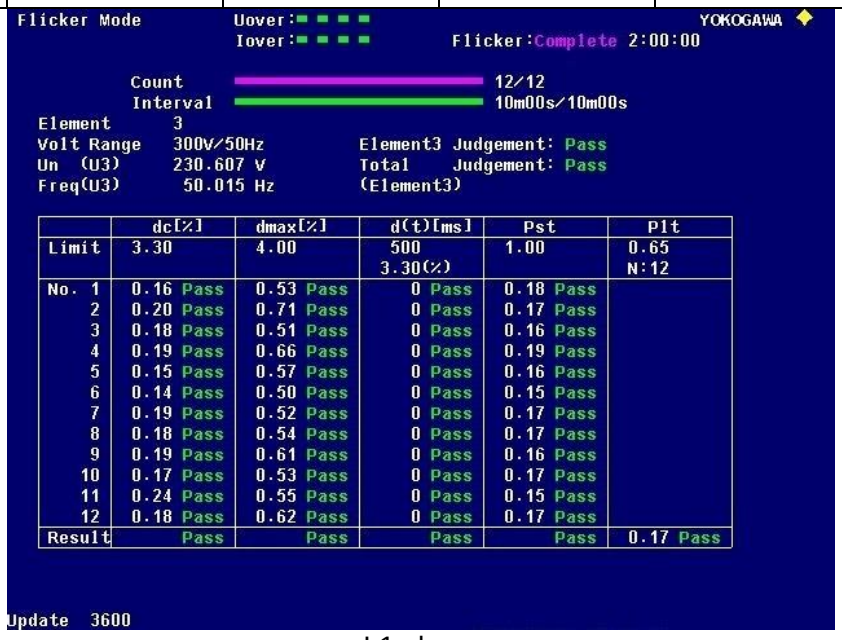
**4.8 EMC**

| **TABLE: Flick** | | | | | | **P** |
|---|---|---|---|---|---|---|
| **Model：AF6k-SL-0** | | | | | | |
| **Value** | | **Dc (%)** | **Dmax (%)** | **d(t) – 500ms** | **$P_{st}$** | **$P_{lt}$** |
| Limit | | 3.30 | 4.00 | 3.30% | 1.00 | 0.65 |
| Test value | L1 | 0.38 | 0.70 | 0 | 0.19 | 0.17 |
| | L2 | --- | --- | --- | --- | --- |
| | L3 | --- | --- | --- | --- | --- |




L1 phase

| TABLE: Flick | | | | | | P |
|---|---|---|---|---|---|---|
| **Model：AF1k-SL-0** | | | | | | |
| **Value** | | **Dc (%)** | **Dmax (%)** | **d(t) – 500ms** | **$P_{st}$** | **$P_{lt}$** |
| Limit | | 3.30 | 4.00 | 3.30% | 1.00 | 0.65 |
| Test value | L1 | 0.24 | 0.71 | 0 | 0.19 | 0.17 |
| | L2 | --- | --- | --- | --- | --- |
| | L3 | --- | --- | --- | --- | --- |



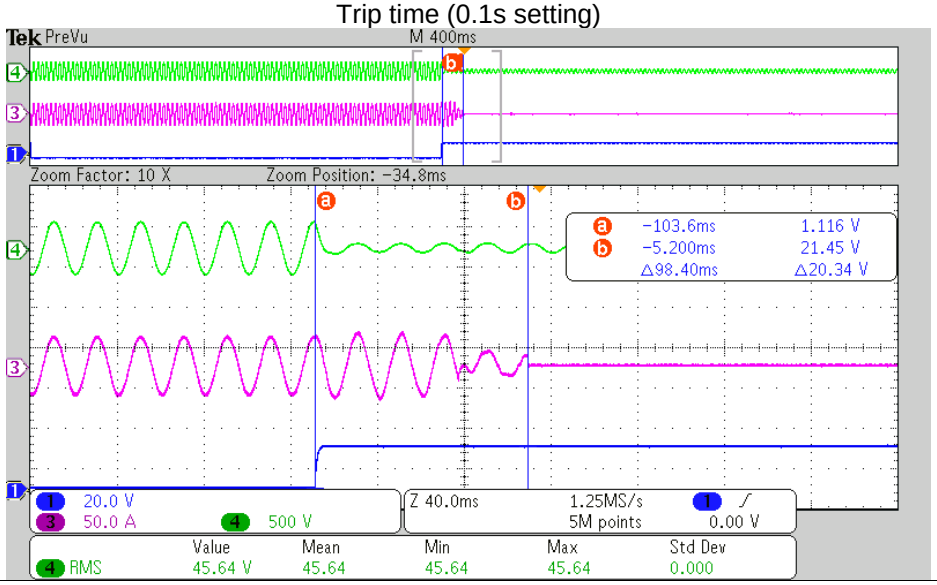

L1 phase

| 4.8 | Table: Harmonic current emissions | | | AF6k-SL-0 |
|---|---|---|---|---|
| **Hamonics order n** | **Measured Value (%)** | | | **Limit in BS EN 61000-3-12 (%)** |
| | **33%** | **66%** | **100%** | |
| **2** | 0.28 | 0.29 | 0.33 | 8% |
| **3** | 0.83 | 0.93 | 1.41 | 21.6% |
| **4** | 0.04 | 0.07 | 0.09 | 4% |
| **5** | 0.50 | 0.53 | 0.62 | 10.7% |
| **6** | 0.04 | 0.02 | 0.02 | 2.67% |
| **7** | 0.43 | 0.49 | 0.59 | 7.2% |
| **8** | 0.05 | 0.02 | 0.02 | 2% |
| **9** | 0.34 | 0.41 | 0.46 | 3.8% |
| **10** | 0.03 | 0.03 | 0.03 | 1.6% |
| **11** | 0.19 | 0.29 | 0.34 | 3.1% |
| **12** | 0.05 | 0.02 | 0.02 | 1.33% |
| **13** | 0.17 | 0.24 | 0.28 | 2% |
| **14** | 0.05 | 0.02 | 0.02 | N/A |
| **15** | 0.14 | 0.16 | 0.19 | N/A |
| **16** | 0.04 | 0.02 | 0.03 | N/A |
| **17** | 0.11 | 0.15 | 0.15 | N/A |
| **18** | 0.04 | 0.03 | 0.02 | N/A |
| **19** | 0.06 | 0.11 | 0.10 | N/A |
| **20** | 0.02 | 0.03 | 0.02 | N/A |
| **21** | 0.05 | 0.08 | 0.07 | N/A |
| **22** | 0.02 | 0.03 | 0.02 | N/A |
| **23** | 0.03 | 0.06 | 0.05 | N/A |
| **24** | 0.02 | 0.03 | 0.03 | N/A |
| **25** | 0.02 | 0.05 | 0.06 | N/A |
| **26** | 0.02 | 0.02 | 0.02 | N/A |
| **27** | 0.03 | 0.03 | 0.04 | N/A |
| **28** | 0.01 | 0.02 | 0.02 | N/A |
| **29** | 0.02 | 0.04 | 0.04 | N/A |
| **30** | 0.01 | 0.02 | 0.03 | N/A |
| **31** | 0.02 | 0.04 | 0.04 | N/A |
| **32** | 0.02 | 0.02 | 0.02 | N/A |
| **33** | 0.02 | 0.03 | 0.02 | N/A |
| **34** | 0.01 | 0.02 | 0.02 | N/A |
| **35** | 0.02 | 0.02 | 0.02 | N/A |
| **36** | 0.02 | 0.02 | 0.03 | N/A |
| **37** | 0.01 | 0.02 | 0.02 | N/A |
| **38** | 0.01 | 0.02 | 0.02 | N/A |
| **39** | 0.01 | 0.02 | 0.03 | N/A |
| **40** | 0.01 | 0.01 | 0.02 | N/A |
| **THD** | 1.17 | 1.38 | 1.84 | 13% |
| **PWHD** | 0.95 | 1.30 | 1.34 | 22% |

| 4.8 | Table: Harmonic current emissions | | | AF1k-SL-0 |
|---|---|---|---|---|
| Hamonics order n | Measured Value (A) | | | Limit in BS EN 61000-3-2 in Amps |
| | 33% | 66% | 100% | |
| 2 | 0.083 | 0.089 | 0.101 | 1.080 |
| 3 | 0.266 | 0.242 | 0.246 | 2.300 |
| 4 | 0.028 | 0.025 | 0.028 | 0.430 |
| 5 | 0.132 | 0.134 | 0.139 | 1.140 |
| 6 | 0.021 | 0.012 | 0.007 | 0.300 |
| 7 | 0.093 | 0.116 | 0.118 | 0.770 |
| 8 | 0.009 | 0.012 | 0.005 | 0.230 |
| 9 | 0.038 | 0.090 | 0.097 | 0.400 |
| 10 | 0.009 | 0.007 | 0.005 | 0.184 |
| 11 | 0.023 | 0.054 | 0.074 | 0.330 |
| 12 | 0.006 | 0.010 | 0.011 | 0.153 |
| 13 | 0.009 | 0.047 | 0.065 | 0.210 |
| 14 | 0.009 | 0.015 | 0.012 | 0.131 |
| 15 | 0.018 | 0.040 | 0.045 | 0.150 |
| 16 | 0.007 | 0.011 | 0.009 | 0.115 |
| 17 | 0.022 | 0.030 | 0.034 | 0.132 |
| 18 | 0.009 | 0.012 | 0.008 | 0.102 |
| 19 | 0.019 | 0.016 | 0.021 | 0.118 |
| 20 | 0.005 | 0.003 | 0.004 | 0.092 |
| 21 | 0.016 | 0.012 | 0.020 | 0.107 |
| 22 | 0.005 | 0.004 | 0.007 | 0.084 |
| 23 | 0.014 | 0.010 | 0.016 | 0.098 |
| 24 | 0.006 | 0.003 | 0.010 | 0.077 |
| 25 | 0.005 | 0.005 | 0.016 | 0.090 |
| 26 | 0.004 | 0.003 | 0.007 | 0.071 |
| 27 | 0.008 | 0.007 | 0.008 | 0.083 |
| 28 | 0.004 | 0.003 | 0.003 | 0.066 |
| 29 | 0.006 | 0.005 | 0.007 | 0.078 |
| 30 | 0.005 | 0.003 | 0.003 | 0.061 |
| 31 | 0.007 | 0.004 | 0.006 | 0.073 |
| 32 | 0.003 | 0.003 | 0.004 | 0.058 |
| 33 | 0.008 | 0.003 | 0.008 | 0.068 |
| 34 | 0.003 | 0.002 | 0.004 | 0.054 |
| 35 | 0.008 | 0.004 | 0.008 | 0.064 |
| 36 | 0.005 | 0.006 | 0.007 | 0.051 |
| 37 | 0.007 | 0.003 | 0.007 | 0.061 |
| 38 | 0.002 | 0.003 | 0.004 | 0.048 |
| 39 | 0.005 | 0.003 | 0.007 | 0.058 |
| 40 | 0.003 | 0.003 | 0.004 | 0.046 |
| THD | 2.402 | 2.538 | 2.778 | 5% |

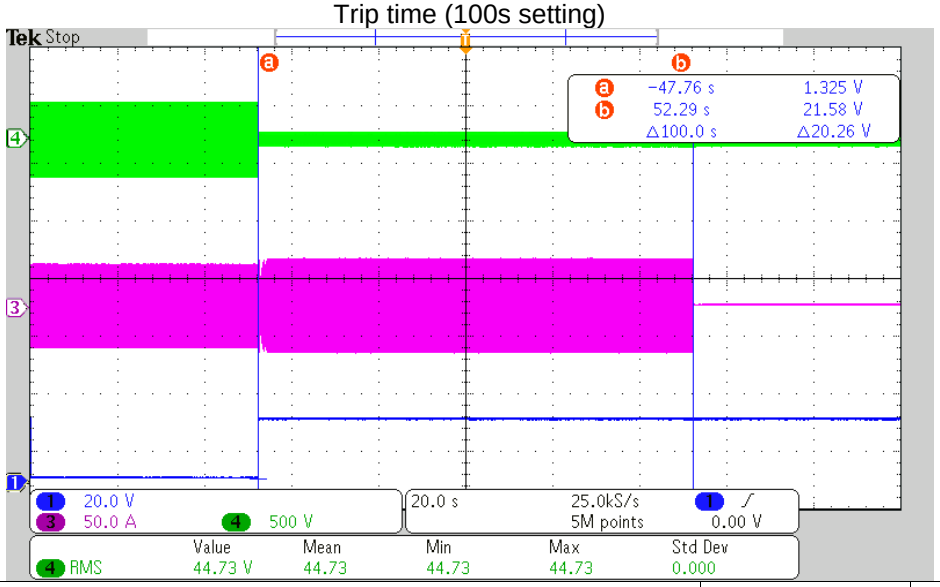
| Table 4.9.3 Interface protection | | | | | P |
|---|---|---|---|---|---|
| **Undervoltage threshold stage 1 [27 < ] Adjustment range** | | | | **Yes** | **No** |
| Trip value Config. from 0.2 to 1 Un (0.01 Un steps) | | | | Yes | |
| Trip time Config. from 0.1 to 100 s (0.1 s steps) | | | | Yes | |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value L1[V] | 46 | 45.64 | 45.84 | 45.31 | 46±2.3 |
| Trip time [ms] | 100 | 98.40 | 99.20 | 99.40 | 100±10 |
| L2 [V] | | | | | 46±2.3 |
| Trip time [ms] | | | | | 100±10 |
| L3 [V] | | | | | 46±2.3 |
| Trip time [ms] | | | | | 100±10 |
| L1L2L3[V] | | | | | 46±2.3 |
| Trip time [ms] | | | | | 100±10 |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value L1[V] | 46 | 44.73 | 45.46 | 45.22 | 46±2.3 |
| Trip time [s] | 100 | 100.00 | 99.98 | 99.99 | 100±10 |
| L2 [V] | | | | | 46±2.3 |
| Trip time [s] | | | | | 100±10 |
| L3 [V] | | | | | 46±2.3 |
| Trip time [s] | | | | | 100±10 |
| L1L2L3[V] | | | | | 46±2.3 |
| Trip time [s] | | | | | 100±10 |

Trip time (0.1s setting)



| Table 4.9.3 Interface protection | P |
|---|---|

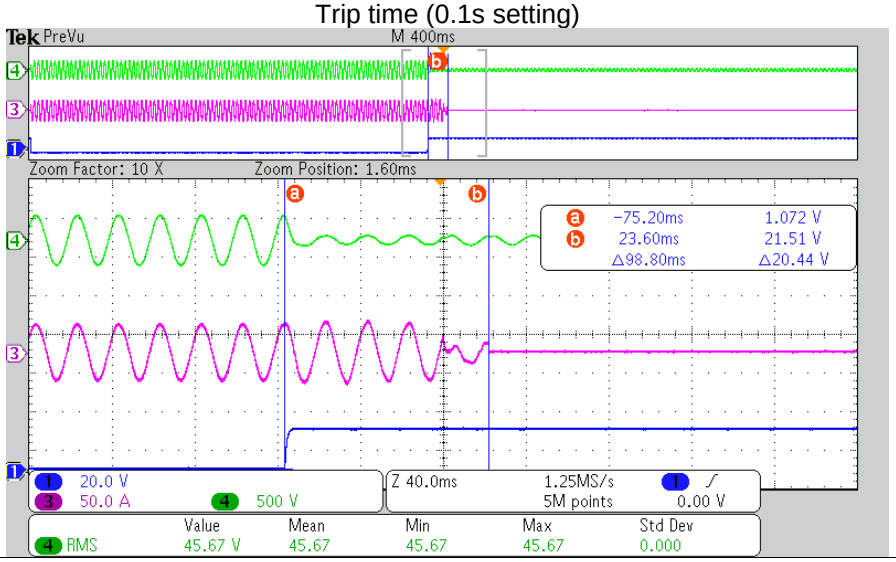
Trip time (100s setting)




| Undervoltage threshold stage 2 [27 < < ] Adjustment range | Yes | No |
|---|---|---|
| Trip value Config. from 0.2 to 1 Un (0.01 Un steps) | Yes | |
| Trip time Config. from 0.1 to 5s (0.05 s steps) | Yes | |

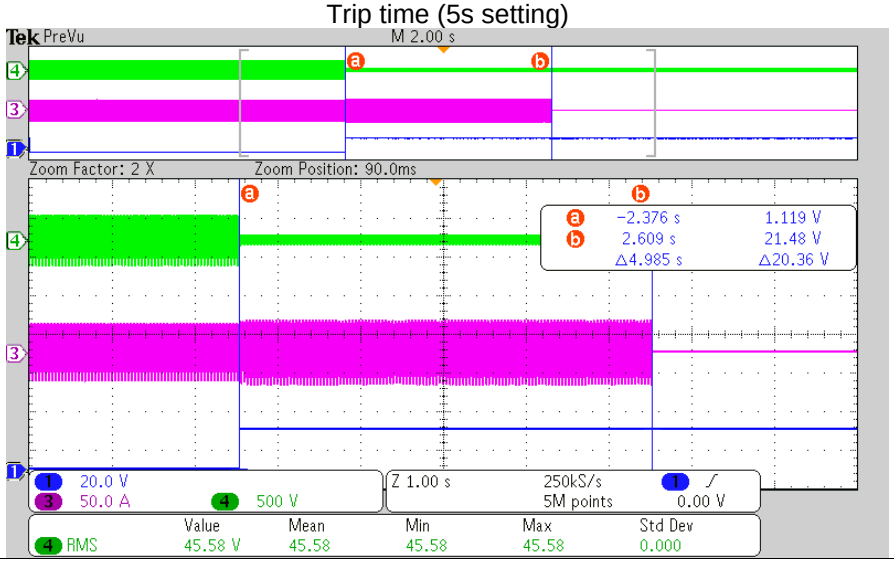
| Parameter | Settings | Test 1 | Test 2 | Test 3 | Limits |
|---|---|---|---|---|---|
| Trip value L1 [V] | 46 | 45.67 | 45.18 | 45.96 | 46±2.3 |
| Trip time [ms] | 100 | 98.80 | 96.97 | 97.64 | 100±10 |
| L2 [V] | | | | | 46±2.3 |
| Trip time [ms] | | | | | 100±10 |
| L3 [V] | | | | | 46±2.3 |
| Trip time [ms] | | | | | 100±10 |
| L1L2L3[V] | | | | | 46±2.3 |
| Trip time [ms] | | | | | 100±10 |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value L1 [V] | 46 | 45.58 | 44.79 | 44.86 | 46±2.3 |
| Trip time [s] | 5 | 4.985 | 4.990 | 4.982 | 5±0.05 |
| L2 [V] | | | | | 46±2.3 |
| Trip time [s] | | | | | 5±0.05 |
| L3 [V] | | | | | 46±2.3 |
| Trip time [s] | | | | | 5±0.05 |
| L1L2L3[V] | | | | | 46±2.3 |
| Trip time [s] | | | | | 5±0.05 |

Trip time (0.1s setting)



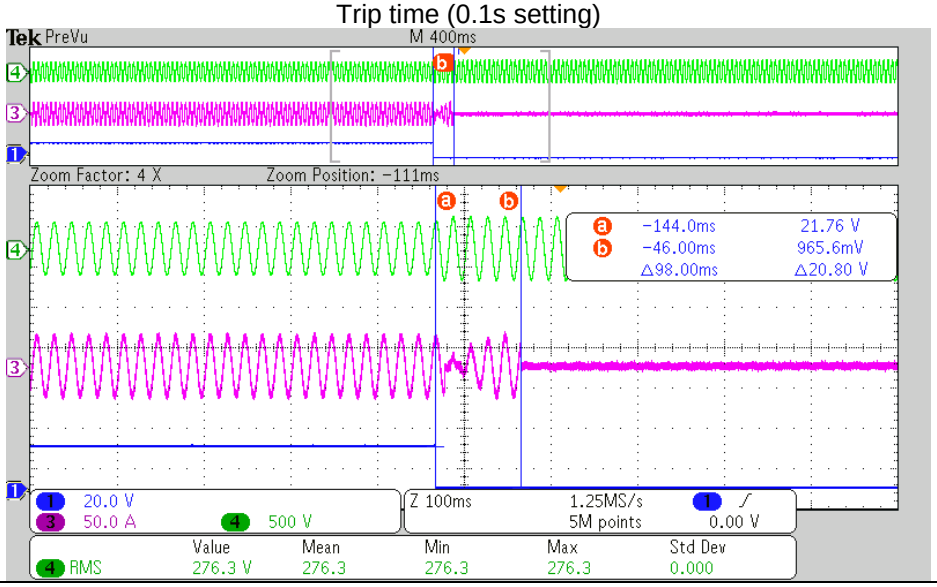
| Table 4.9.3 Interface protection | P |
|---|---|

Trip time (5s setting)

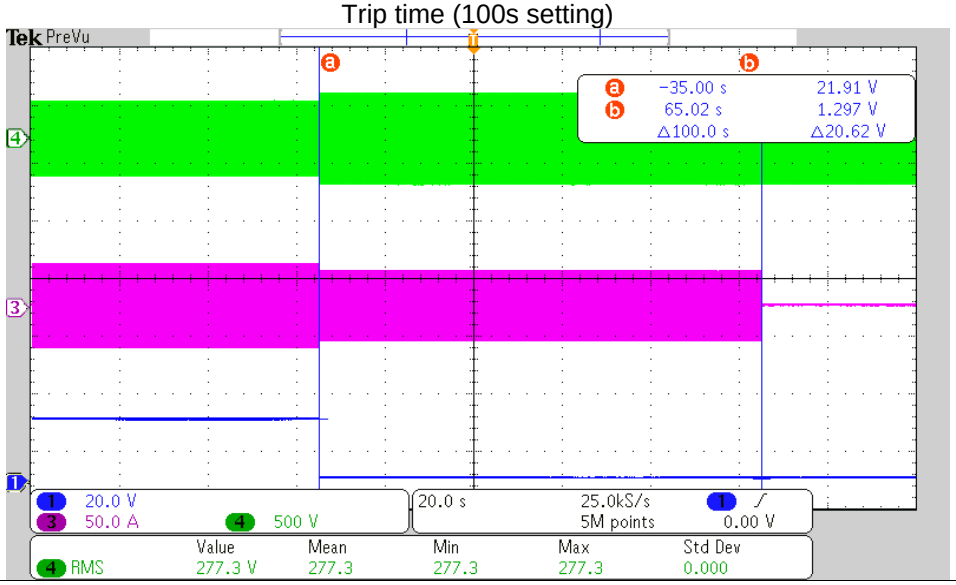


| Table 4.9.3 Interface protection | | | | | P |
|---|---|---|---|---|---|
| **Overvoltage threshold stage 1 [59 >] Adjustment range** | | | | **Yes** | **No** |
| Trip value Config. from 1.0 to 1.2 Un (0.01 Un steps) | | | | Yes | |
| Trip time Config. from 0.1 to 100s (0.1 s steps) | | | | Yes | |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value L1 [V] | 276 | 276.3 | 276.4 | 277.3 | 276±2.3 |
| Trip time [ms] | 100 | 98.00 | 97.85 | 97.23 | 100±10 |
| L2 [V] | | | | | |
| Trip time [ms] | | | | | |
| L3 [V] | | | | | |
| Trip time [ms] | | | | | |
| L1L2L3[V] | | | | | |
| Trip time [ms] | | | | | |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value L1 [V] | 276 | 277.3 | 276.5 | 277.4 | 276±2.3 |
| Trip time [s] | 100 | 100.00 | 100.00 | 100.00 | 100±10 |
| L2 [V] | | | | | |
| Trip time [s] | | | | | |
| L3 [V] | | | | | |
| Trip time [s] | | | | | |
| L1L2L3[V] | | | | | |
| Trip time [s] | | | | | |

Trip time (0.1s setting)

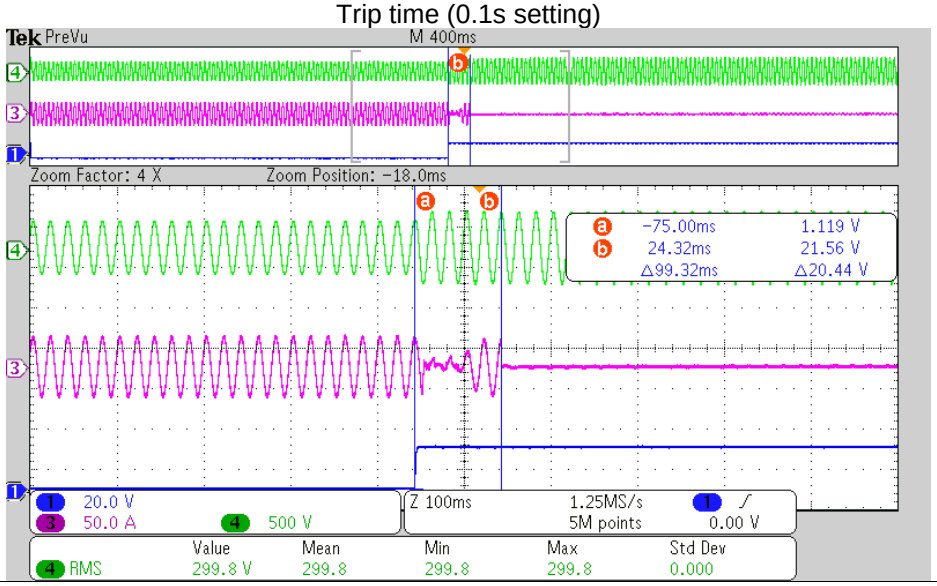



Trip time (100s setting)

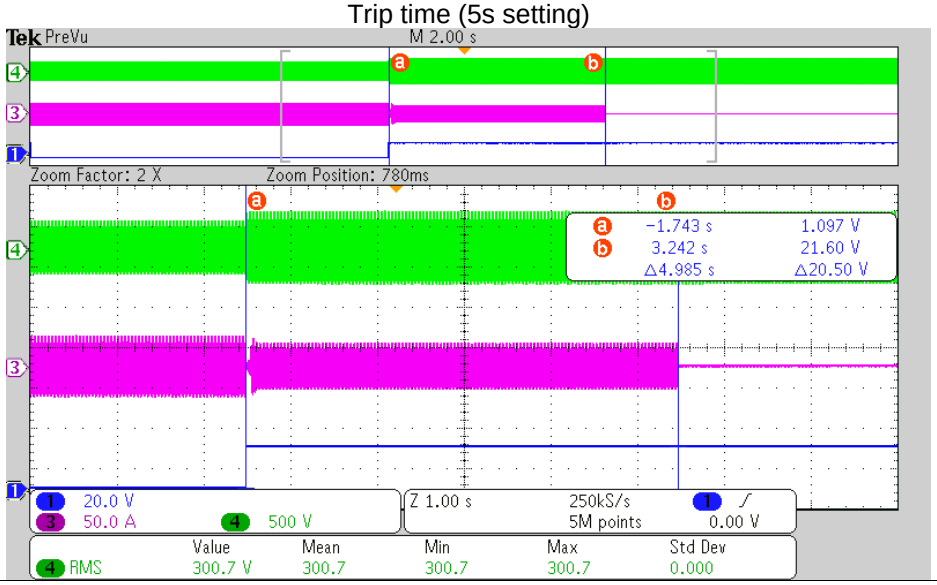


| Table 4.9.3 Interface protection | | | | | P |
|---|---|---|---|---|---|
| **Overvoltage threshold stage 2 [59 > > ] Adjustment range** | | | | **Yes** | **No** |
| Trip value Config. from 1.0 to 1.3 Un (0.01 Un steps) | | | | Yes | |
| Trip time Config. from 0.1 to 5s (0.05s steps) | | | | Yes | |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value L1 [V] | 299 | 299.8 | 299.60 | 299.20 | 299±2.3 |
| Trip time [ms] | 100 | 99.32 | 97.64 | 98.27 | 100±10 |
| L2 [V] | | | | | |
| Trip time [ms] | | | | | |
| L3 [V] | | | | | |
| Trip time [ms] | | | | | |
| L1L2L3[V] | | | | | |
| Trip time [ms] | | | | | |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value L1 [V] | 299 | 300.7 | 300.3 | 299.8 | 299±2.3 |
| Trip time [s] | 5 | 4.985 | 4.992 | 4.996 | 5±0.05 |
| L2 [V] | | | | | |
| Trip time [s] | | | | | |
| L3 [V] | | | | | |
| Trip time [ms] | | | | | |
| L1L2L3[V] | | | | | |
| Trip time [s] | | | | | |

Trip time (0.1s setting)

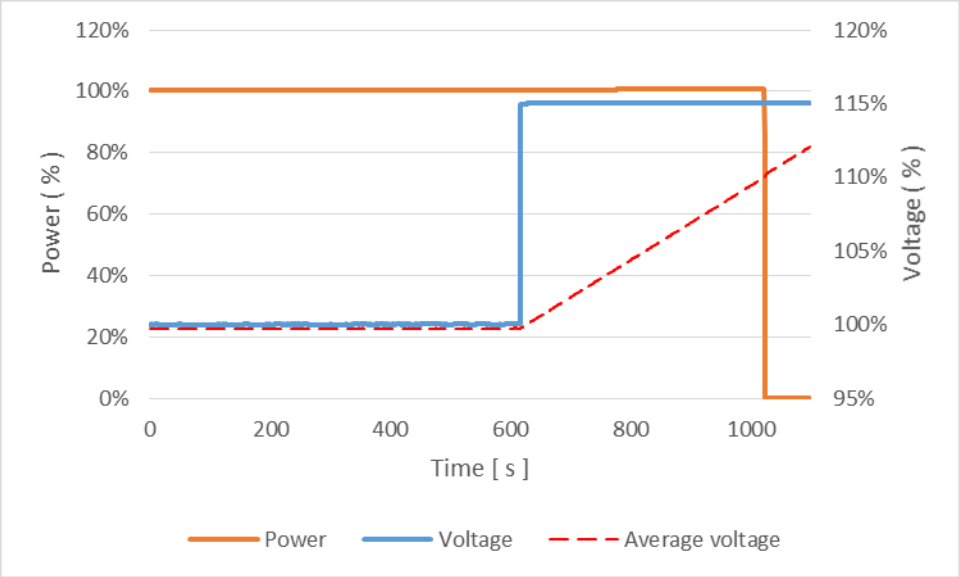



Trip time (5s setting)



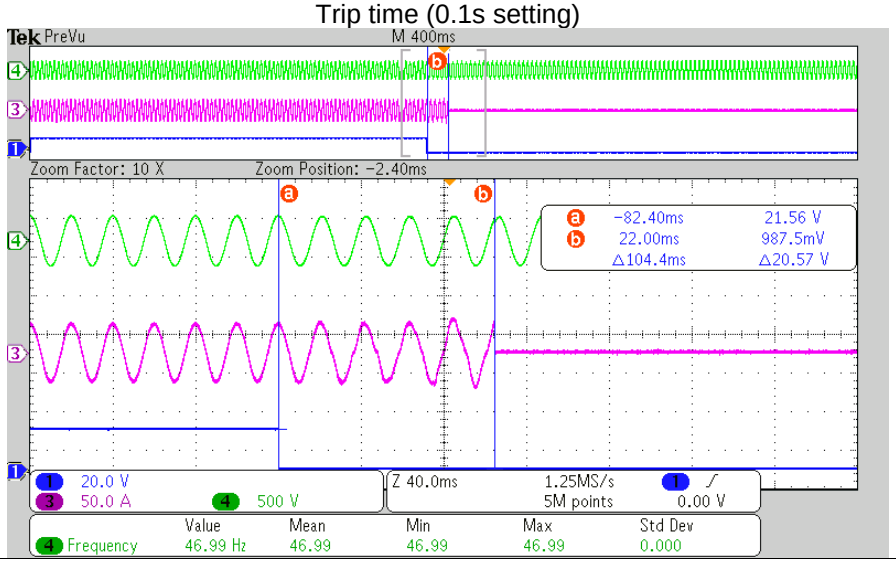
| Table 4.9.3 Interface protection | | | | | P |
|---|---|---|---|---|---|
| **Overvoltage 10 min mean protection Adjustment range** | | | | **Yes** | **No** |
| Trip value Config. from 1.0 to 1.15Un (0.01 Un steps) | | | | Yes | -- |
| Trip time Config ≤ 3s not adjustable Time delay setting = 0 ms | | | | Yes | -- |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value L1 [V] | 253 | 253.03 | 253.06 | 253.04 | 253±1% |
| Trip time [s] | < 603s | 403.2 | 401.4 | 402.2 | ≤ 603s |
| L2 [V] | | | | | |
| Trip time [s] | | | | | |
| L3 [V] | | | | | |
| Trip time [s] | | | | | |
| L1L2L3[V] | | | | | |
| Trip time [s] | | | | | |

Graph_L1

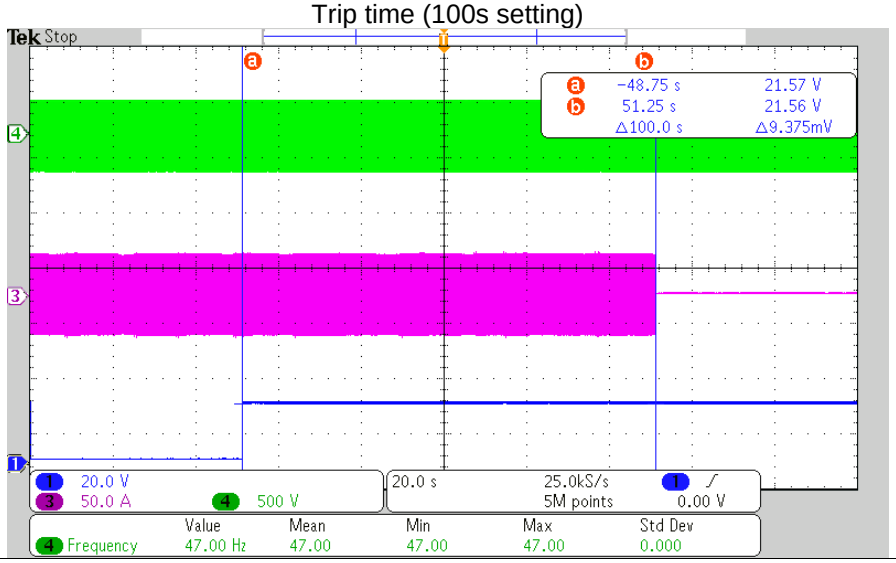


| Table 4.9.3 Interface protection | | | | | P |
|---|---|---|---|---|---|
| **Underfrequency threshold stage 1 [81 < ] Adjustment range** | | | | **Yes** | **No** |
| Trip value Config. from 47.0 to 50.0Hz (0.1Hz steps) | | | | Yes | -- |
| Trip time Config. from 0.1 to 100s (0.1s steps) | | | | Yes | -- |
| it may be required to have the ability to activate and deactivate a stage by an external signal. | | | | -- | No |
| This protection trips in the range from 0.2Un to 1.20Un.it is inhibited for input voltages of less than 20 % Un | | | | -- | No |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value [Hz] | 47.0 | 46.99 | 46.99 | 46.98 | 47.0±0.05 |
| Trip time [ms] | 100 | 104.40 | 100.80 | 100.60 | 100±10 |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value [Hz] | 47.0 | 47.00 | 47.00 | 46.99 | 47.0±0.05 |
| Trip time [s] | 100 | 100.00 | 99.98 | 100.00 | 100±10 |

Trip time (0.1s setting)

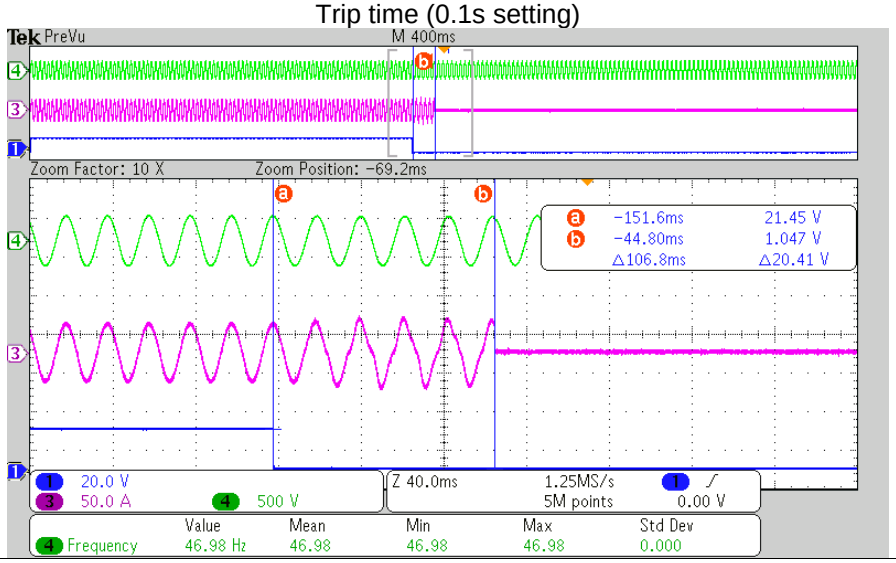



Trip time (100s setting)

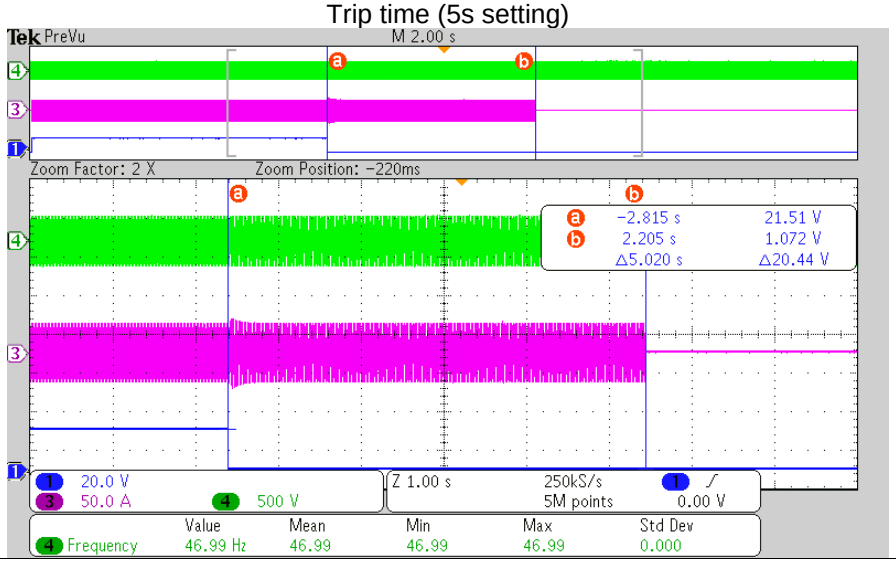


| Table 4.9.3 Interface protection | | | | | P |
|---|---|---|---|---|---|
| **Underfrequency threshold stage 2 [81 < < ] Adjustment range** | | | | **Yes** | **No** |
| Trip value Config. from 47.0 to 50.0Hz (0.1Hz steps) | | | | Yes | -- |
| Trip time Config. from 0.1 to 5s (0.05s steps) | | | | Yes | -- |
| it may be required to have the ability to activate and deactivate a stage by an external signal. | | | | -- | No |
| This protection trips in the range from 0.2Un to 1.20Un.it is inhibited for input voltages of less than 20 % Un | | | | -- | No |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value [Hz] | 47.0 | 46.98 | 46.97 | 46.98 | 47.0±0.05 |
| Trip time [ms] | 100 | 106.80 | 101.70 | 100.40 | 100±10 |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value [Hz] | 47.0 | 46.99 | 47.00 | 46.99 | 47.0±0.05 |
| Trip time [s] | 5 | 5.02 | 5.00 | 5.00 | 5±0.05 |

Trip time (0.1s setting)

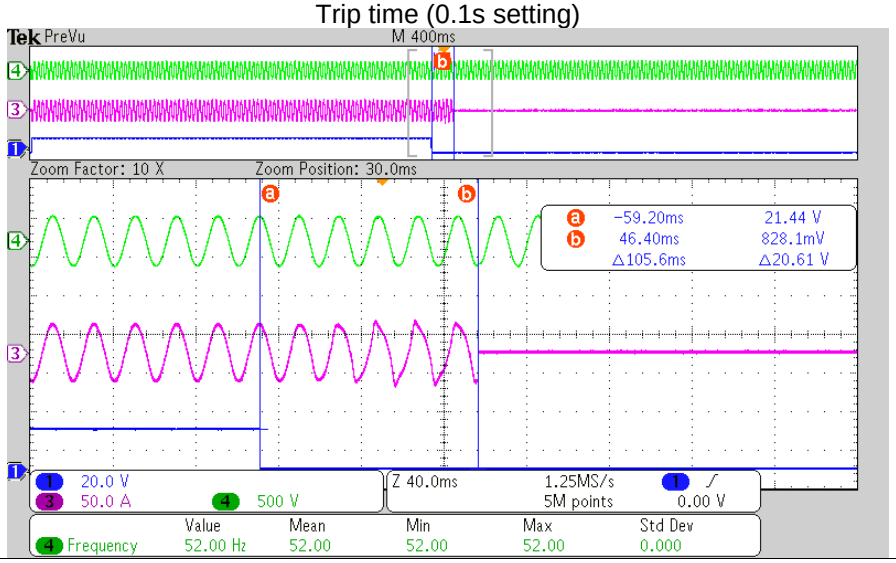



Trip time (5s setting)

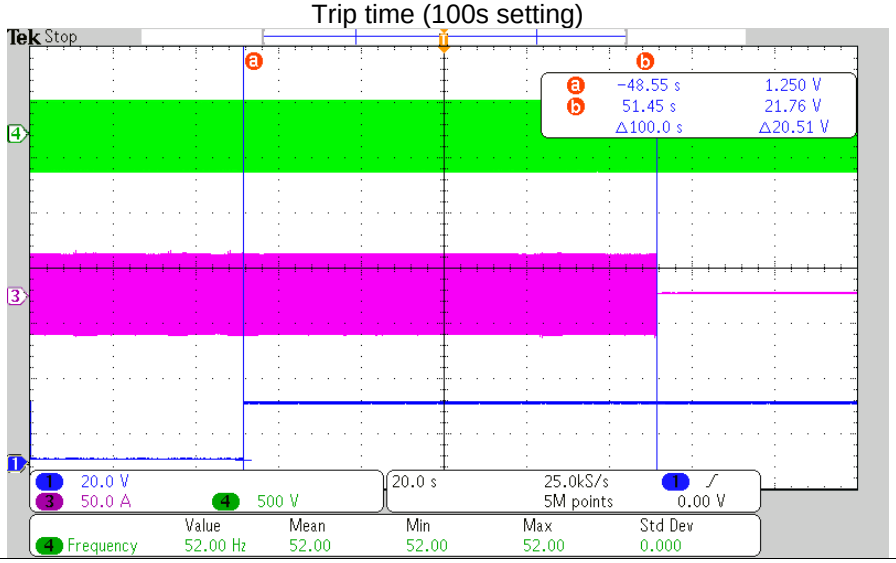


| Table 4.9.3 Interface protection | | | | | P |
|---|---|---|---|---|---|
| **Overfrequency threshold stage 1 [81 > ] Adjustment range** | | | | **Yes** | **No** |
| Trip value Config. from 50.0 to 52.0Hz (0.1Hz steps) | | | | Yes | -- |
| Trip time Config. from 0.1 to 100s (0.1s steps) | | | | Yes | -- |
| it may be required to have the ability to activate and deactivate a stage by an external signal. | | | | -- | No |
| This protection trips in the range from 0.2Un to 1.20Un.it is inhibited for input voltages of less than 20 % Un | | | | -- | No |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value [Hz] | 52.0 | 52.00 | 52.00 | 52.00 | 52.0±0.05 |
| Trip time [ms] | 100 | 105.60 | 100.20 | 100.60 | 100±10 |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value [Hz] | 52.0 | 52.00 | 52.00 | 52.01 | 52.0±0.05 |
| Trip time [s] | 100 | 100.00 | 100.00 | 100.00 | 100±10 |

Trip time (0.1s setting)

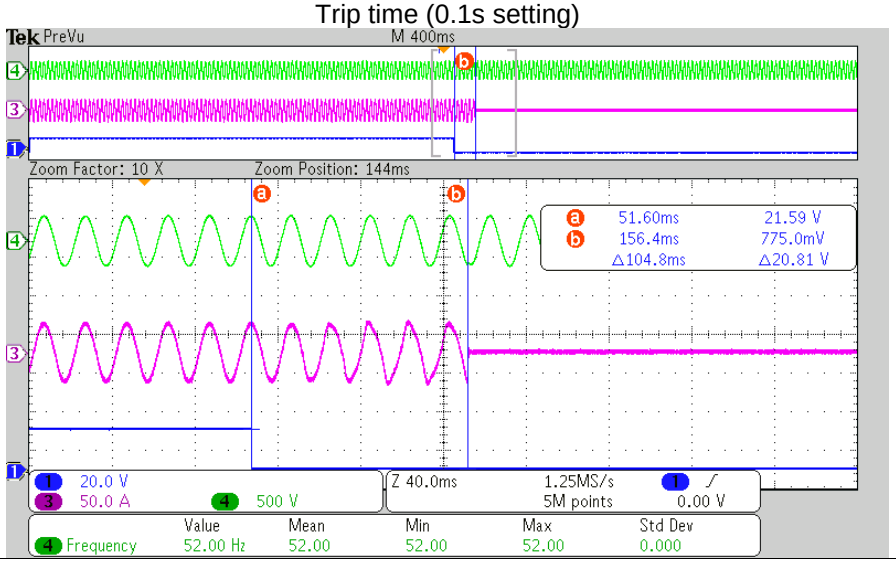



Trip time (100s setting)

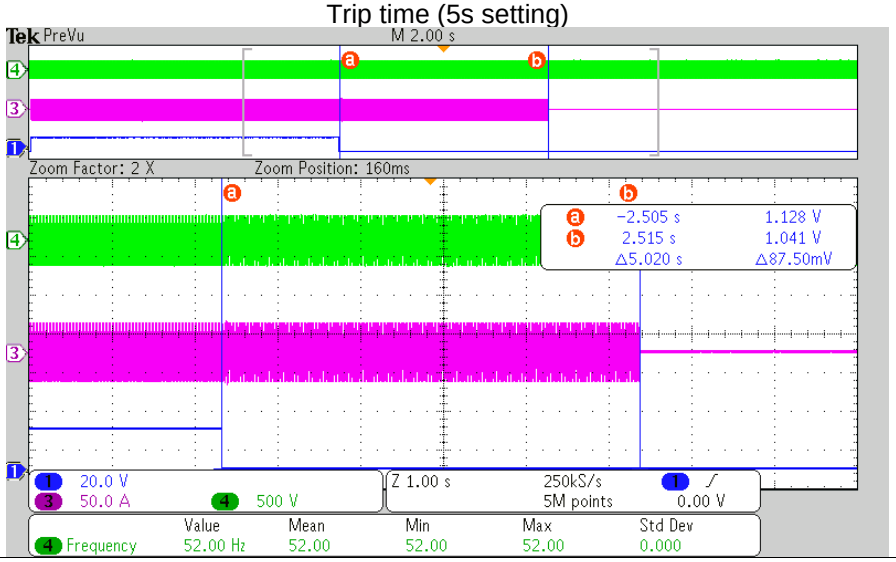


| Table 4.9.3 Interface protection | | | | | P |
|---|---|---|---|---|---|
| Overfrequency threshold stage 2 [81 > > ] Adjustment range | | | | Yes | No |
| Trip value Config. from 50.0 to 52.0Hz (0.1Hz steps) | | | | Yes | -- |
| Trip time Config. from 0.1 to 5s (0.05s steps) | | | | Yes | -- |
| it may be required to have the ability to activate and deactivate a stage by an external signal. | | | | -- | No |
| This protection trips in the range from 0.2Un to 1.20Un.it is inhibited for input voltages of less than 20 % Un | | | | -- | No |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value [Hz] | 52.0 | 52.00 | 52.00 | 52.01 | 52.0±0.05 |
| Trip time [ms] | 100 | 104.80 | 100.40 | 100.10 | 100±10 |
| **Parameter** | **Settings** | **Test 1** | **Test 2** | **Test 3** | **Limits** |
| Trip value [Hz] | 52.0 | 52.00 | 52.00 | 52.00 | 52.0±0.05 |
| Trip time [s] | 5 | 5.02 | 5.00 | 4.99 | 5±0.05 |

Trip time (0.1s setting)




Trip time (5s setting)



| **4.9.4 Means to detect island situation** | | | | | | | | | **P** |
|---|---|---|---|---|---|---|---|---|---|
| No. | *P*EUT[1)] (% of EUT rating) | Reactive load (% of QL in 6.1.d)1) | PAC[2)] (% of nominal) | QAC [3)] (% of nominal) | Run on time (ms) | $P_{EUT}$ (W) | Actual Qf | $V_{DC}$ | Remarks [4)] |
| 1. | 100 | 100 | 0 | 0 | 322 | 6000 | 0.99 | 355 | Test A at BL |
| 2. | 66 | 66 | 0 | 0 | 300 | 3960 | 1.00 | 270 | Test B at BL |
| 3. | 33 | 33 | 0 | 0 | 281 | 1980 | 0.98 | 168 | Test C at BL |
| 4. | 100 | 100 | -5 | -5 | 304 | 6000 | 1.01 | 355 | Test A at IB |
| 5. | 100 | 100 | -5 | 0 | 289 | 6000 | 1.04 | 355 | Test A at IB |
| 6. | 100 | 100 | -5 | 5 | 212 | 6000 | 1.07 | 355 | Test A at IB |
| 7. | 100 | 100 | 0 | -5 | 277 | 6000 | 0.96 | 355 | Test A at IB |
| 8. | 100 | 100 | 0 | 5 | 237 | 6000 | 1.01 | 355 | Test A at IB |
| 9. | 100 | 100 | 5 | -5 | 210 | 6000 | 0.92 | 355 | Test A at IB |
| 10. | 100 | 100 | 5 | 0 | 280 | 6000 | 0.94 | 355 | Test A at IB |
| 11. | 100 | 100 | 5 | 5 | 282 | 6000 | 0.96 | 355 | Test A at IB |
| 12. | 66 | 66 | 0 | -5 | 222 | 3960 | 0.97 | 270 | Test B at IB |
| 13. | 66 | 66 | 0 | -4 | 228 | 3960 | 0.98 | 270 | Test B at IB |
| 14. | 66 | 66 | 0 | -3 | 230 | 3960 | 0.98 | 270 | Test B at IB |
| 15. | 66 | 66 | 0 | -2 | 280 | 3960 | 0.99 | 270 | Test B at IB |
| 16. | 66 | 66 | 0 | -1 | 236 | 3960 | 0.99 | 270 | Test B at IB |
| 17. | 66 | 66 | 0 | 1 | 238 | 3960 | 1.00 | 270 | Test B at IB |
| 18. | 66 | 66 | 0 | 2 | 256 | 3960 | 1.01 | 270 | Test B at IB |
| 19. | 66 | 66 | 0 | 3 | 254 | 3960 | 1.01 | 270 | Test B at IB |
| 20. | 66 | 66 | 0 | 4 | 242 | 3960 | 1.02 | 270 | Test B at IB |
| 21. | 66 | 66 | 0 | 5 | 168 | 3960 | 1.02 | 270 | Test B at IB |
| 22. | 33 | 33 | 0 | -5 | 203 | 1980 | 0.96 | 168 | Test C at IB |
| 23. | 33 | 33 | 0 | -4 | 218 | 1980 | 0.96 | 168 | Test C at IB |
| 24. | 33 | 33 | 0 | -3 | 220 | 1980 | 0.97 | 168 | Test C at IB |
| 25. | 33 | 33 | 0 | -2 | 242 | 1980 | 0.97 | 168 | Test C at IB |
| 26. | 33 | 33 | 0 | -1 | 230 | 1980 | 0.98 | 168 | Test C at IB |
| 27. | 33 | 33 | 0 | 1 | 263 | 1980 | 0.99 | 168 | Test C at IB |
| 28. | 33 | 33 | 0 | 2 | 245 | 1980 | 0.99 | 168 | Test C at IB |
| 29. | 33 | 33 | 0 | 3 | 256 | 1980 | 1.00 | 168 | Test C at IB |
| 30. | 33 | 33 | 0 | 4 | 200 | 1980 | 1.00 | 168 | Test C at IB |
| 31. | 33 | 33 | 0 | 5 | 160 | 1980 | 1.01 | 168 | Test C at IB |

Remark:

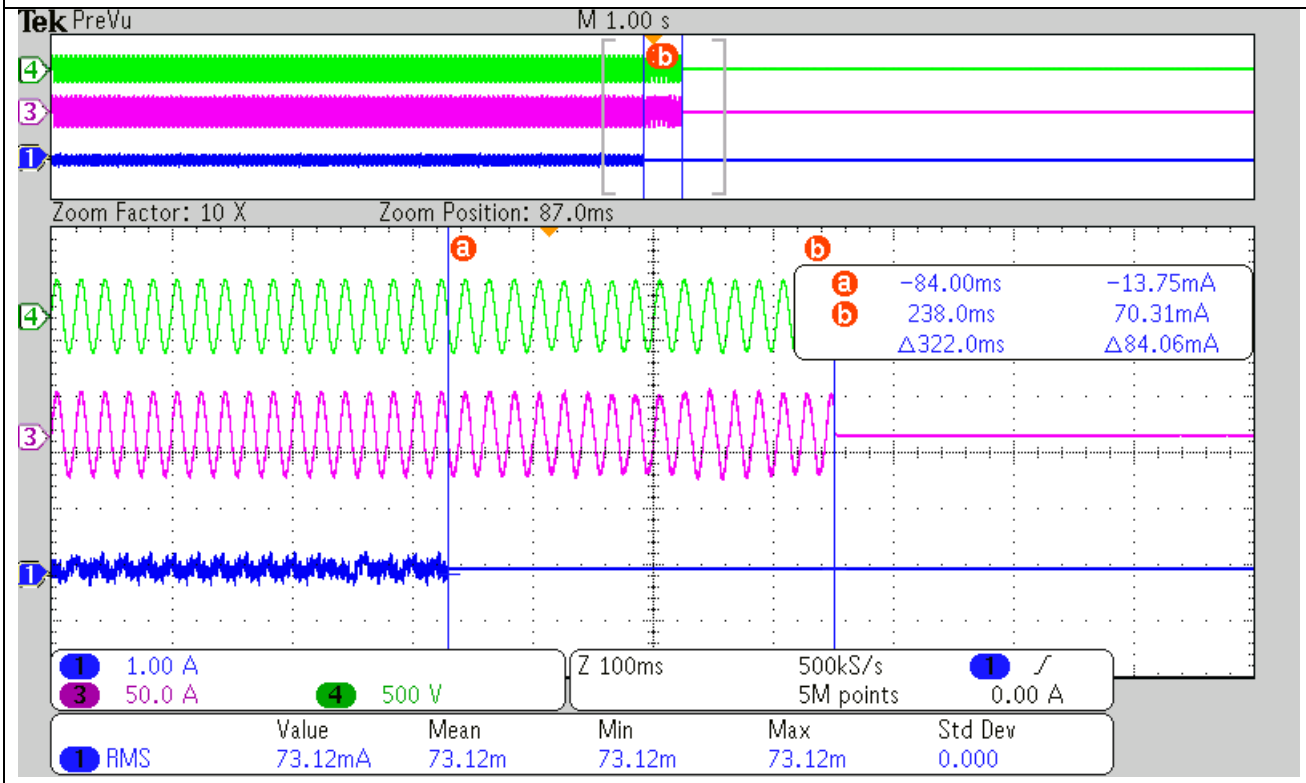
1) *P*EUT: EUT output power

2) *P*AC: Real power flow at S1 in Figure 1. Positive means power from EUT to utility. Nominal is the 0 % test condition value.

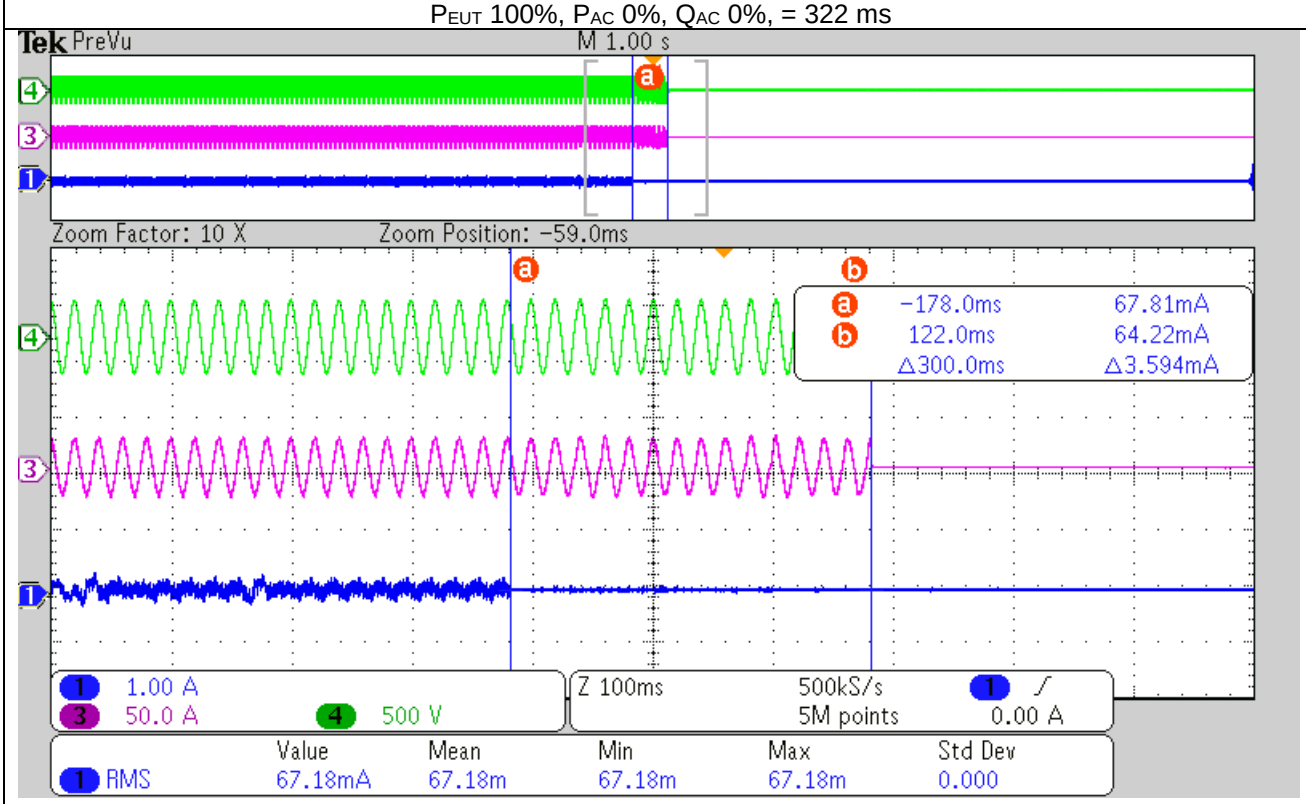
3) *Q*AC: Reactive power flow at S1 in Figure 1. Positive means power from EUT to utility. Nominal is the 0 % test condition value.

| 4.9.4 Means to detect island situation | P |
|---|---|

4) BL: Balance condition, IB: Imbalance condition.

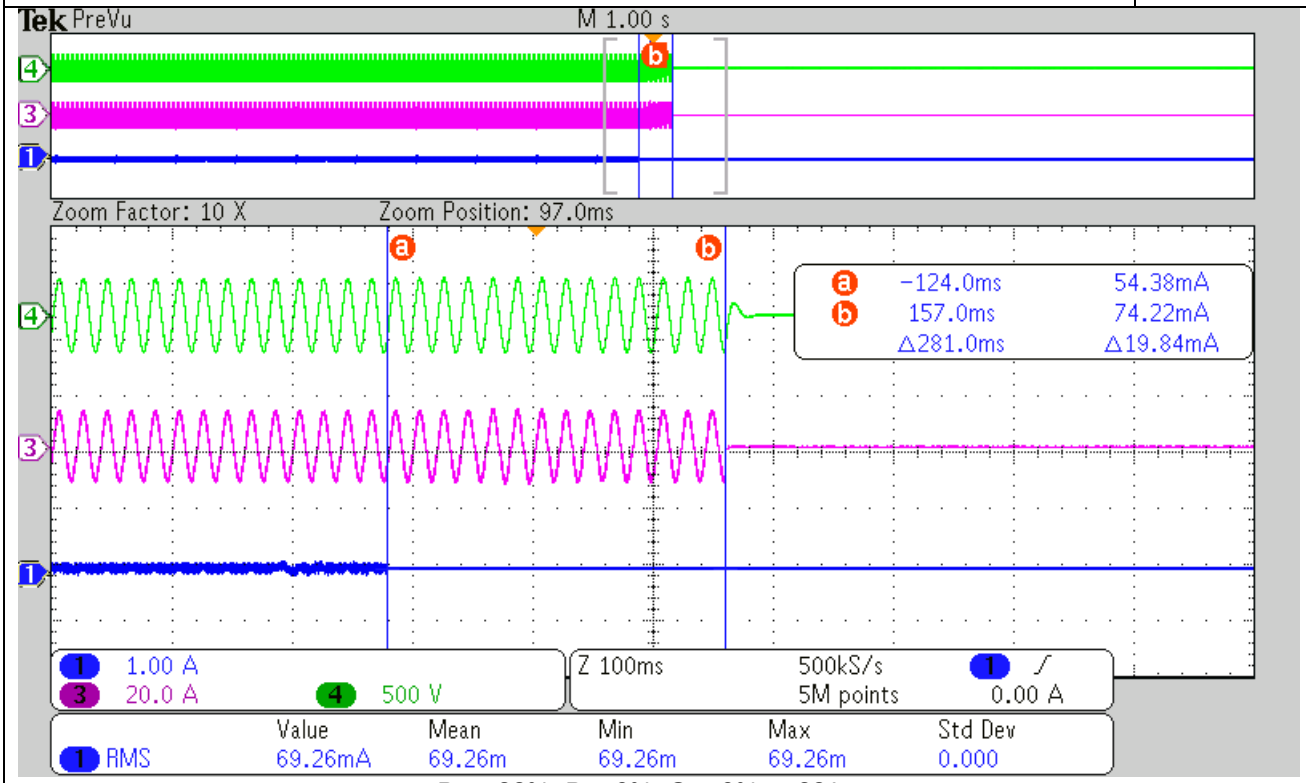



$P_{EUT}$ 100%, $P_{AC}$ 0%, $Q_{AC}$ 0%, = 322 ms




$P_{EUT}$ 66%, $P_{AC}$ 0%, $Q_{AC}$ 0%, = 300 ms

| 4.9.4 Means to detect island situation | P |
|---|---|



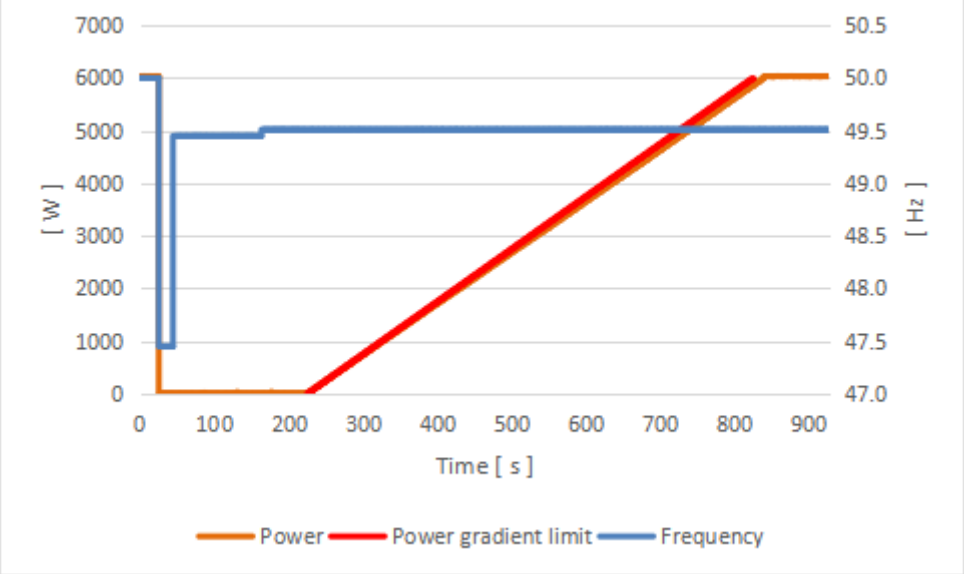

$P_{EUT}$ 33%, $P_{AC}$ 0%, $Q_{AC}$ 0%, = 281 ms

**4.10.2 Automatic reconnection after tripping** **P**

| Parameter | Range | Default setting |
|---|---|---|
| Lower frequency | 47,0Hz – 50,0Hz | 49,5Hz |
| Upper frequency | 50,0Hz – 52,0Hz | 50,2Hz |
| Lower voltage | 50% – 100%$U_n$ | 85 % $U_n$ |
| Upper voltage | 100% – 120% $U_n$ | 110 % $U_n$ |
| Observation time | 10s – 600s | 60s |
| Active power increase gradient | 6% – 3000%/min | 10%/min |

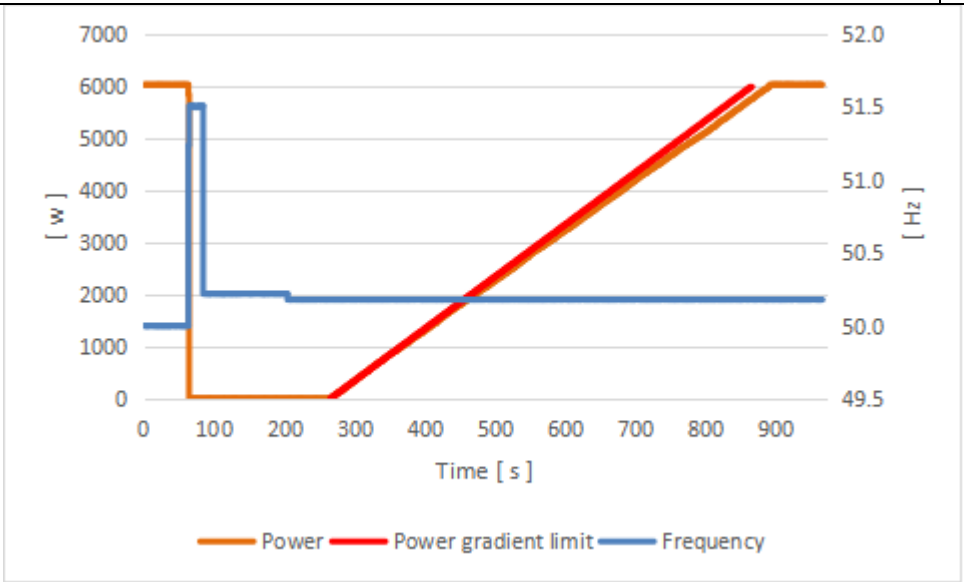
| Test sequence after trip | connection | connection allowed | Observation time (s) | Power gradient after Connection (%/min) |
|---|---|---|---|---|
| Step a) | <49.5Hz | No | -- | -- |
| Step b) | ≥49.5Hz | Yes | 61.0 | 9.70 |
| Step c) | >50.2Hz | No | -- | -- |
| Step d) | ≤50.2Hz | Yes | 61.0 | 9.63 |
| Step e) | <195.5V | No | -- | -- |
| Step f) | ≥195.5V | Yes | 61.0 | 9.78 |
| Step g) | >253V | No | -- | -- |
| Step h) | ≤253V | Yes | 61.0 | 9.72 |

Remark: Tested at default setting.

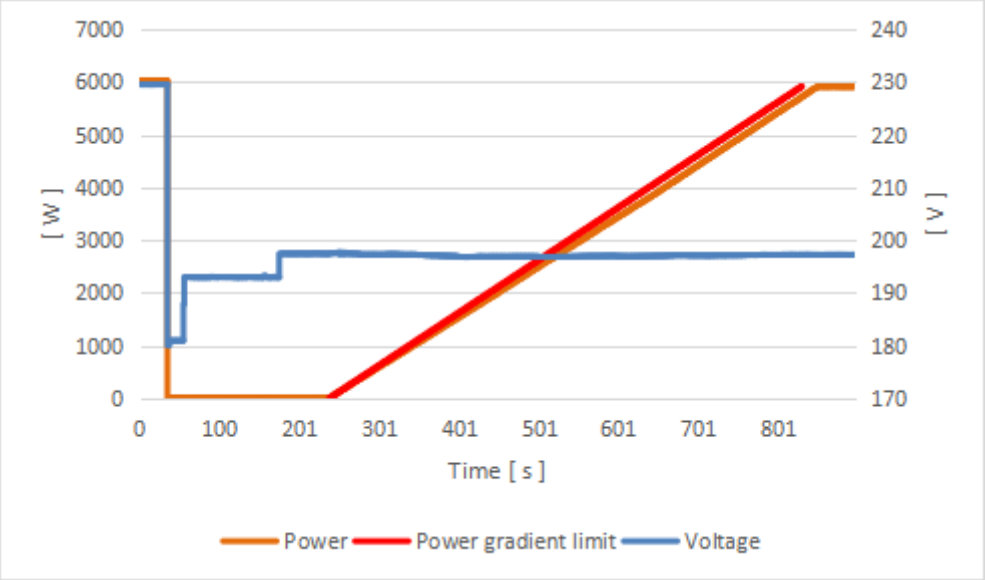



Graph_49.5Hz setting

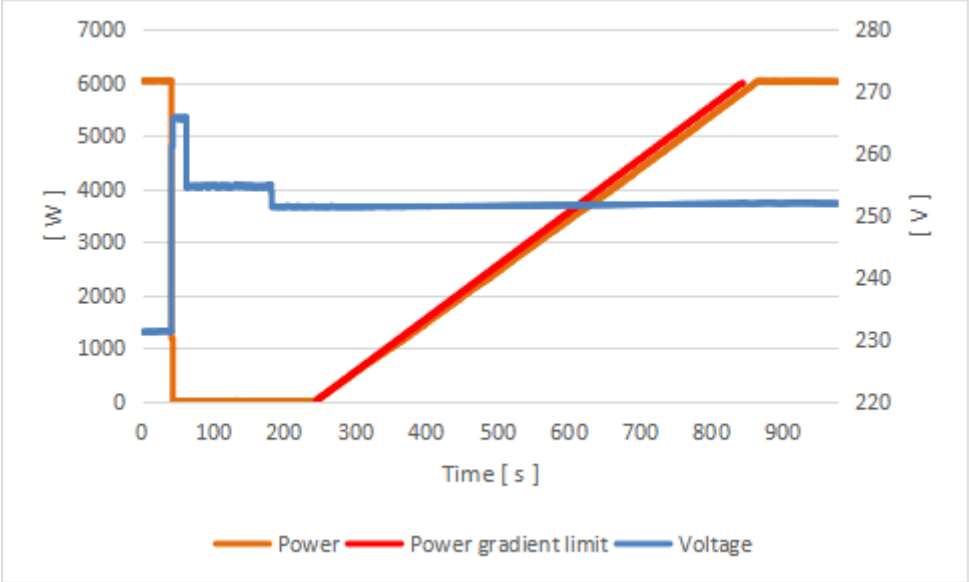
| 4.10.2 Automatic reconnection after tripping | P |
|---|---|




Graph_50.2Hz setting




Graph_195.5V setting




Graph_253V setting

**4.10.3 Starting to generate electrical power** — **P**

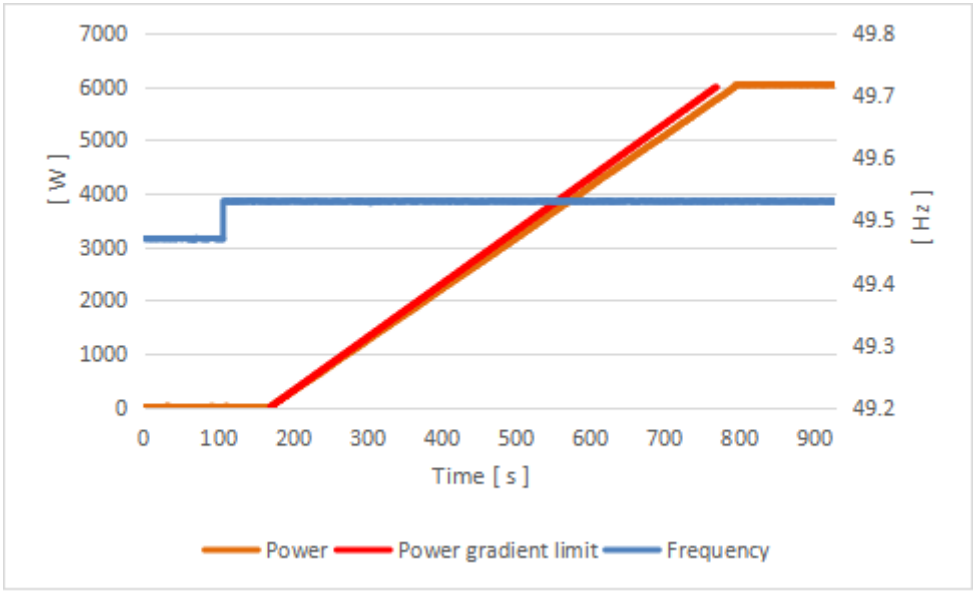
| Parameter | Range | Default setting |
|---|---|---|
| Lower frequency | 47,0Hz – 50,0Hz | 49,5Hz |
| Upper frequency | 50,0Hz – 52,0Hz | 50,1Hz |
| Lower voltage | 50% – 100% $U_n$ | 85 % $U_n$ |
| Upper voltage | 100% – 120% $U_n$ | 110 % $U_n$ |
| Observation time | 10s – 600s | 60s |
| Active power increase gradient | 6% – 3000%/min | disabled |

Test result:

| Test sequence at normal operation starting | connection | connection allowed | Observation time (s) | Power gradient after Connection (%/min) |
|---|---|---|---|---|
| Step a) | <49.5Hz | No | -- | -- |
| Step b) | ≥49.5Hz | Yes | 61.0 | 9.57 |
| Step c) | >50.1Hz | No | -- | -- |
| Step d) | ≤50.1Hz | Yes | 61.0 | 9.54 |
| Step e) | <195.5V | No | -- | -- |
| Step f) | ≥195.5V | Yes | 61.0 | 9.78 |
| Step g) | >253V | No | -- | -- |
| Step h) | ≤253V | Yes | 61.0 | 9.62 |

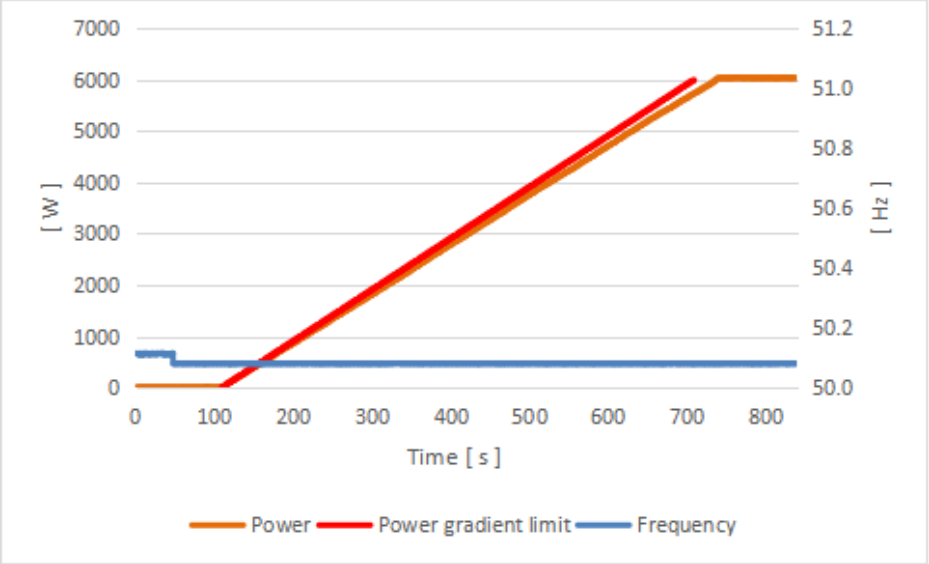
Remark: Tested at default setting.

Graph_49.5Hz

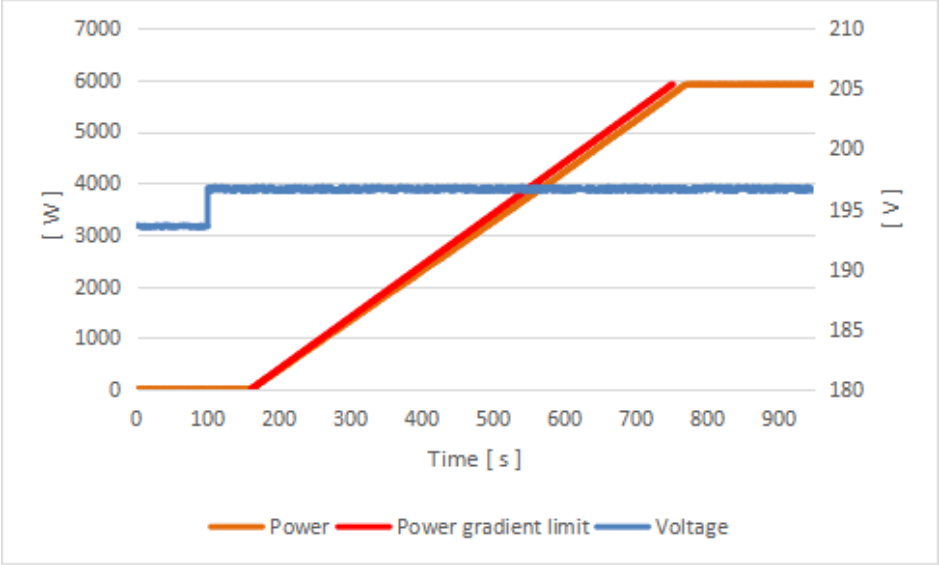


| 4.10.3 Starting to generate electrical power | P |
|---|---|

Graph_50.1Hz

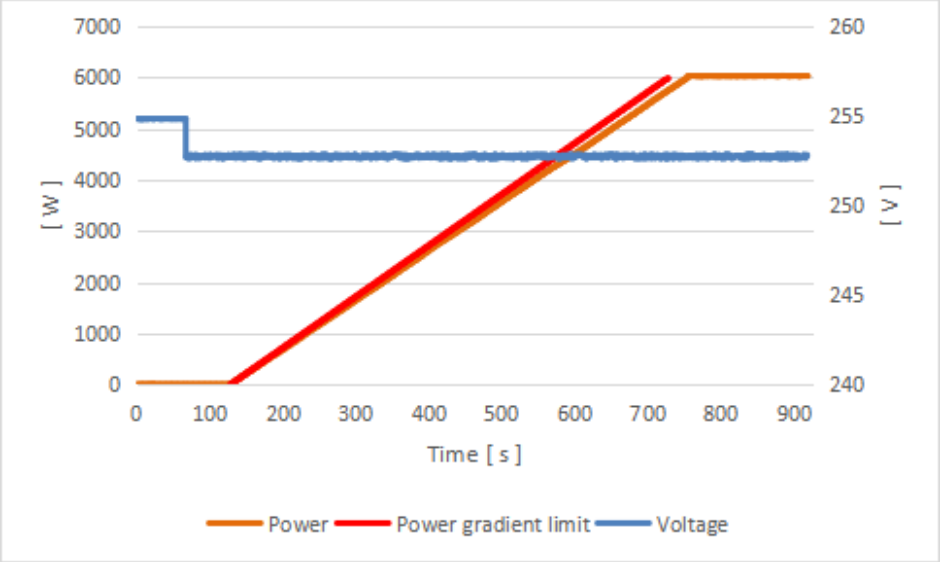



Graph_195.5V



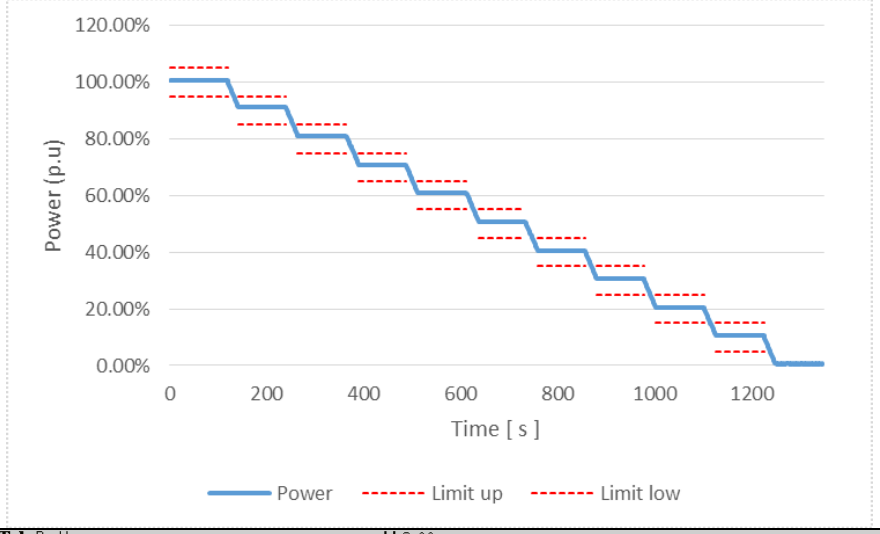
| 4.10.3 Starting to generate electrical power | P |
|---|---|

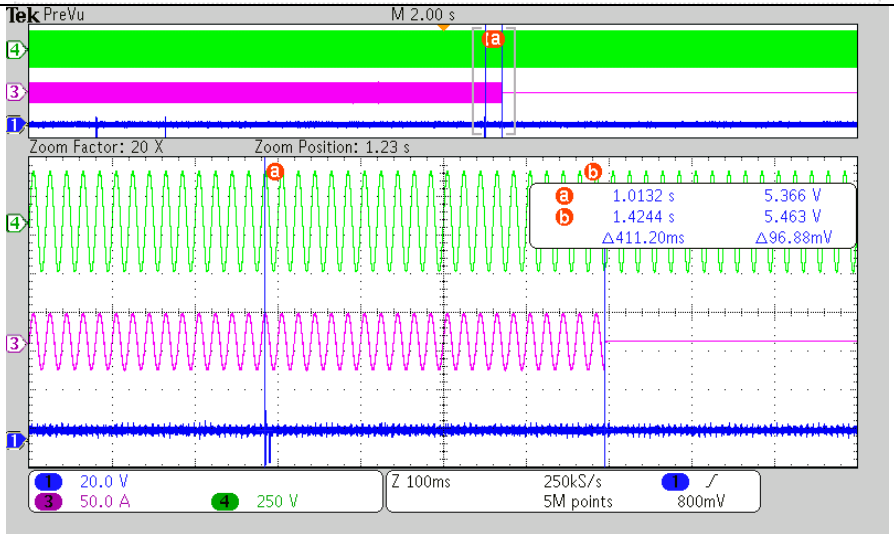
Graph_253V



| 4.11 Active power reduction by setpoint and ceasing active power (Logic interface) | | | | | | | P |
|---|---|---|---|---|---|---|---|
| String | 1 | $U_{DC}$ = | 360 Vdc | Uac = Un | 230 Vac | $P_{Emax}$ (KW) | 6 |

| 1 min mean value P/Pn Psetpoint (%) | Pmeasured (%) | △Pmeasured (%) | Limit [%] |
|---|---|---|---|
| 100% | 100.10% | 0.10% | ±5% |
| 90% | 90.24% | 0.24% | ±5% |
| 80% | 80.23% | 0.23% | ±5% |
| 70% | 70.27% | 0.27% | ±5% |
| 60% | 60.14% | 0.14% | ±5% |
| 50% | 50.15% | 0.15% | ±5% |
| 40% | 40.32% | 0.32% | ±5% |
| 30% | 30.27% | 0.27% | ±5% |
| 20% | 20.39% | 0.39% | ±5% |
| 10% | 10.42% | 0.42% | ±5% |
| 0% | 0.29% | 0.29% | ±5% |
| The power gradient for increasing and reducing (%$P_n$/s) | | | 0.42%$P_n$/s |
| Time for Logic interface (at input port) activated | | | 0.411s |



| 4.13 | TABLE: Single fault tolerance | | | | P |
|---|---|---|---|---|---|
| No. | Fault | Component No. | Fault point | Duration | Result |
| 1. | ISO Relay | ALFG1 | Short circuit before start up inverter | 3min | Unit can't operate, EM: Iso Fault. no danger, no hazard, no fire |
| 2. | Monitoring Relay - L | K1 | Pin3 to Pin4 short circuit before start up inverter | 3min | Unit can't operate, EM: GridRelay Fault. no danger, no hazard, no fire |
| 3. | Monitoring Relay - L | K1 | Pin3 to Pin4 open circuit before start up inverter | 3min | Unit can't operate, EM: GridRelay Fault. no danger, no hazard, no fire |
| 4. | Monitoring Relay - N | K3 | Pin3 to Pin4 short circuit before start up inverter | 3min | Unit can't operate, EM: GridRelay Fault. no danger, no hazard, no fire |
| 5. | Monitoring Relay - N | K3 | Pin3 to Pin4 open circuit before start up inverter | 3min | Unit can't operate, EM: GridRelay Fault. no danger, no hazard, no fire |
| 6. | AC voltage measure1 | D4 | Pin2-Pin3 Short circuit | 3min | Unit shut down, EM: GridOverVolt Fault. no danger, no hazard, no fire |
| 7. | AC voltage measure1 | D4 | Pin1-Pin3 Short circuit | 3min | Unit shut down, EM: GridOverVolt Fault. no danger, no hazard, no fire |
| 8. | AC voltage measure2 | D10 | Pin1-Pin3 Short circuit | 3min | Unit can't operate, EM: PSInvHighVoltFault. No damage, no hazard, no fire |
| 9. | AC voltage measure2 | D10 | Pin2-Pin3 Short circuit | 3min | Unit can't operate, EM: PSInvHighVoltFault. No damage, no hazard, no fire |
| 10. | AC current measure1 | D19 | Pin1-Pin3 Short circuit | 3min | Unit can't operate, EM: RInvCurAdChaFault. No damage, no hazard, no fire. |
| 11. | AC current measure1 | D19 | Pin2-Pin3 Short circuit | 3min | Unit can't operate, EM: RInvCurAdChaFault. No damage, no hazard, no fire. |
| 12. | AC current measure2 | D20 | Pin1-Pin3 Short circuit | 3min | Unit can't operate, EM: SInvCurAdChaFault. No damage, no hazard, no fire. |
| 13. | AC current measure2 | D20 | Pin2-Pin3 Short circuit | 3min | Unit can't operate, EM: SInvCurAdChaFault. No damage, no hazard, no fire. |
| 14. | AC current measure3 | D22 | Pin2-Pin3 Short circuit | 3min | Unit can't operate, EM: RUPSInstCurrHighFault. No damage, no hazard, no fire. |
| 15. | AC frequency measure | R255 | Pin1-Pin2 Short circuit | 3min | Unit shut down, EM: GridOverFreq Fault. No damage, no hazard, no fire |
| 16. | V-bus measure | D31 | Pin2-Pin3 Short circuit | 3min | Unit can't operate, EM: BusAllVoltHwOveFault. No damage, no hazard, no fire. |
| 17. | T measure | R180 | Pin1-Pin2 Short circuit | 3min | Unit can't operate, EM: TemperatureAdChanFault. No damage, no hazard, no fire. |
| 18. | power tube IGBT | QA5 | Pin2-Pin3 Short circuit before start up | 3min | Unit can't operate, EM: InvOpenTestErr. No danger, no hazard, no fire |
| 19. | power tube IGBT | QA6 | Pin2-Pin3 Short circuit before start up | 3min | Unit shut down, EM: InvOpenTestErr. No damage, no hazard, no fire |
| 20. | GFCI check | -- | Short circuit | 3min | Unit shut down, EM: LeakCurrFault. No damage, no hazard, no fire |

| 4.13 | TABLE: Single fault tolerance | | | | | P |
|---|---|---|---|---|---|---|
| 21. | Bus cap | C208 | Pin1-Pin2<br>Short circuit before start up | 3min | Unit can not start up, No damage, no hazard, no fire. | |
| 4.4.4.4 Transformer short circuit tests | | | | | | |
| 22. | Transformer short circuit tests | T4 | Pin22-Pin24<br>Short circuit | 10min | Unit can not start up, No damage, no hazard, no fire. | |
| 23. | Transformer short circuit tests | T4 | Pin32-Pin36<br>Short circuit | 10min | Unit can not start up, No damage, no hazard, no fire. | |
| 24. | power tube MOS-SPS | Q-MOS1 | G-D<br>Short circuit | 10min | SPS no output, no danger, no hazard, no fire | |
| 25. | power tube MOS-SPS | Q-MOS1 | D-S<br>Short circuit | 10min | SPS no output,<br>no danger, no hazard, no fire | |
| 4.4.4.5 Output short circuit | | | | | | |
| 26. | Output L to N | -- | short circuit | 3min | Unit shut down, EM: GridUnderVoltFault.<br>No damage, no hazard, no fire | |
| 27. | Output L to PE | -- | short circuit | 3min | Unit shut down, EM: GridLossFault.<br>No damage, no hazard, no fire | |
| 4.4.4.6 Backfeed current test for equipment with more than one source of supply | | | | | | |
| 28. | AC | -- | -- | 10min | Vdc=0, $V_{BAT}$=0 | |
| 29. | BAT | -- | -- | 10min | Vdc=0, Vac=0 | |
| 30. | BAT | -- | -- | 10min | Vdc=0, Vac=0 | |
| 4.4.4.7 Output overload | | | | | | |
| 31. | Overload | -- | Output overload (110%) | 30 min | Unit normal operation,<br>No damage, no hazard, no fire | |
| 4.4.4.8 cooling system failure test | | | | | | |
| 32. | Cooling system failure – Blanketing test | -- | Put the unit to box | 2Hour | 1 hour power run at 50% | |
| 4.4.4.13 Mis-wiring with incorrect phase sequence or polarity | | | | | | |
| 33. | Output L - N | -- | Reverse polarity before start up | 3min | Unit normal operation.<br>No damage, no hazard, no fire. | |

**Remarks:**

Abbreviations

APS: auxiliary power supply, EM: error message,

EUT: equipment under test, SC short circuit, OP: open circuit, O/L: Overloaded

EUT shut down: EUT not connect to Grid, cease to export power to Grid, the relay is opened.

EUT standby: EUT connect to Grid, cease to export power to Grid, the relay is closed.

During the test:

Fire can not propagate beyond the EUT.

Equipment shall not emitt molten metal.

Enclosures shall not deform to cause non-compliance with the standard.

Dielectric test is made on RI and BI between Pri. circuit and protective earthing terminal after the test.

No Backfeed voltage on the test

## Annex B Photos

| Front |
| --- |
|  |
| Back |
|  |

## Annex B Photos

| Left |
| --- |
|  |
| Right |
|  |

## Annex B Photos

| Top |
| --- |
|  |
| Bottom |
|  |

## Annex B Photos

| Internal |
| --- |
|  |